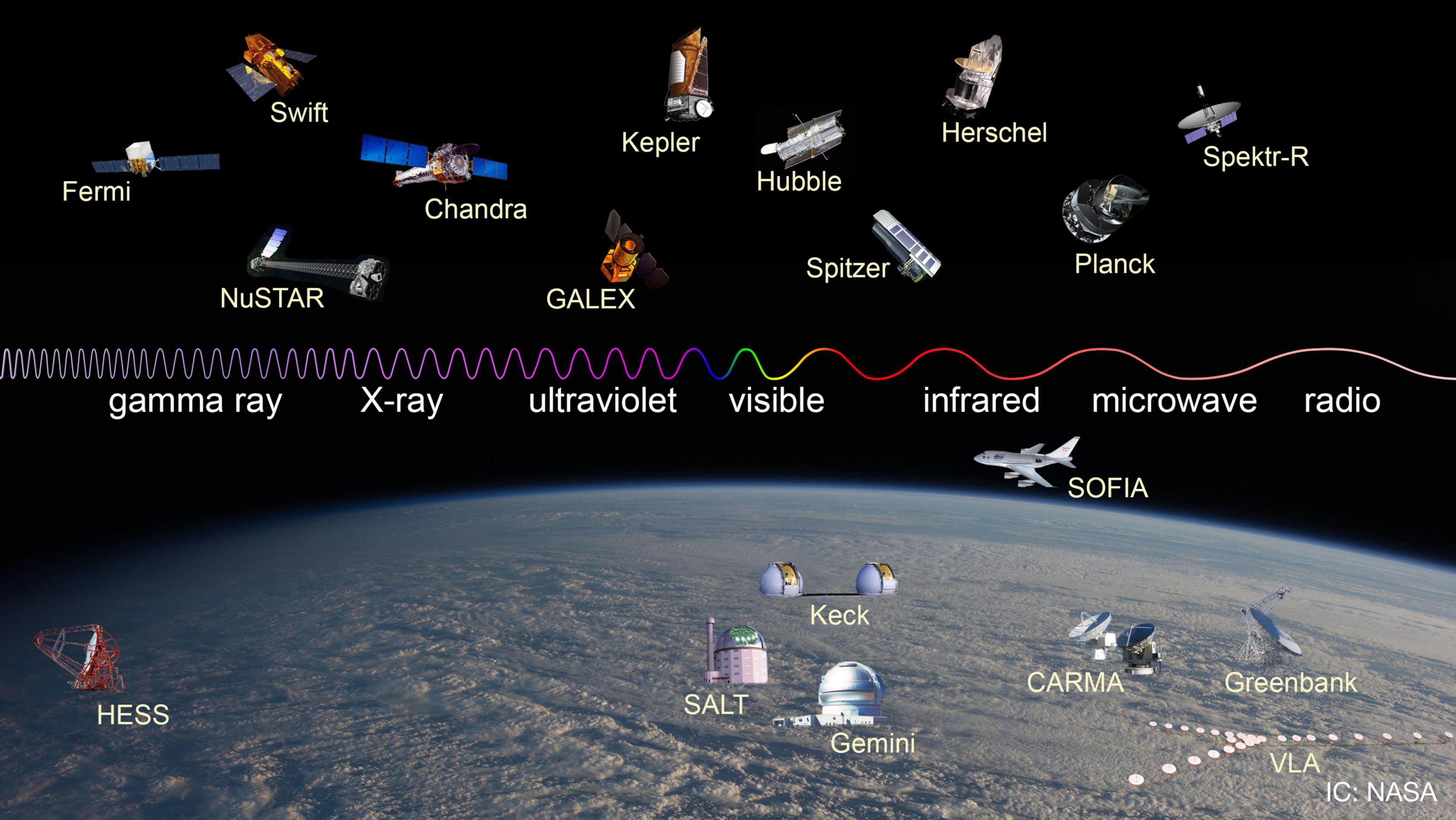


Extracting Gas Pressure Profiles of Galaxy Clusters

mm Universe 2023
LPSC Grenoble

Kang Wang, Yvette Perrott, Richard Arnold, David Huijser





Fermi

Swift

Chandra

Kepler

Hubble

Herschel

Spektr-R

NuSTAR

GALEX

Spitzer

Planck

gamma ray

X-ray

ultraviolet

visible

infrared

microwave

radio

SOFIA

HESS

SALT

Keck

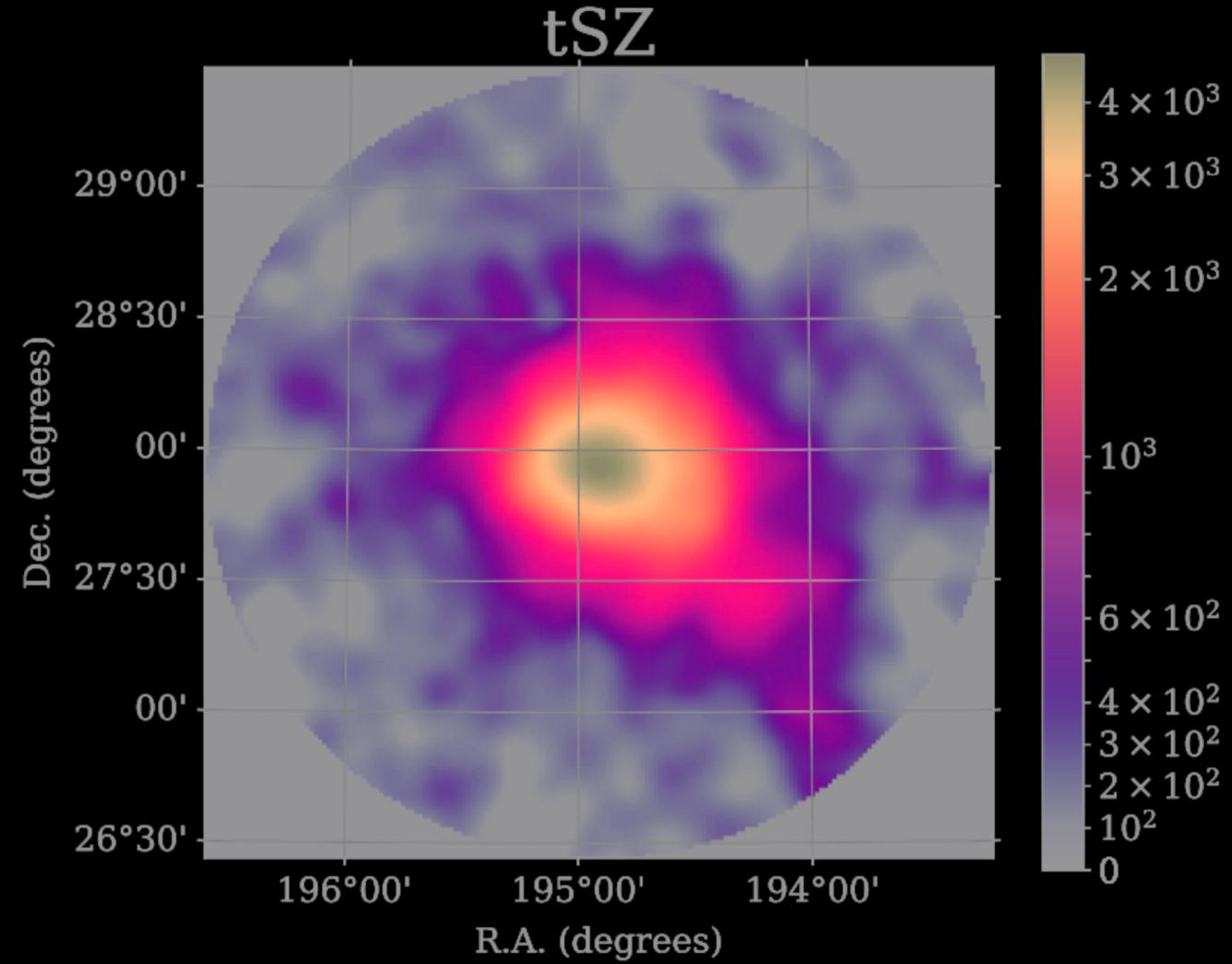
Gemini

CARMA

Greenbank

VLA

IC: NASA



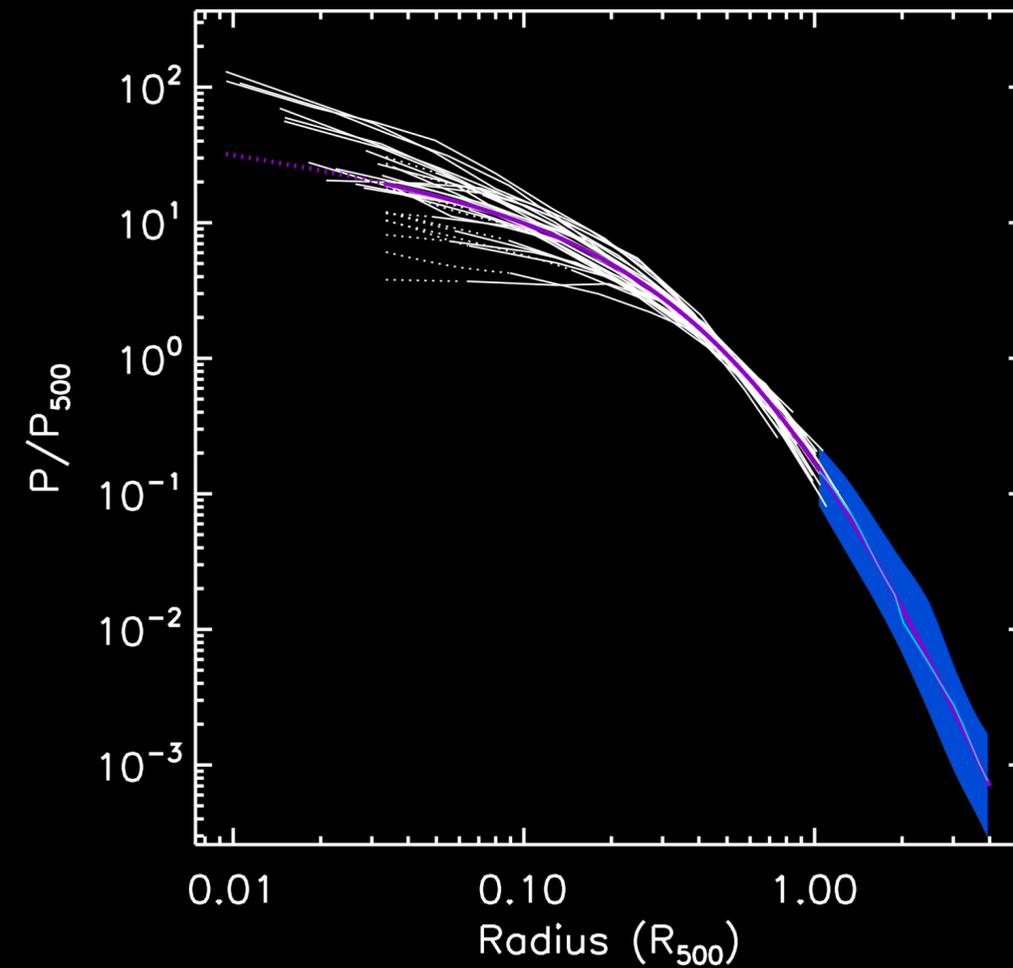
The tSZ signal of Coma cluster from Planck Legacy Archive (Adam et al., 2021)

$$y(r_{proj}) = \int \frac{\sigma_T}{m_e c^2} P(r) d\ell$$

Cluster Pressure Profiles

gNFW model

$$P(r) = \frac{P_{ei}}{\left(\frac{r}{r_s}\right)^\gamma \left[1 + \left(\frac{r}{r_s}\right)^\alpha\right]^{(\beta-\gamma)/\alpha}}$$



Arnaud et al., 2010

gNFW Model

Parameter and prior

$$y = \frac{\sigma_T}{m_e c^2} \int_{-\infty}^{\infty} \frac{P_{ei}}{\left(\frac{\sqrt{r_{proj}^2 + \ell^2}}{r_s}\right)^\gamma \left[1 + \left(\frac{\sqrt{r_{proj}^2 + \ell^2}}{r_s}\right)^\alpha\right]^{(\beta-\gamma)/\alpha}} d\ell$$

$$r_{proj} = \sqrt{(x - corefindX)^2 + (y - corefindY)^2}$$

$$corefindX \sim U(0, 2.55362) \text{ Mpc}$$

$$corefindY \sim U(0, 2.55362) \text{ Mpc}$$

$$\alpha \sim U(0, 2)$$

$$\beta \sim U(1, 10)$$

$$\gamma \sim U(0.001, 1)$$

$$r_s \sim U(1, 1.915) \text{ Mpc}$$

$$P_{ei} \sim U(0, 10^{-18}) \frac{M_\odot}{\text{Mpc} \cdot \text{s}^2}$$

gNFW Model

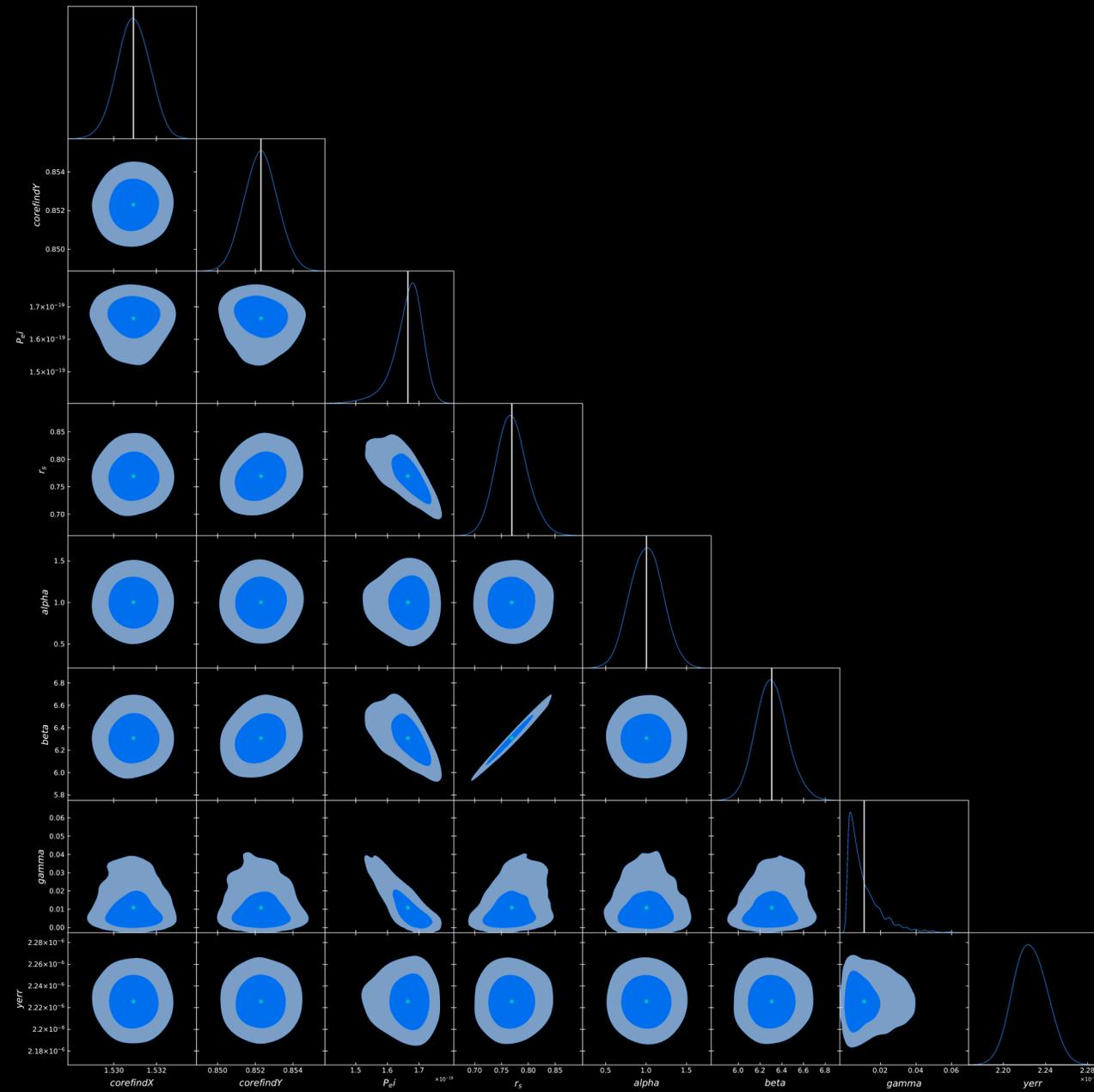
Likelihood Function

$$\Pr(\mathbf{D} | \Theta, \mathbf{M}) = (2\pi)^{-N/2} \exp \left[-\chi^2/2 \right] \prod_{k=1}^N \sigma_k^{-1}$$

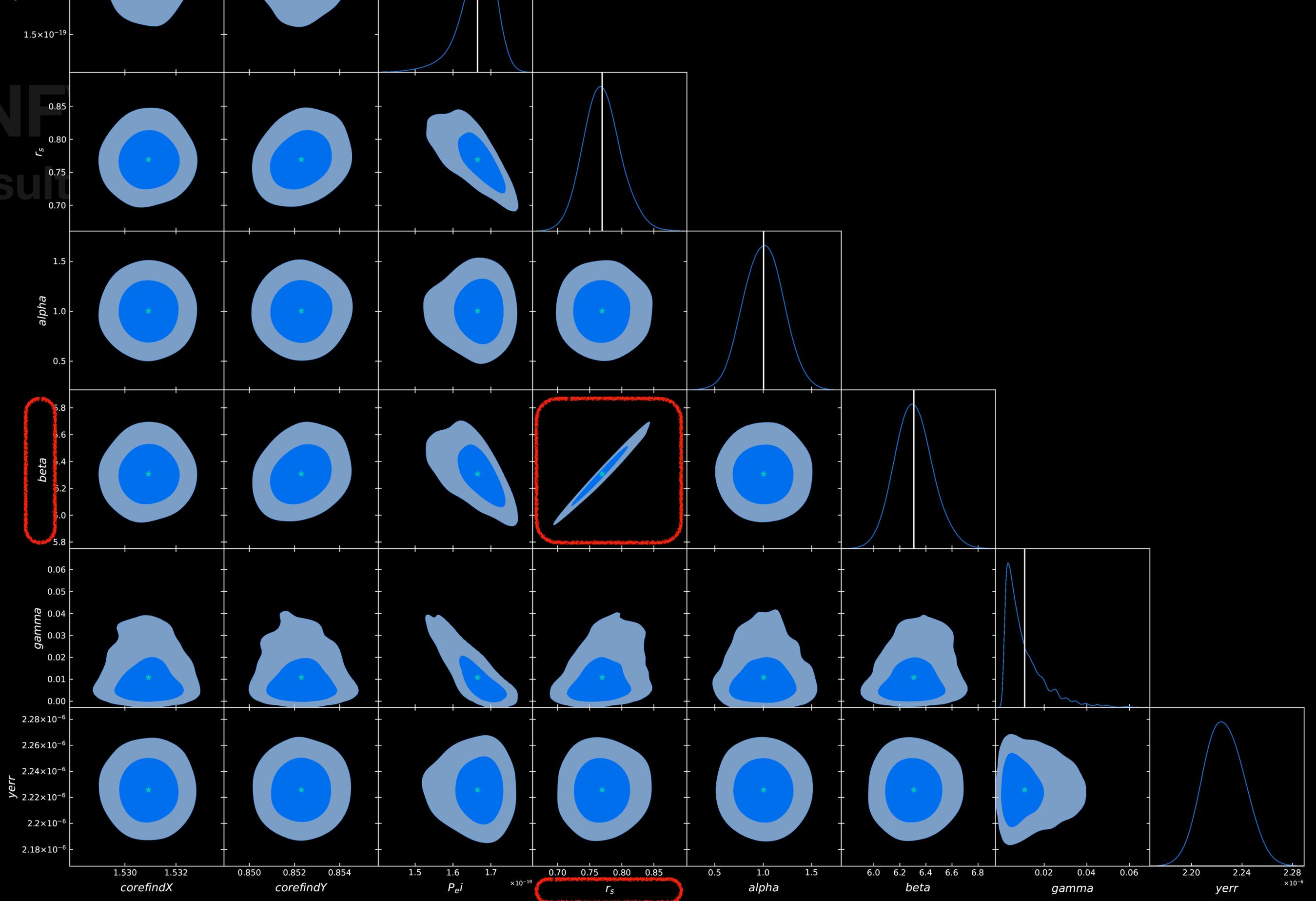
$$\ln \Pr(\mathbf{D} | \Theta, \mathbf{M}) = -\frac{N}{2} \ln(2\pi) - \frac{1}{2} \chi^2 - \sum_{k=1}^N \ln \sigma_k$$

$$\chi^2 = \sum_{k=1}^N \left(\frac{\mathbf{D}_k - \mathbf{M}_k}{\sigma_k} \right)^2$$

gNFW Model Results

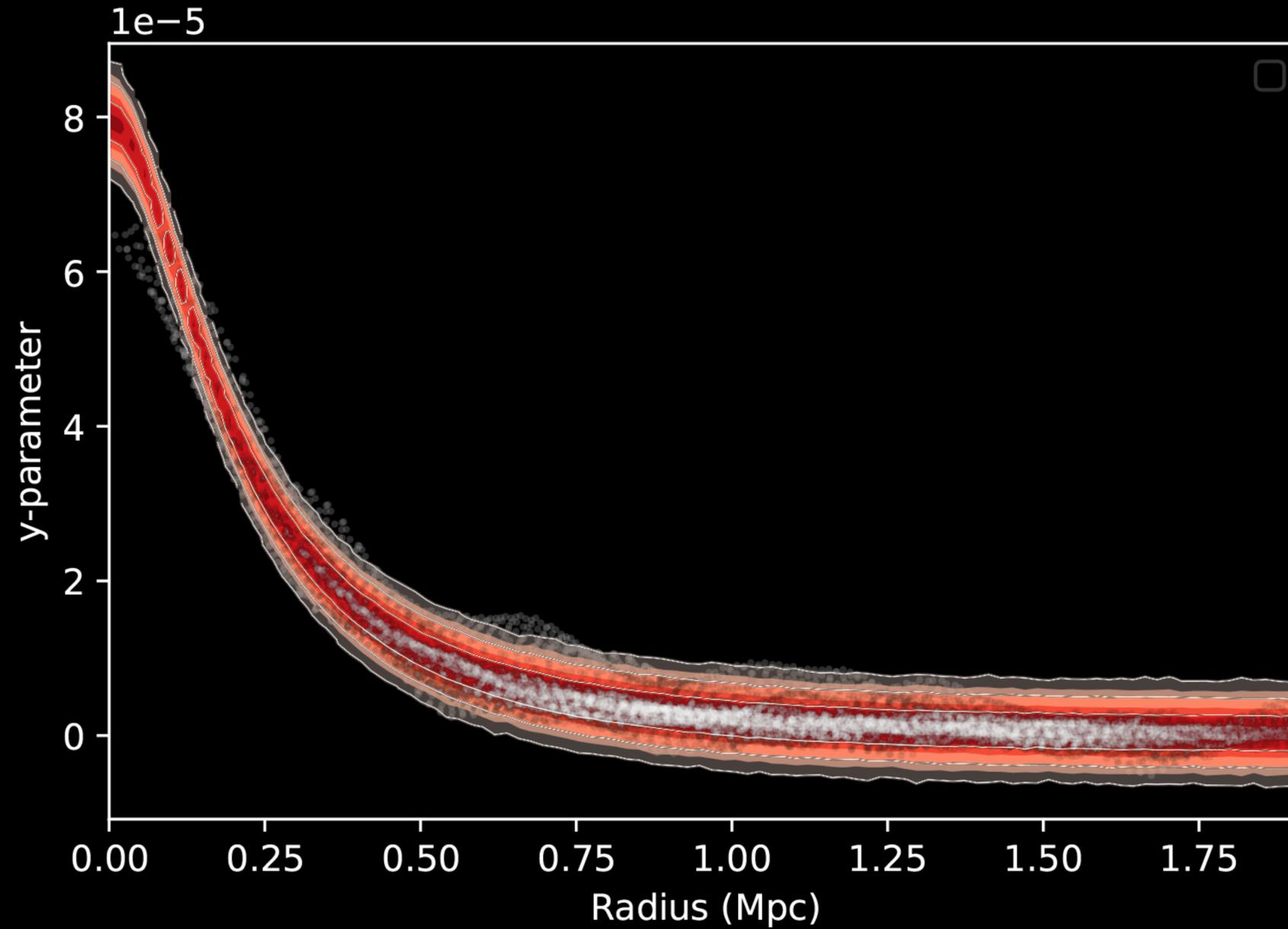


gNF
Result



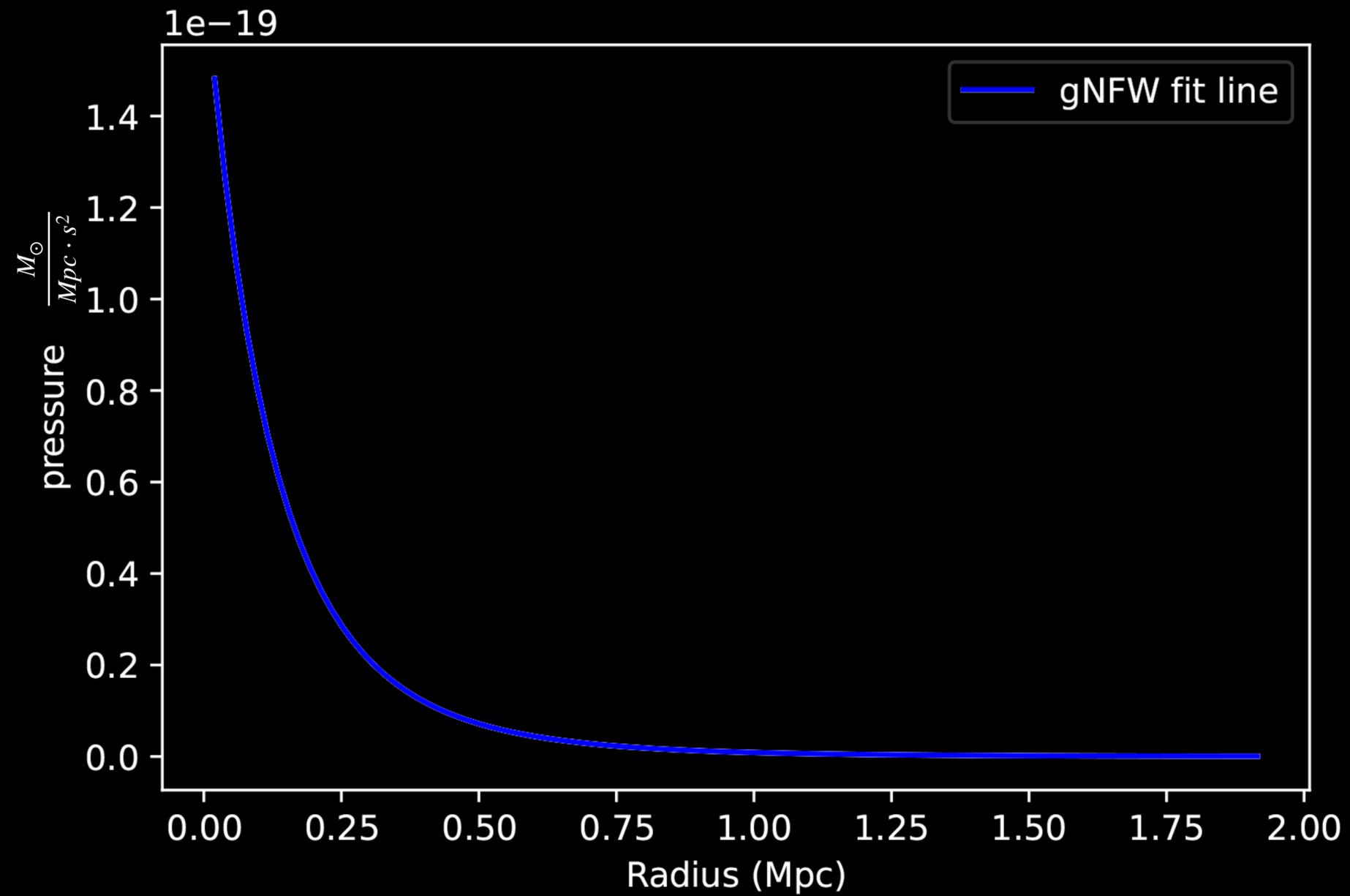
gNFW Model

Results



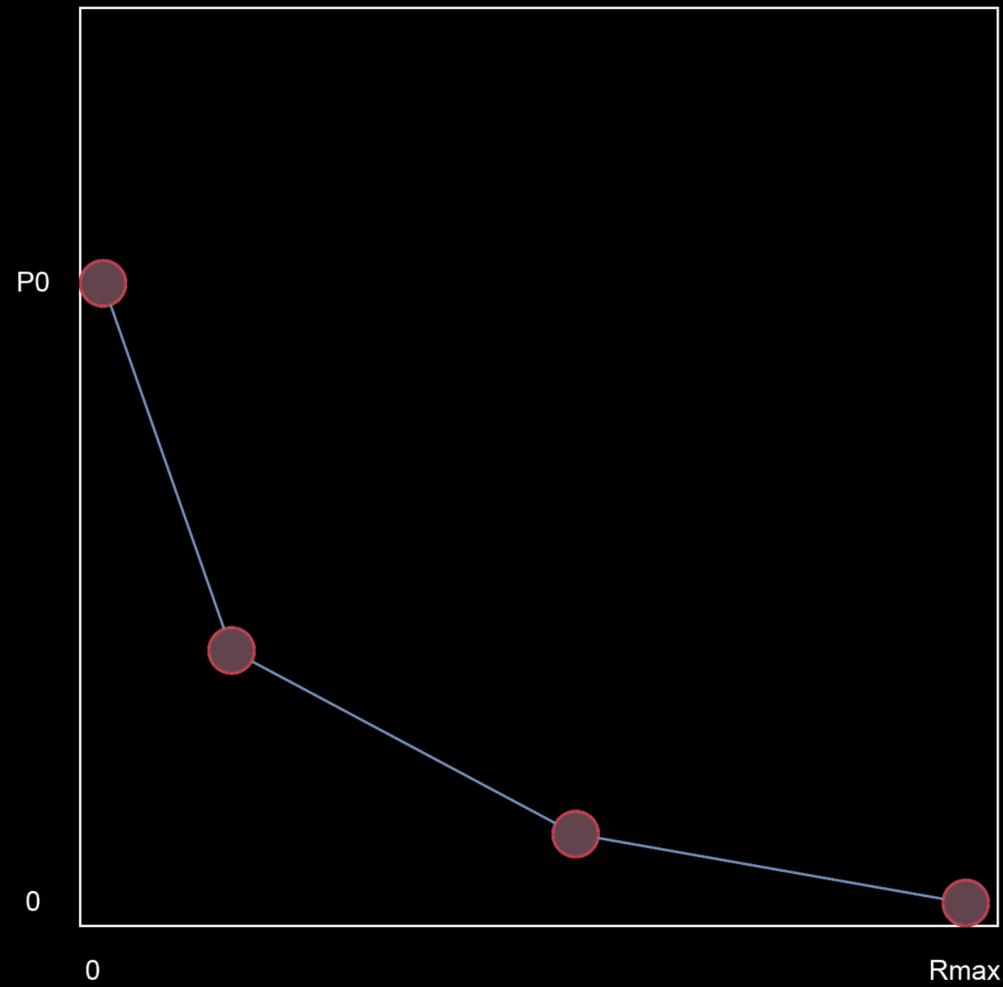
gNFW Model

Results



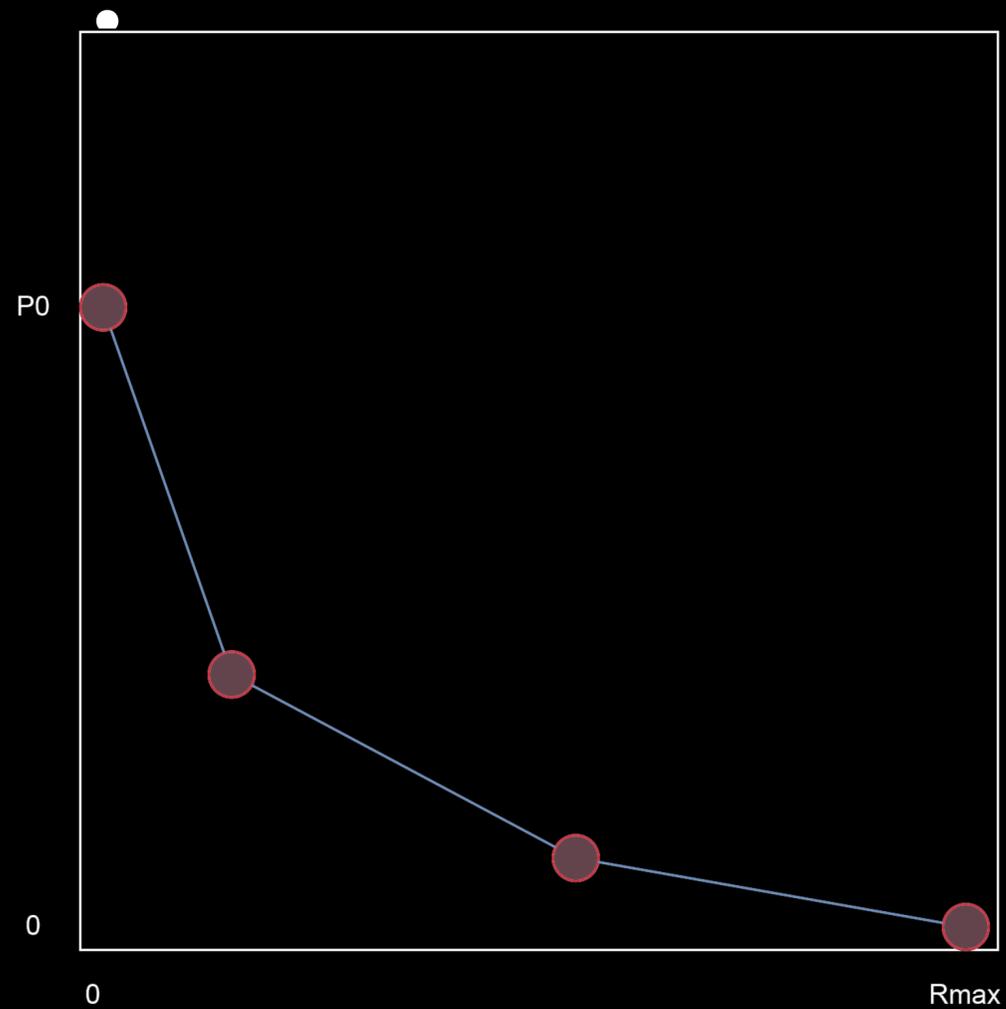
How to build a flexible model?

Nodal Model



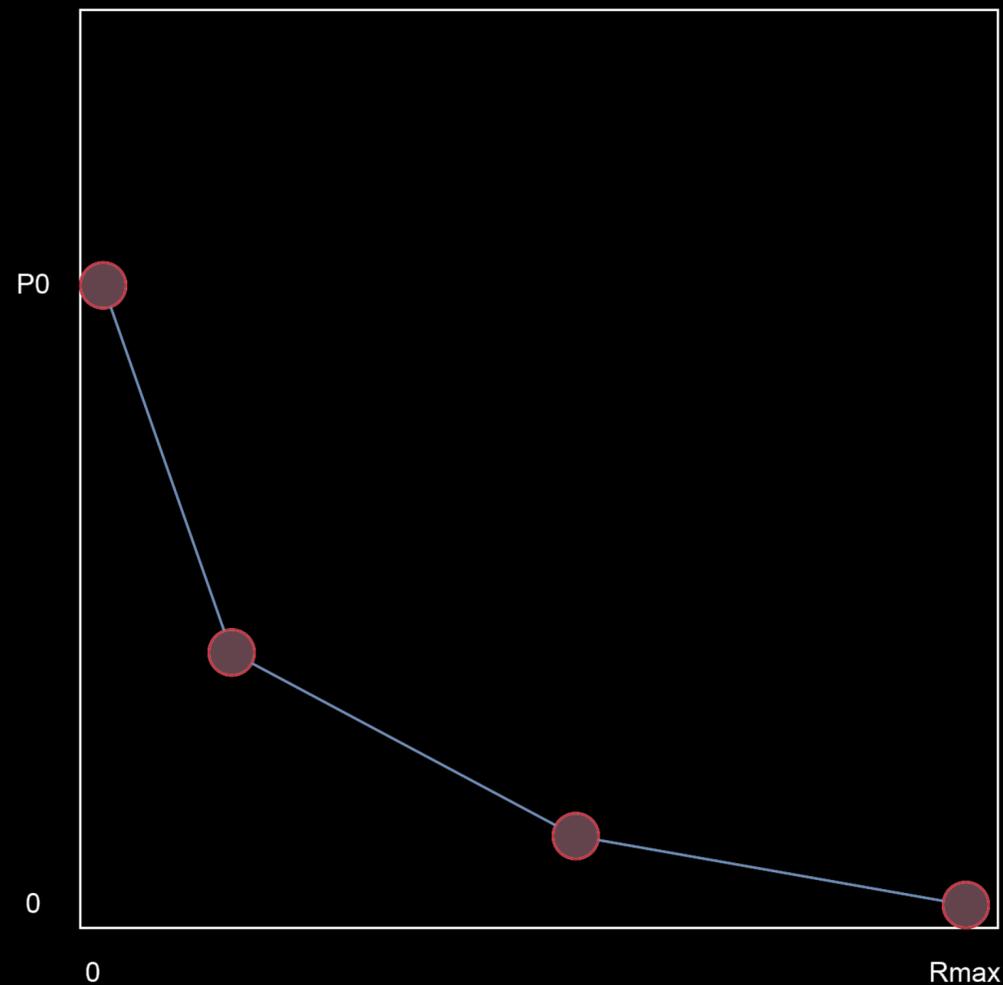
Olamaie et al., 2018

Nodal Model



$$P(r) = \left(\frac{P_0 - P_1}{r_0 - r_1} (r - r_0) + P_0 \right) 1_{[r_0 \leq r \leq r_1]} + \left(\frac{P_1 - P_{max}}{r_1 - r_{max}} (r - r_1) + P_1 \right) 1_{[r_1 \leq r \leq r_{max}]}$$

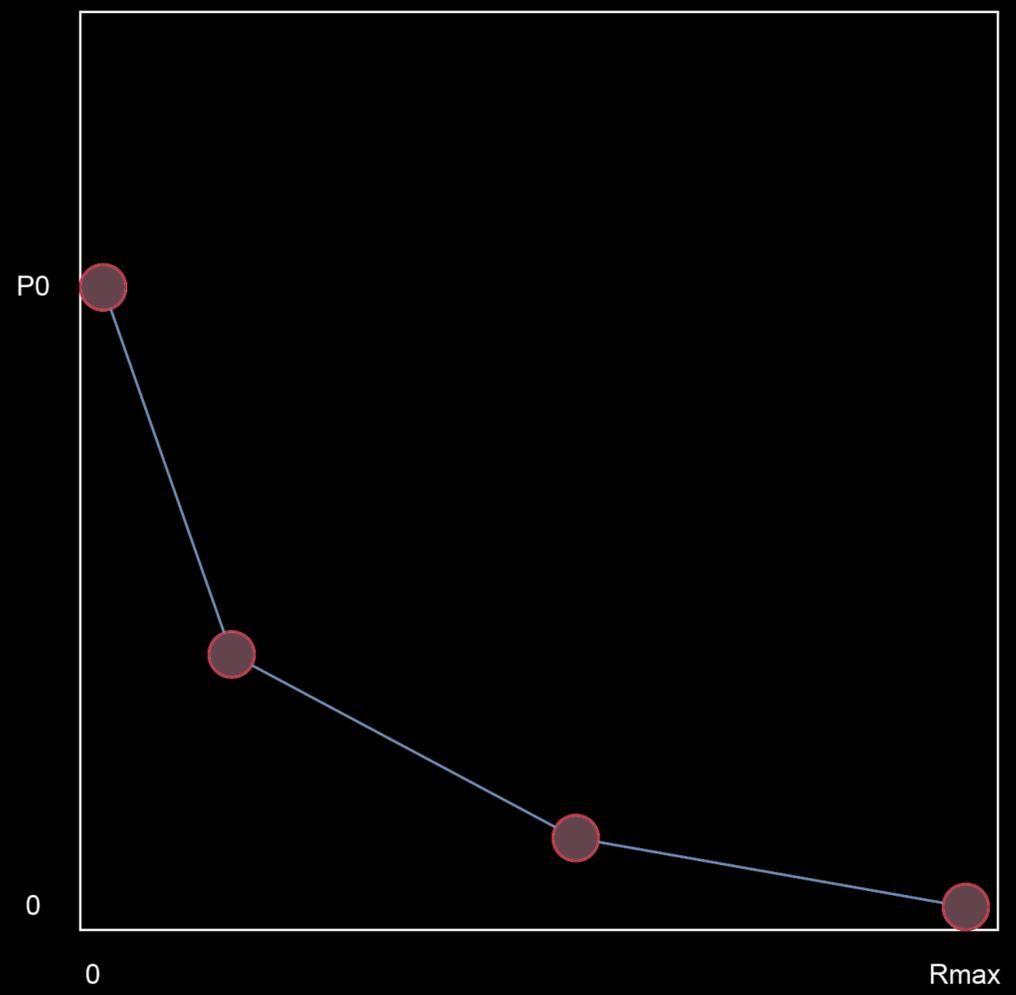
Nodal Model



$$P(r) = \left(\frac{P_0 - P_1}{r_0 - r_1} (r - r_0) + P_0 \right) \mathbb{1}_{[r_0 \leq r \leq r_1]} + \left(\frac{P_1 - P_{max}}{r_1 - r_{max}} (r - r_1) + P_1 \right) \mathbb{1}_{[r_1 \leq r \leq r_{max}]}$$

$$\begin{aligned} & \frac{\sigma_T}{m_e c^2} \int \left(\frac{P_0 - P_1}{r_0 - r_1} (\sqrt{r_p^2 + l^2} - r_0) + p_0 \right) \mathbb{1}_{[r_0 \leq \sqrt{r_p^2 + l^2} \leq r_1]} \\ & + \left(\frac{P_1 - P_{max}}{r_1 - r_{max}} (\sqrt{r_p^2 + l^2} - r_1) + p_1 \right) \mathbb{1}_{[r_1 \leq \sqrt{r_p^2 + l^2} \leq r_{max}]} dl \\ & = \frac{\sigma_T}{m_e c^2} \left\{ \left[\frac{P_0 - p_1}{2(r_0 - r_1)} (l (\sqrt{l^2 + r_p^2} - 2r_1) + r_p^2 \log(\sqrt{l^2 + r_p^2} + l)) \right] \frac{\sqrt{r_1^2 - r_p^2}}{\sqrt{r_0^2 - r_p^2}} \right\} \\ & + \frac{\sigma_T}{m_e c^2} \left\{ \left[\frac{P_1 - P_{max}}{2(r_1 - r_{max})} (l (\sqrt{l^2 + r_p^2} - 2r_{max}) + r_p^2 \log(\sqrt{l^2 + r_p^2} + l)) \right] \frac{\sqrt{r_{max}^2 - r_p^2}}{\sqrt{r_1^2 - r_p^2}} \right\} \end{aligned}$$

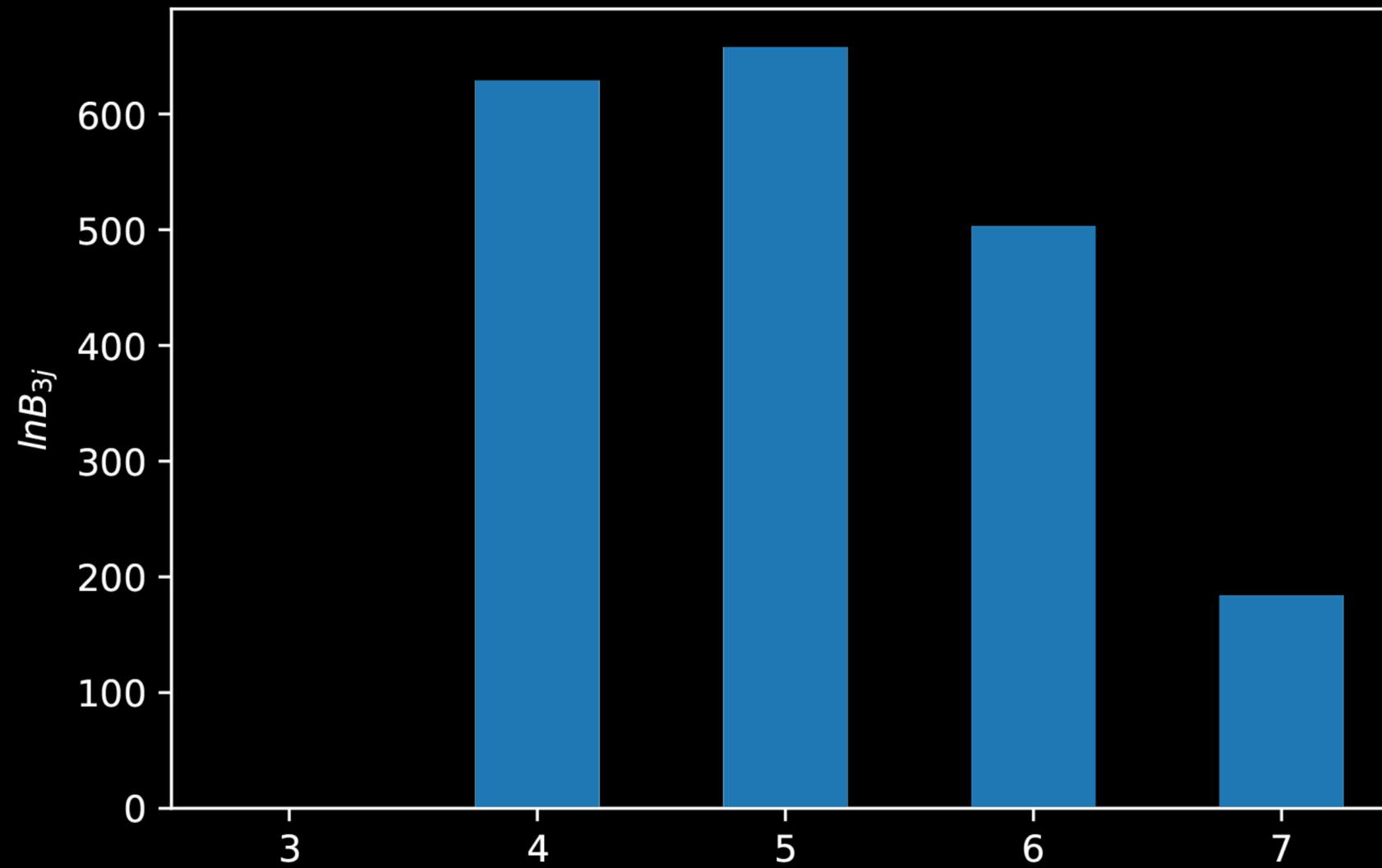
Nodal Model Prior



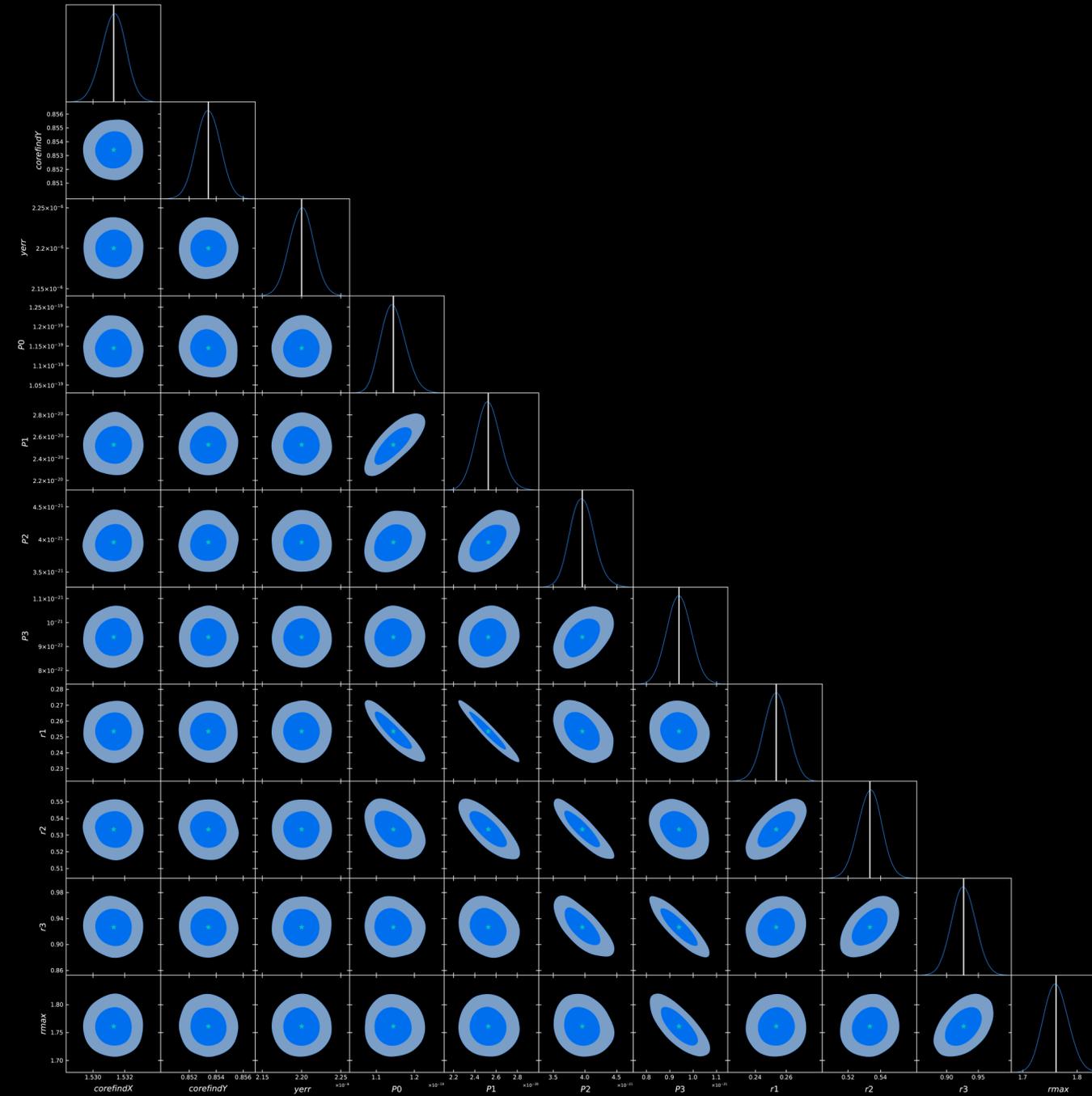
$$r_0 < r_1 < r_2 \dots < r_{max}$$

Nodal Model

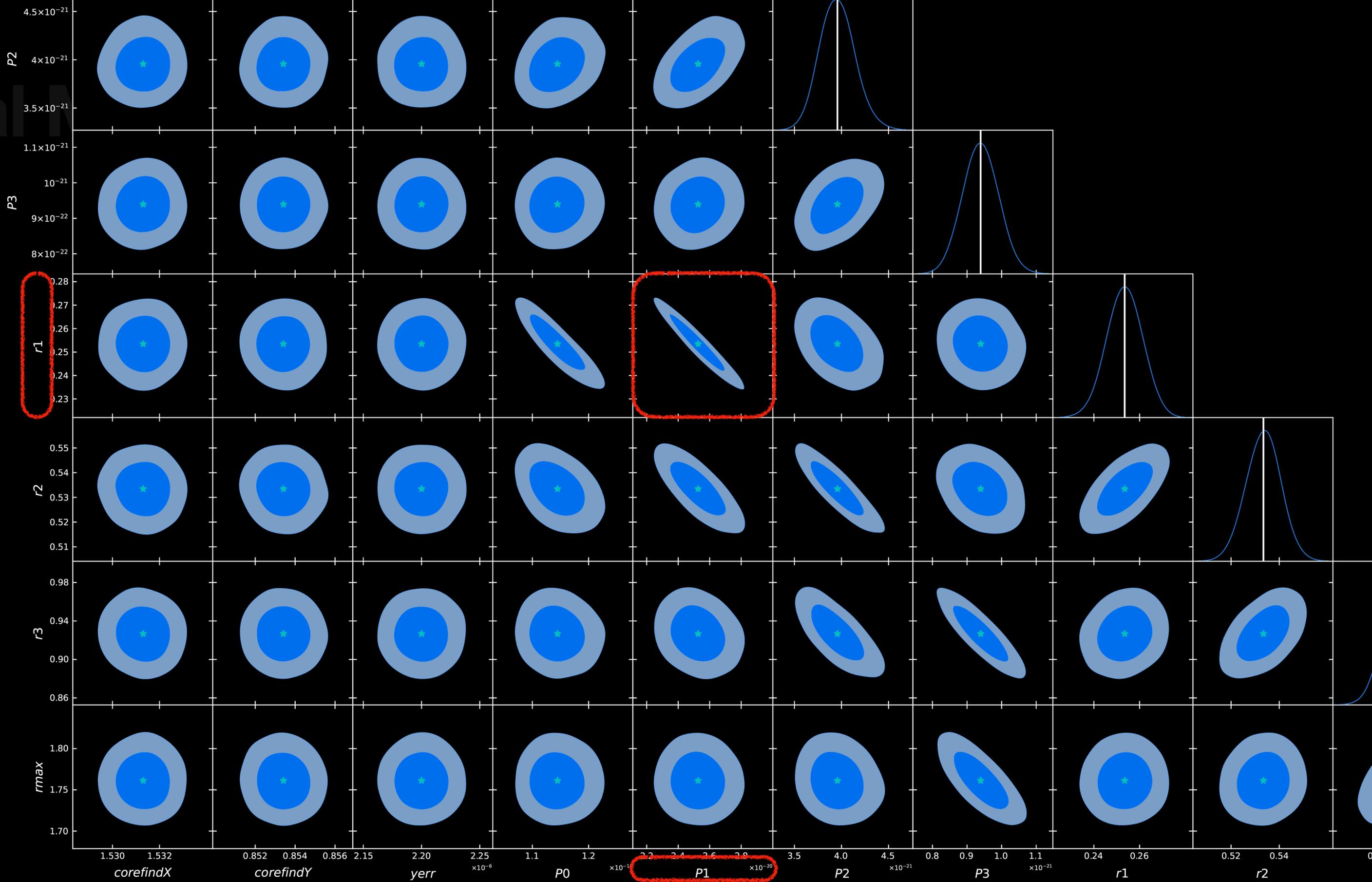
Results



Nodal Model Results

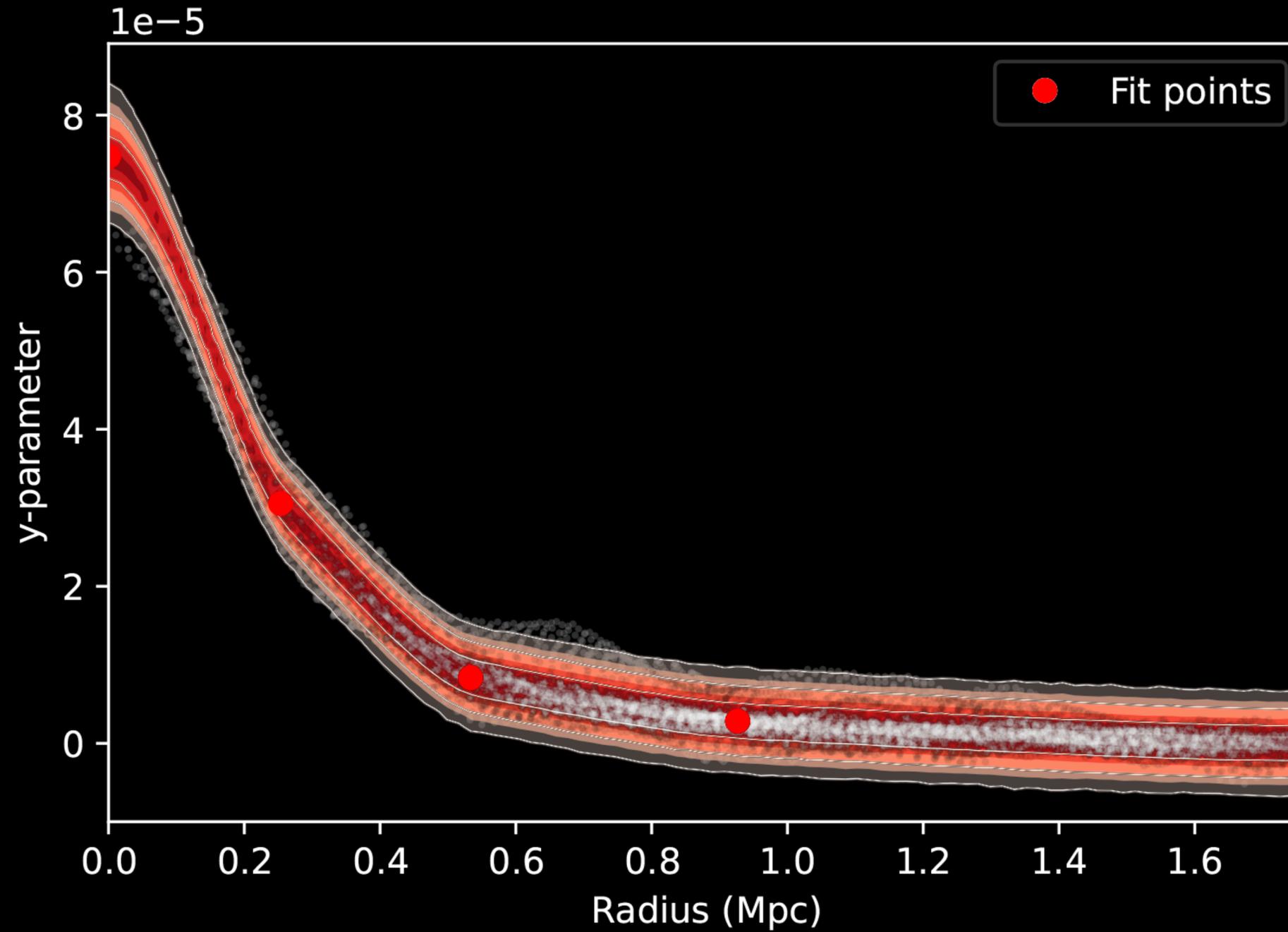


Nodal Results



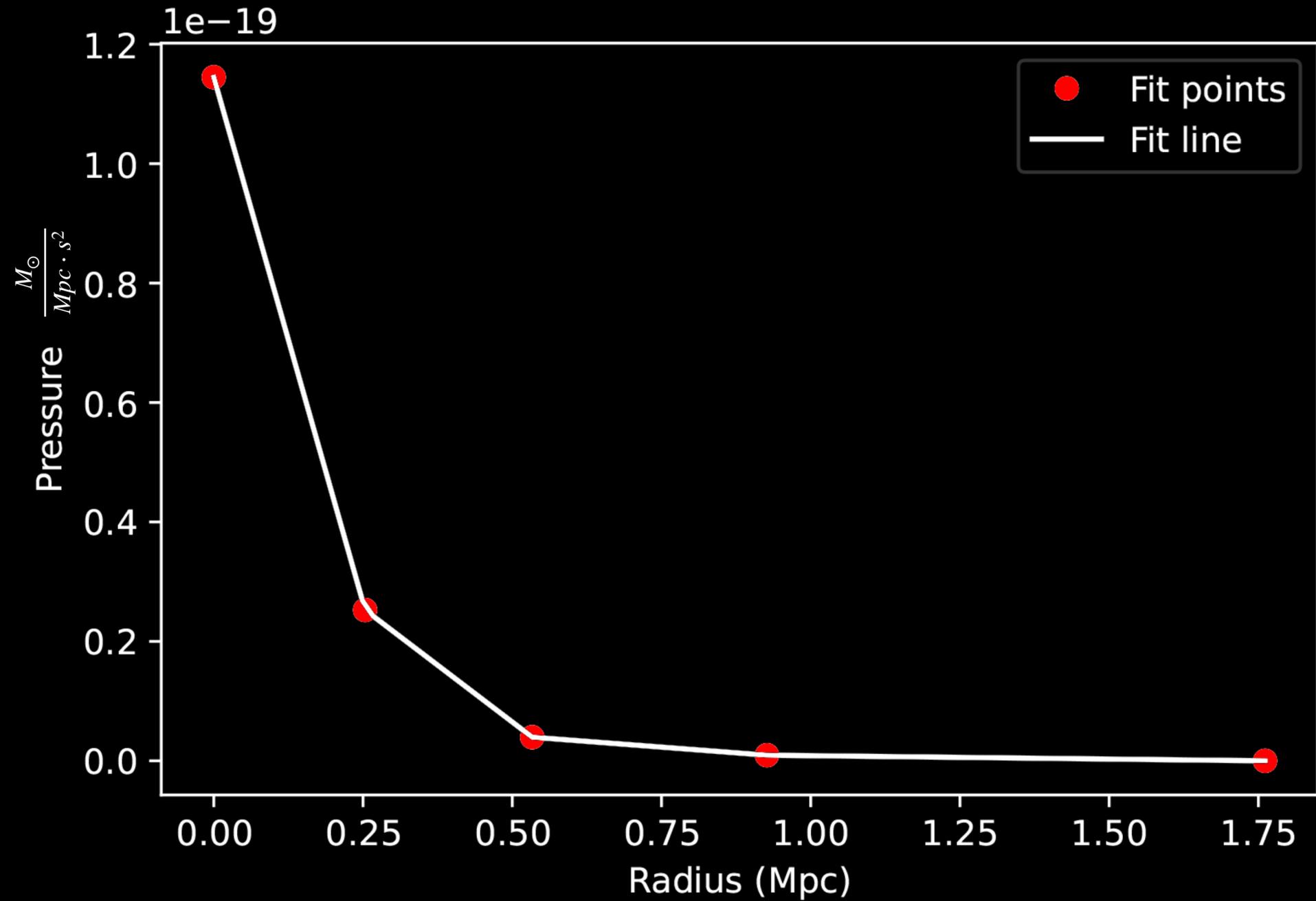
Nodal Model

Results



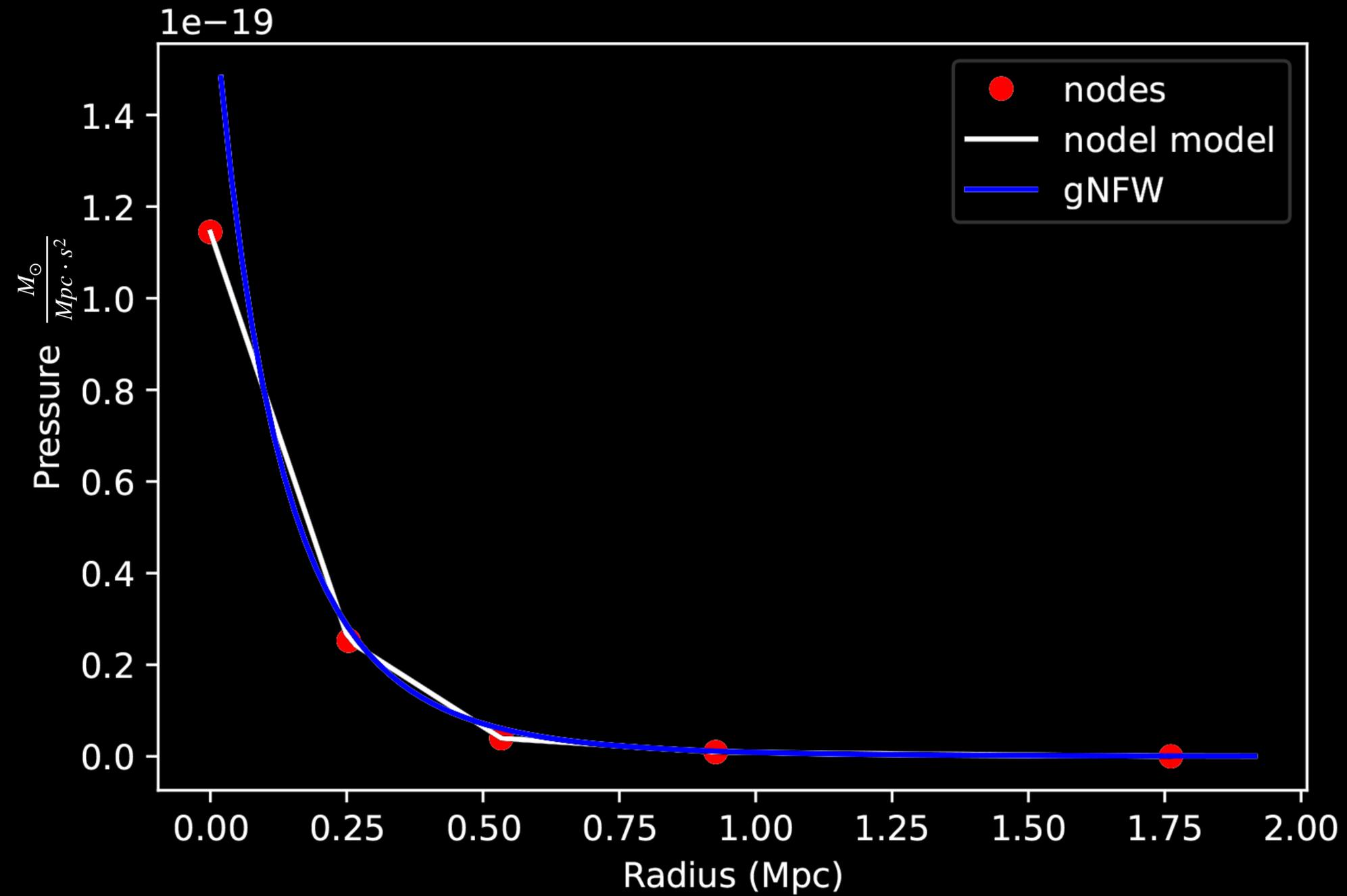
Nodal Model

Results



Nodal Model

Results



How to deal with trans-dimensional problem?

DNest

Nested Sampling vs Diffusive Nested Sampling

- Nested Sampling is limited to ascending in likelihood levels and can only explore the most recent level.
- Diffusive Nested Sampling, however, can backtrack, thereby gathering samples from lower levels.
- Unlike Nested Sampling, which halts after establishing the final level, Diffusive Nested Sampling continues exploring all levels.

Reversible Jump

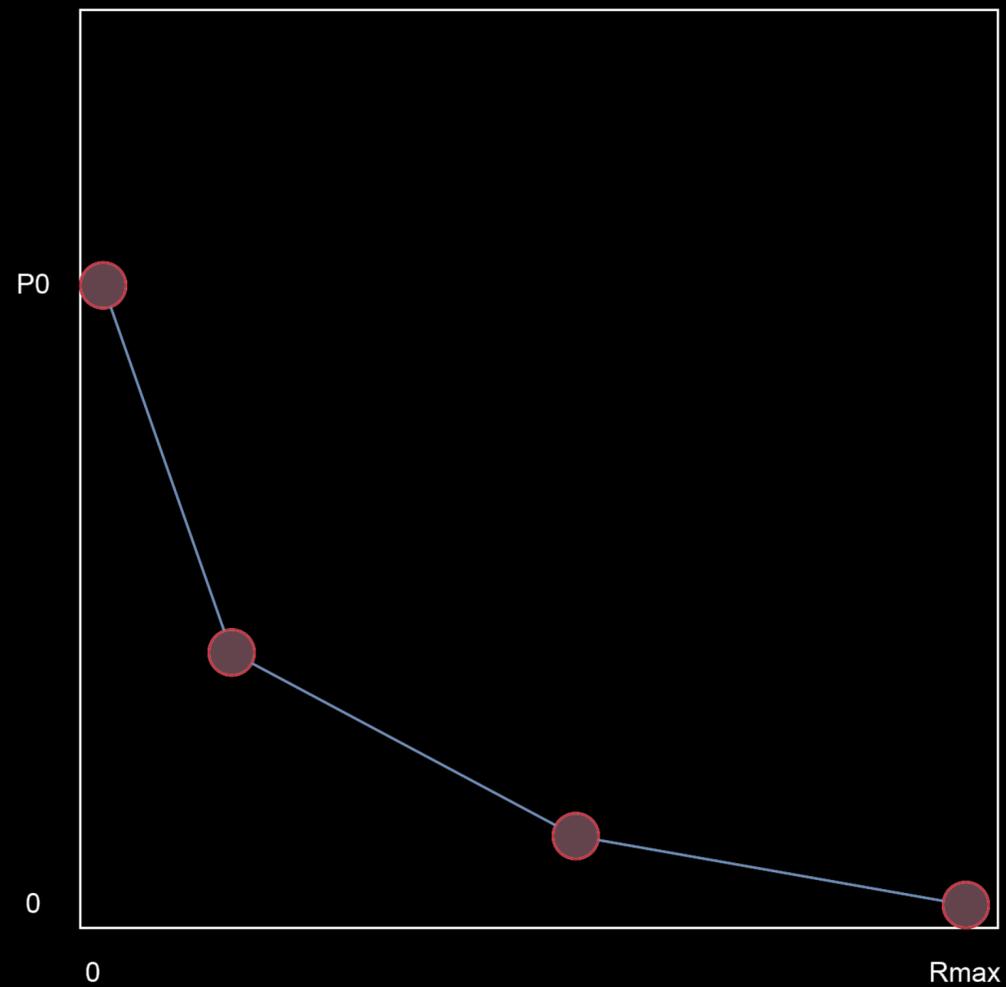
- A generalised version of the Metropolis-Hastings algorithm
- The exploration of multiple parameter spaces by reducing or increasing the number of parameters at each iteration.
 - *E.g. compare completely different models with either the same or different numbers of parameters*
 - *Or look for models with unknown numbers of objects where each additional object increases the number of parameters by the same amount.*

Conclusion

- Parametric models have degenerate problems
- The non-parametric model is more flexible
- Future work: DNest + RJ

Nodal Model

Prior



$$r_0 < r_1 < r_2 \dots < r_{max}$$

$$U_i \sim U(0,1)$$

$$x_i = -\ln U_i$$

$$d_i = \frac{x_i}{\sum_j x_j} \sim Dir$$

$$w_i = \sum_j d_j = \frac{\sum_{k=1}^i x_k}{\sum_{j=1}^n x_j} = \frac{\sum_{k=1}^i -\ln U_k}{\sum_{j=1}^n -\ln U_j}$$

$$r_i = r_0 + w_i (r_{max} - r_0)$$