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Poincaré Invariant Three-Body Scattering

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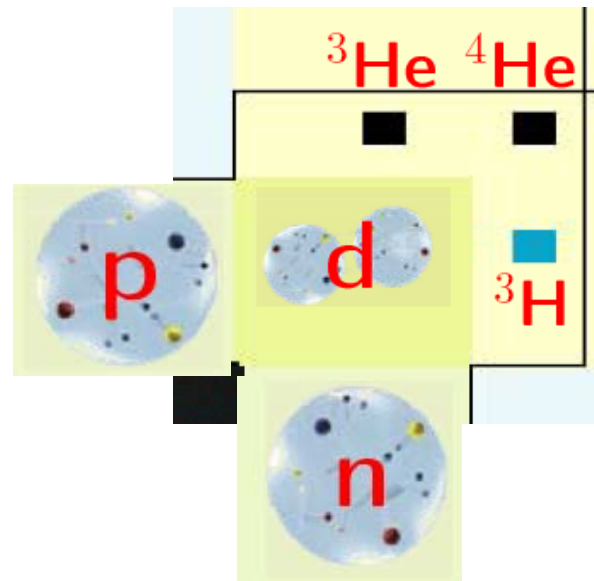
W. Polyzou, W. Glöckle

10/9/2008

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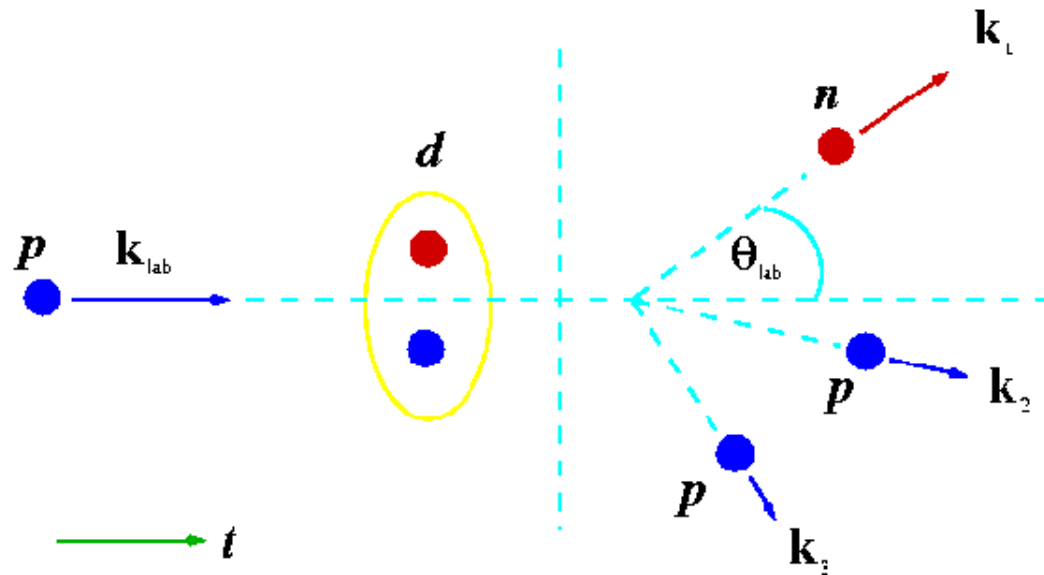


A Few-Body Theorist's view of the Nuclear Chart



3 Nucleons

- Bound State: ${}^3\text{H}$ - ${}^3\text{He}$
- Scattering: **Elastic – Inelastic (Breakup)**
- Energy Scale: keV \rightarrow MeV \rightarrow GeV



Challenges in 3N Physics

- Test of nuclear forces in the simplest nuclear environment (over a large energy range!)
 - Two-body forces
 - Genuine three-body forces
- **Reaction mechanisms**
 - Example: deuteron breakup, (p,n) charge exchange
 - Higher Energy: Lorentz vs. Galilean Invariance
 - Check of commonly used approximations (Glauber)
 - Three-body decays of particles (e.g. η or η')

Relativistic Effects at Higher Energies

Computational Challenge:

3N and 4N systems:

- standard treatment based on pw projected momentum space successful (3N scattering up to ≈ 250 MeV) but rather tedious
- 2N: $j_{\max}=5$, 3N: $J_{\max}=25/2 \rightarrow 200$ 'channels'
- Computational maximum today:
- 2N: $j_{\max}=7$, 3N: $J_{\max}=31/2$

\Rightarrow **Solution:**

\Rightarrow **NO partial wave decomposition of basis states**

Roadmap for 3N problem without PW

Scalar NN model

- NN scattering + bound state
- 3N bound state
- 3N bound state + 3NF
- 3N scattering:
- Full Faddeev Calculation

- Elastic scattering
- Below and above break-up
- Break-up

- **Poincaré Invariant Faddeev Calculations**

Realistic NN Model

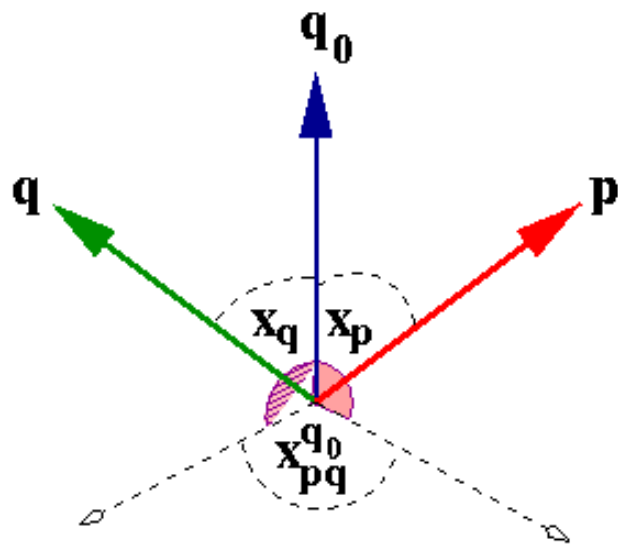
- NN scattering + deuteron
 - Potentials AV18 and Bonn-B
- Break-up in first order:
 - (p,n) charge exchange
 - Max. Energy 500 MeV
 - Lorentz kinematics

- Exact Faddeev Calculation
 - NN interactions
 - High energy limits



Variables for 3D Scattering Calculation

3 distinct vectors in the problem: \mathbf{q}_0 \mathbf{q} \mathbf{p}



5 independent variables:

$$p = |\mathbf{p}|, \quad q = |\mathbf{q}|$$

$$x_p = \hat{\mathbf{p}} \cdot \hat{\mathbf{q}}_0, \quad x_q = \hat{\mathbf{q}} \cdot \hat{\mathbf{q}}_0$$

$$x_{pq}^{q_0} = (\mathbf{q}_0 \times \mathbf{q}) \cdot (\mathbf{q}_0 \times \mathbf{p})$$

Numerical calculation:

Three-body transition amplitude is a function of 5 variables

\mathbf{q} system : $\mathbf{z} \parallel \mathbf{q}$

\mathbf{q}_0 system : $\mathbf{z} \parallel \mathbf{q}_0$

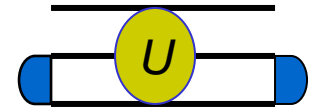
Relativistic Three-Body Problem

- **Context: Poincaré Invariant Quantum Mechanics**
 - Poincaré invariance is exact symmetry, realized by a unitary representation of the Poincaré group on a few-particle Hilbert space
 - Instant form
 - Faddeev equations same operator form but different ingredients
- **Kinematics**
 - Lorentz transformations between frames
- **Dynamics**
 - Bakamjian-Thomas Scheme: Mass Operator $M=M_0+V$ replaces Hamiltonian $H=H_0+\mathbf{v}$
 - Connect Galilean two-body \mathbf{v} with Poincaré two-body v
 - Construct $V := \sqrt{M^2 + q^2} - \sqrt{M_0^2 + q^2}$

Three-Body Scattering

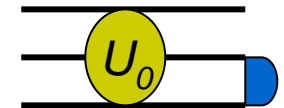
- Transition operator for elastic scattering

$$U = PG_0^{-1} + PT$$



- Transition operator for breakup scattering

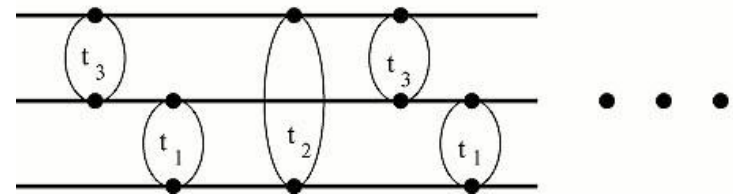
$$U_0 = (1 + P)T$$



- Faddeev equation (Multiple Scattering Series)

$$T = tP \left| + tG_0 PtP + \dots \right.$$

1st Order in tP



$t = v + vg_0t =:$ NN t-matrix

$P = P_{12} P_{23} + P_{13} P_{23} \equiv$ Permutation Operator

Kinematic Relativistic Ingredients:

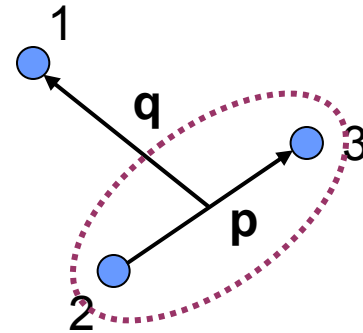
- Lorentz transformation Lab \rightarrow c.m. frame (3-body)
- Phase space factors in cross sections
- Poincaré-Jacobi momenta
- Permutations for identical particles

Kinematics: Poincaré-Jacobi momenta

- Nonrelativistic (Galilei)

$$\mathbf{p} = \frac{1}{2}(\mathbf{k}_2 - \mathbf{k}_3)$$

$$\mathbf{q} = \frac{2}{3}(\mathbf{k}_1 - \frac{1}{2}(\mathbf{k}_2 + \mathbf{k}_3))$$



- Relativistic (Lorentz)

$$\mathbf{p} = \frac{1}{2}(\mathbf{k}_2 - \mathbf{k}_3) + \frac{\mathbf{k}_2 + \mathbf{k}_3}{2m_{23}} \left(\frac{(\mathbf{k}_2 - \mathbf{k}_3) \cdot (\mathbf{k}_2 + \mathbf{k}_3)}{(E_2 + E_3) + m_{23}} - (E_2 - E_3) \right)$$

$$\mathbf{q} = \mathbf{k}_1 + \frac{\mathbf{K}}{M} \left(\frac{\mathbf{k}_1 \cdot \mathbf{K}}{E + M} - E_1 \right)$$

$$|\mathbf{k}_1 \mathbf{k}_2 \mathbf{k}_3\rangle = \left| \frac{\partial(Kpq)}{\partial(\mathbf{k}_2 \mathbf{k}_3)} \right|^{1/2} |\mathbf{K} p q\rangle \neq 0$$

$$E = E_1 + E_2 + E_3$$

$$\mathbf{K} = \mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3$$

$$M = \sqrt{E^2 - \mathbf{K}^2}$$

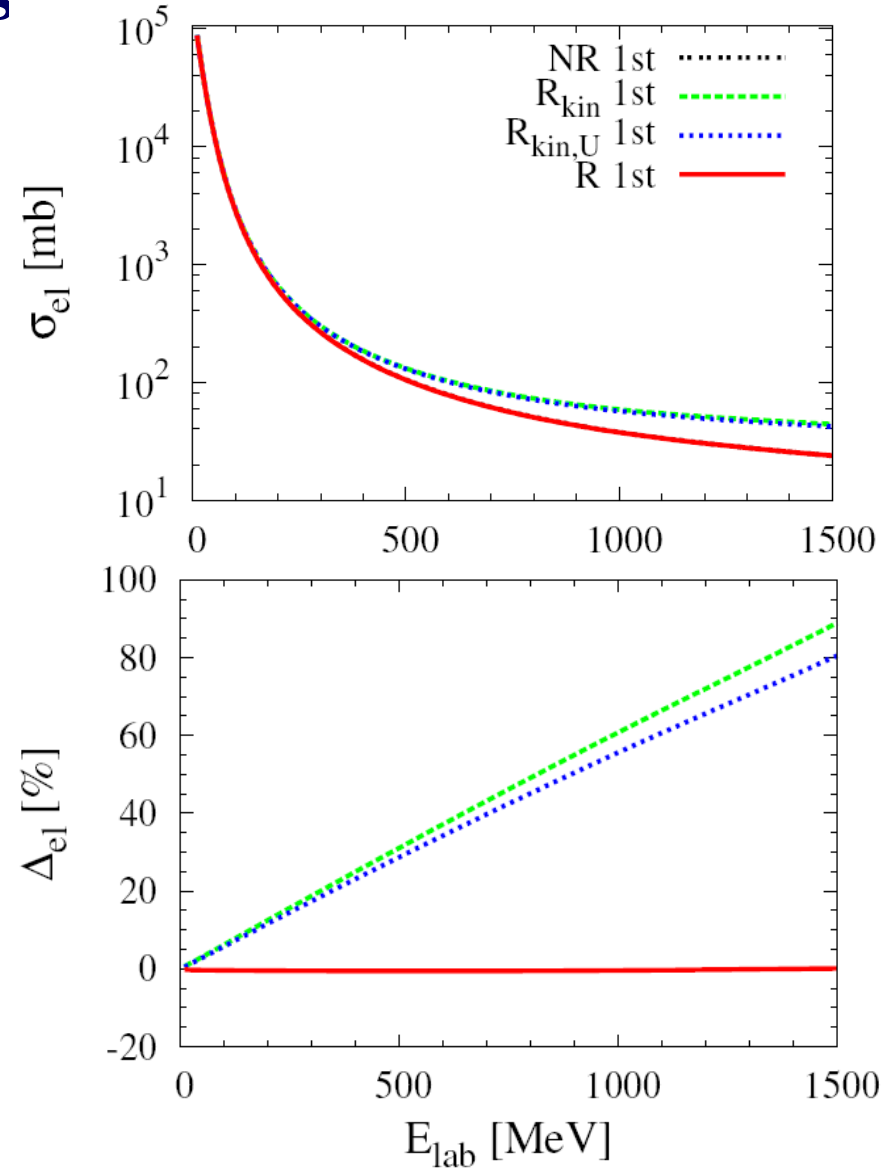
$$m_{23} = \sqrt{(E_2 + E_3)^2 - (\mathbf{k}_2 + \mathbf{k}_3)^2}$$

Relativistic kinematics

IA (1st order)

$$T = tP$$

- Lorentz transformation
Lab \rightarrow c.m. frame) (3-body)
- Phase space factors in
cross sections
- Poincaré-Jacobi momenta
- Permutations



Quantum Mechanics

Galilei Invariant: $H = \frac{\mathbf{K}^2}{2M_g} + h \quad ; \quad h = h_0 + v_{12}^{NR} + v_{13}^{NR} + v_{23}^{NR}$

Poincaré Invariant: $H = \sqrt{\mathbf{K}^2 + M^2} \quad ; \quad M = M_0 + V_{12} + V_{23} + V_{31}$

$$V_{ij} = M_{ij} - M_0 = \sqrt{(m_{0,ij} + v_{ij})^2 + q_k^2} - \sqrt{m_{0,ij}^2 + q_k^2}$$

Two-body interaction embedded in the 3-particle Hilbert space

$$m_{0,ij} = \sqrt{m_i^2 + p_{ij}^2} + \sqrt{m_j^2 + p_{ij}^2}$$

$$M_0 = \sqrt{m_{0,ij}^2 + q_k^2} + \sqrt{m_k^2 + q_k^2}$$

V_{ij} embedded in the 3-particle Hilbert space

$$V_{ij} = M_{ij} - M_0 = \sqrt{(m_{0,ij} + v_{ij})^2 + q_k^2} - \sqrt{m_{0,ij}^2 + q_k^2}$$

need matrix elements: $\langle \vec{k} | V(\vec{p}) | \vec{k}' \rangle$

$$\begin{aligned} &= v(\vec{k}, \vec{k}') + \psi_b(\vec{k})(\sqrt{M_b^2 + p^2} - M_b)\psi_b(\vec{k}') + \frac{1}{\omega - \omega'} \left[(\sqrt{\omega^2 + p^2} - \omega) \Re[t(\vec{k}', \vec{k}; \omega)] \right. \\ &\quad \left. - (\sqrt{\omega'^2 + p^2} - \omega') \Re[t(\vec{k}, \vec{k}'; \omega')] \right] + \frac{1}{\omega - \omega'} \left[\mathcal{P} \int d^3 k'' \frac{(\sqrt{\omega''^2 + p^2} - \omega'')}{\omega'' - \omega} t(\vec{k}, \vec{k}''; \omega'') t^*(\vec{k}', \vec{k}''; \omega'') \right. \\ &\quad \left. - \mathcal{P} \int d^3 k'' \frac{(\sqrt{\omega''^2 + p^2} - \omega'')}{\omega'' - \omega'} t(\vec{k}, \vec{k}''; \omega'') t^*(\vec{k}', \vec{k}''; \omega'') \right]. \end{aligned}$$

H. Kamada,^{1,*} W. Glöckle,^{2,†} J. Golak,^{2,3,‡} and Ch. Elster^{4,§}

PHYSICAL REVIEW C **66**, 044010 (2002)

Two-Body Input: T1-operator embedded in 3-body system

$$T_1(p', p; q) = V(p', p; q) + \int d^3k'' \frac{V(p', k''; q) T_1(k'', p; q)}{\sqrt{(2E(p'))^2 + q^2} - \sqrt{(2E(k''))^2 + q^2} + i\varepsilon}$$

Do not solve for V !

- Obtain fully off-shell matrix elements $T_1(k, k', q)$ from half shell transition matrix elements by

Solving a 1st resolvent type equation:

$$T_1(q) = T_1(q') + T_1(q) [g_0(q) - g_0(q')] T_1(q')$$

- For every single off-shell momentum point
- Proposed in
 - Keister & Polyzou, PRC 73, 014005 (2006)
- Carried out for the first time here **[PRC 76, 1014010 (2007)]**



Exact Boost



Obtain embedded 2N t-matrix $T_1(\mathbf{k}, \mathbf{k}', z')$ half-shell in 2-body c.m. frame first :

$$\begin{aligned}\langle \mathbf{k} | T_1(\mathbf{q}; z') | \mathbf{k}' \rangle &= \langle \mathbf{k} | V(\mathbf{q}) | \mathbf{p}'^{(-)} \rangle \\ &= \frac{2(E_{k'} + E_k)}{\sqrt{4E_{k'}^2 + \mathbf{q}^2} + \sqrt{4E_k^2 + \mathbf{q}^2}} t(\mathbf{k}, \mathbf{k}'; 2E_{k'})\end{aligned}$$

$$t(\mathbf{k}, \mathbf{k}'; 2E_{k'}) = v(\mathbf{k}, \mathbf{k}') + \int d\mathbf{k}'' \frac{v(\mathbf{k}, \mathbf{k}'') t(\mathbf{k}'', \mathbf{k}'; 2E_{k'})}{E_{k'} - 2\sqrt{m^2 + k''^2} + i\epsilon}$$

Solution of the relativistic 2N LS equation with 2-body potential

Consideration for two-body t-matrix

- Relativistic and non-relativistic t-matrix should give identical observables for determining relativistic effects
- Or two-body t-matrices should be phase-shift equivalent
- Four options:
 - Start from relativistic LS equation
 - natural option – employed for NN interactions fit to 1 GeV +
 - **If non-relativistic LS equation is used:**
 - Refit of parameters (maybe time consuming in practice)
 - Transformation of Kamada-Glöckle PRL 80, 2547 (1998)
 - **Transformation of Coester-Piper-Serduke as given in Polyzou PRC 58, 91 (1998)**

Phase equivalent 2-body t-matrices:

Coester-Pieper-Serduke (CPS) (PRC11, 1 (1975))

- Add interaction to square of non-interacting mass operator

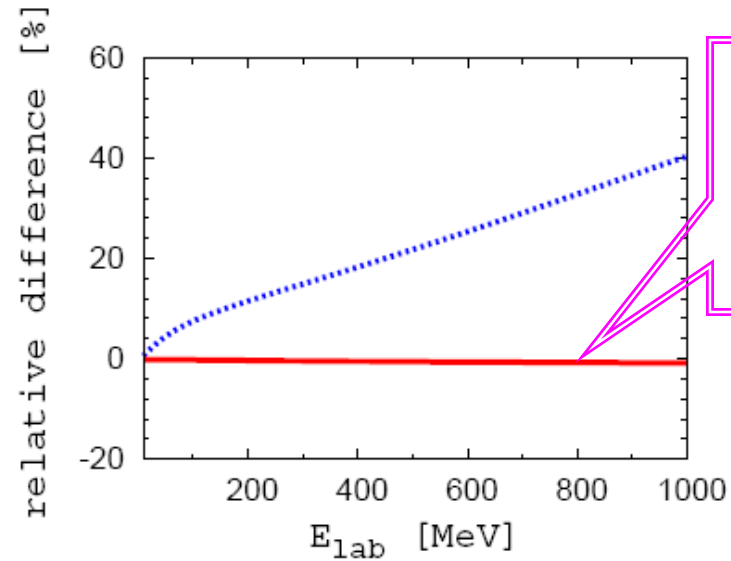
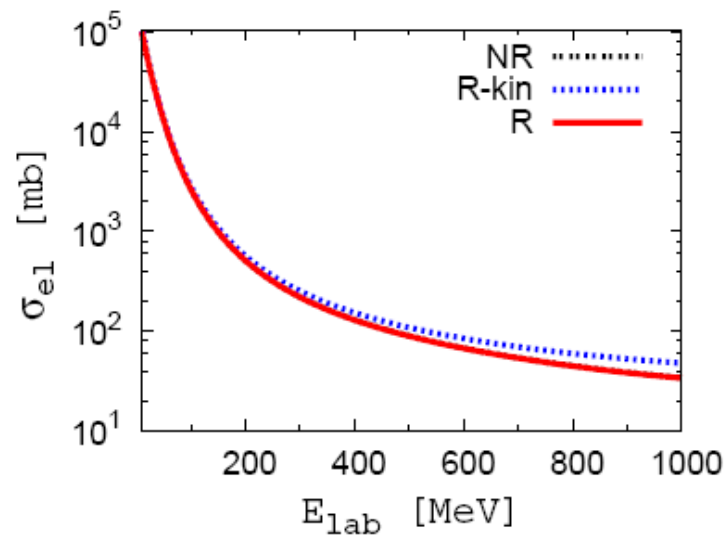
$$M^2 = M_0^2 + u = 4mh \quad \text{with} \quad h \equiv \frac{k^2}{m} + \frac{u}{4m} + m$$
$$u = v^2 + \{ M_0^2, v \}$$

- NO need to evaluate v directly, since M , M^2 , h have the same eigenstates
- Relation between half-shell t-matrices

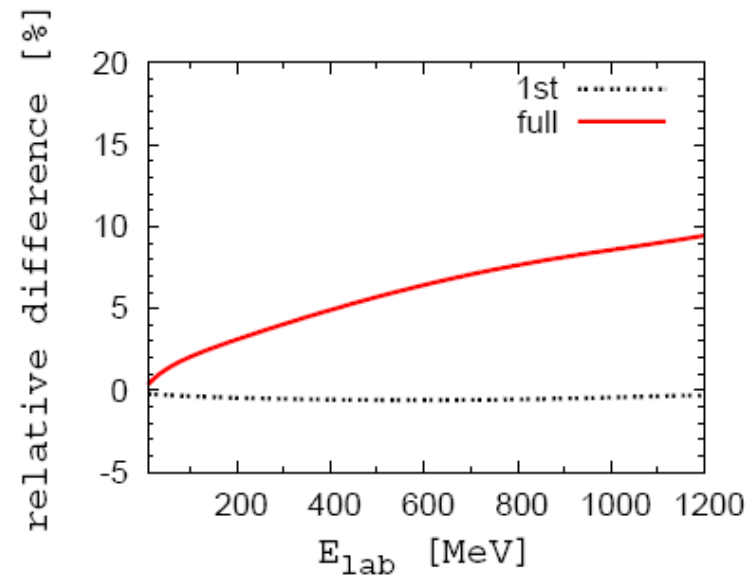
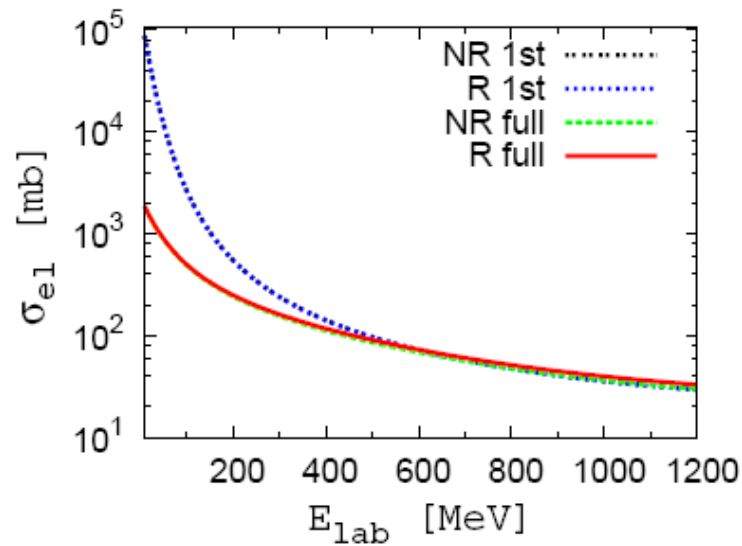
$$\langle k' | t_R(e(k)) | k \rangle = \frac{4m}{e(k) + e(k')} \langle k' | t_{NR}(k^2/m) | k \rangle$$

- Relativistic and nonrelativistic cross sections are identical functions of the invariant momentum k

Total Cross Section for Elastic Scattering:



1st
Order
T = t P

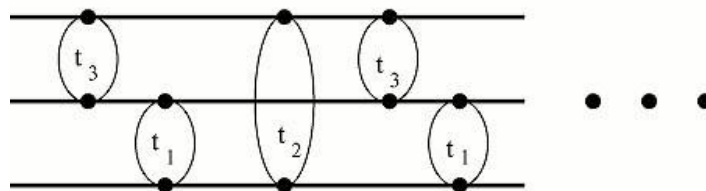


Faddeev Equation as Multiple Scattering Series

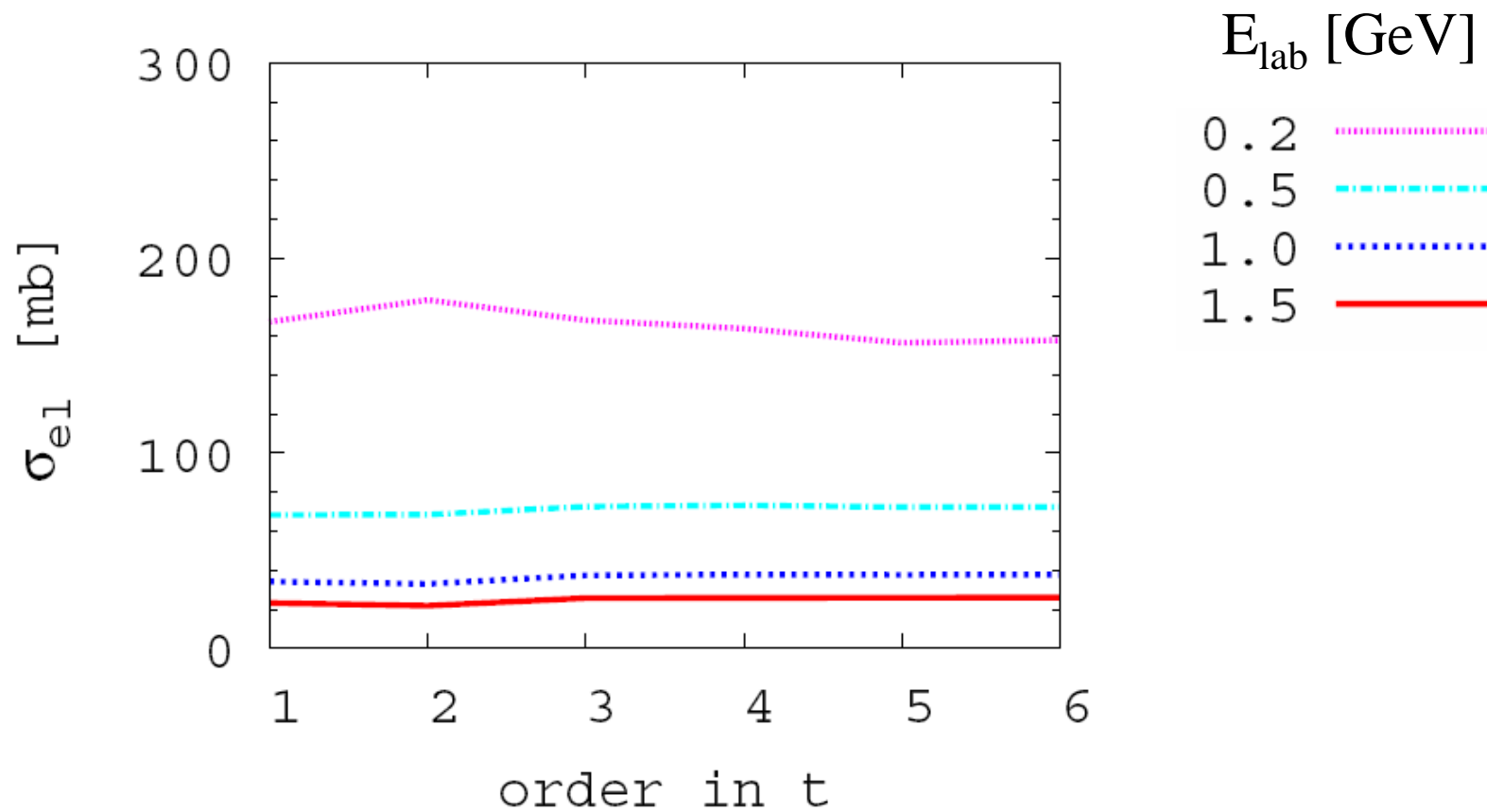
$$T = tP + tG_0PT$$

$$T = tP \Big| + tG_0PtP + \dots$$

1st Order or IA

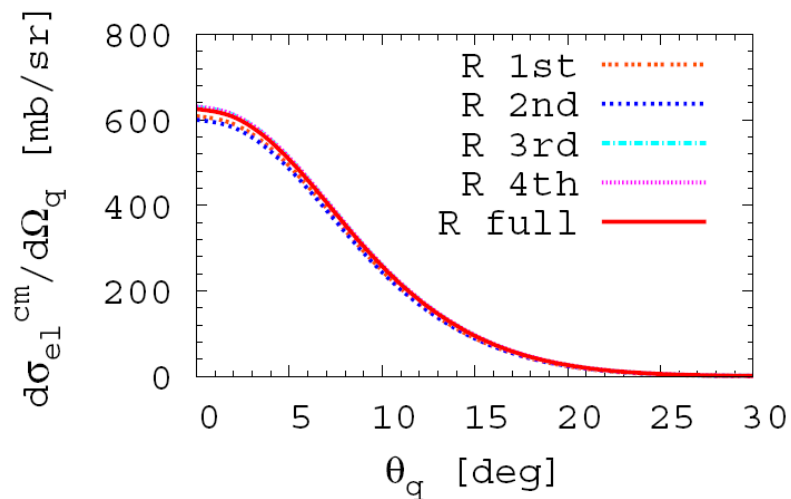


Convergence of the Faddeev Multiple Scattering Series

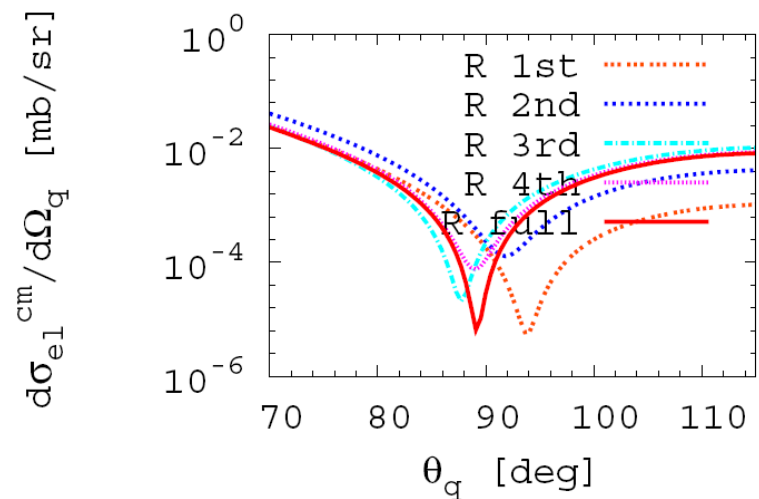


Elastic Scattering: Differential Cross Section

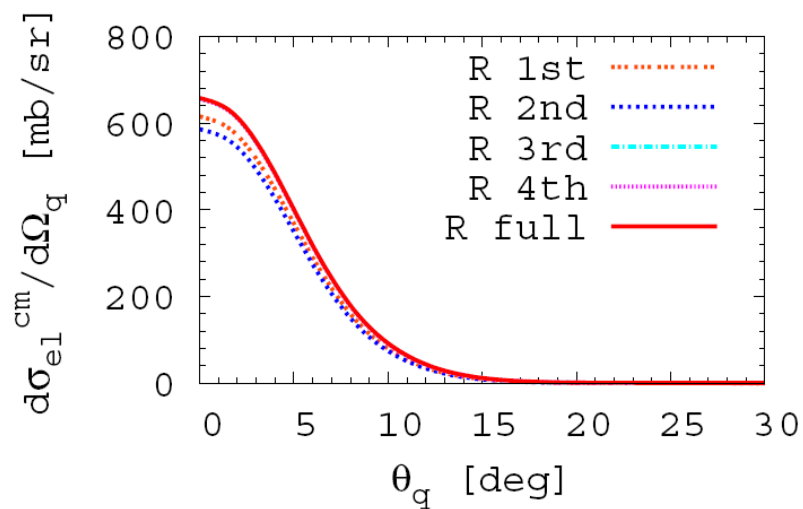
$E_{\text{lab}} = 500 \text{ MeV}$



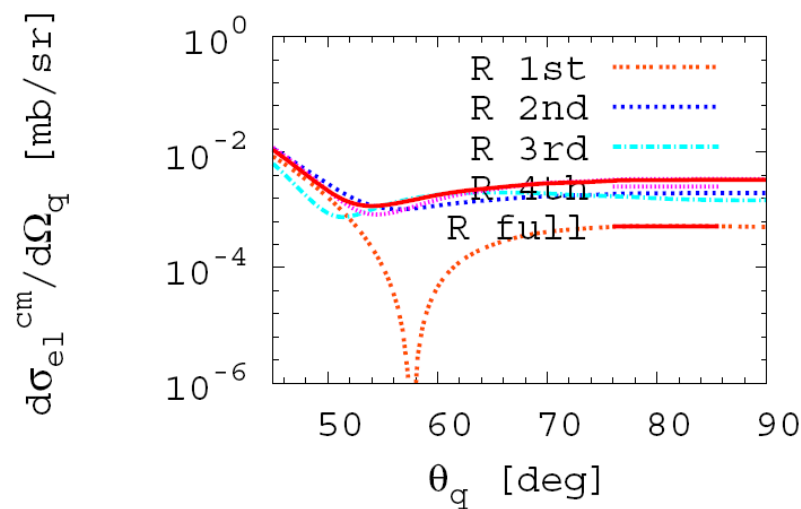
$E_{\text{lab}} = 500 \text{ MeV}$

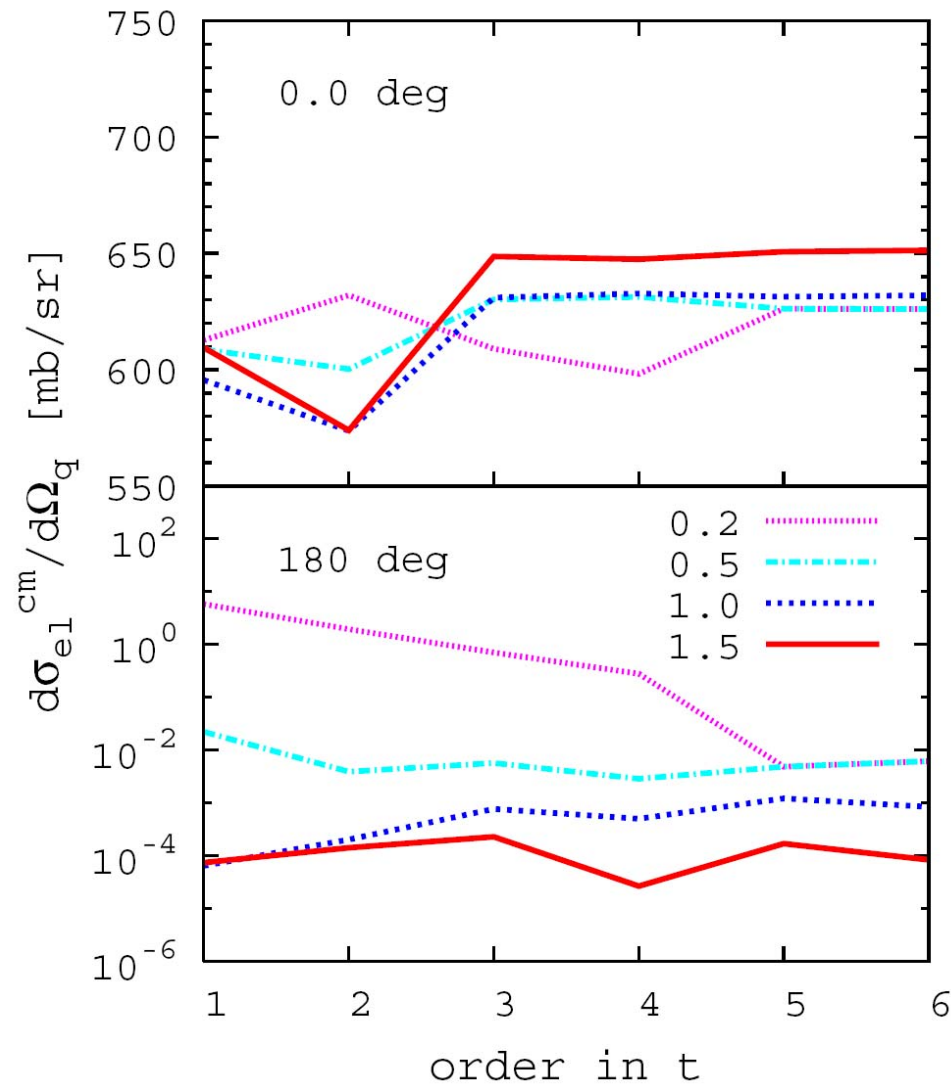


$E_{\text{lab}} = 1200 \text{ MeV}$



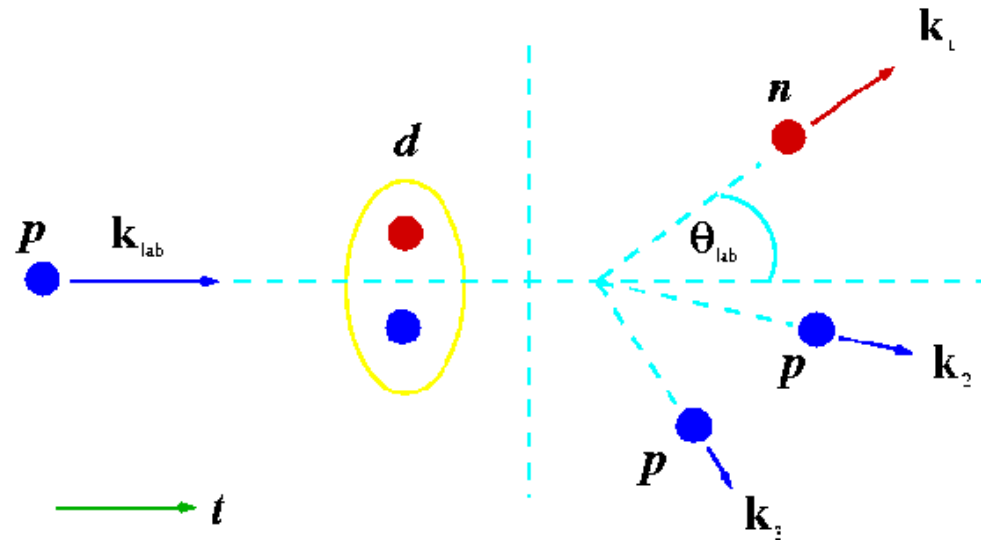
$E_{\text{lab}} = 1200 \text{ MeV}$





Differential Cross Section: Convergence of the Faddeev Multiple Scattering Series

Breakup Scattering



Exclusive: Measure energy & angles of two ejected particles

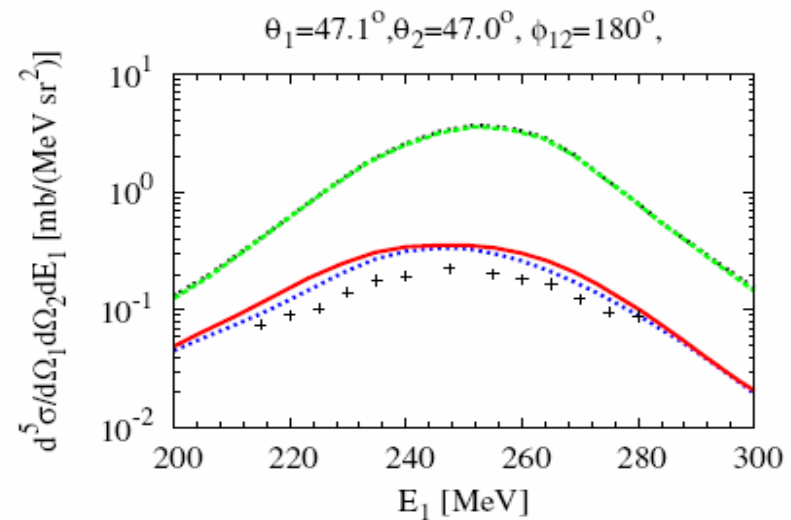
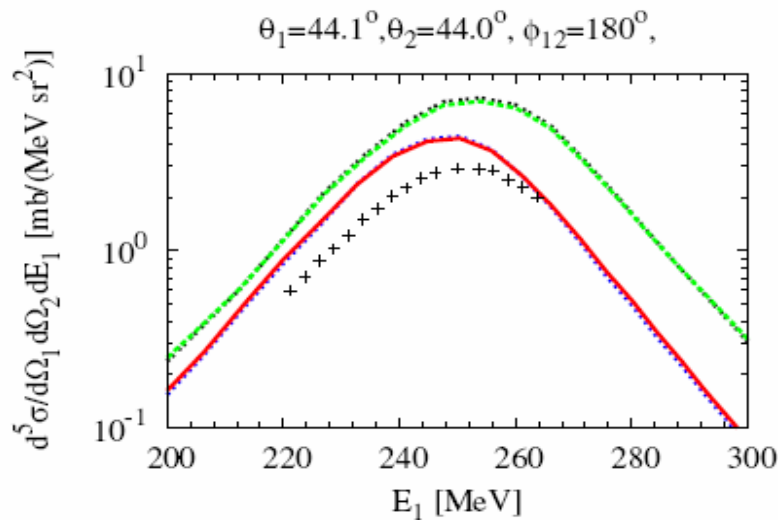
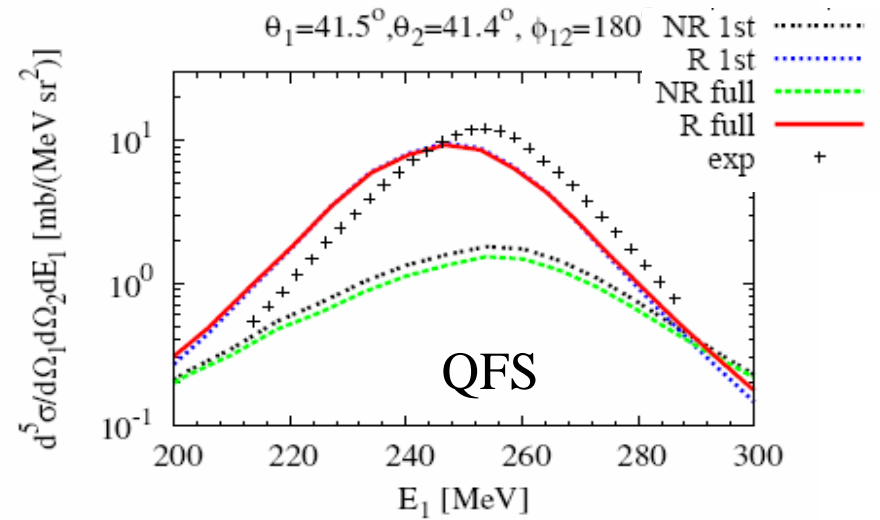
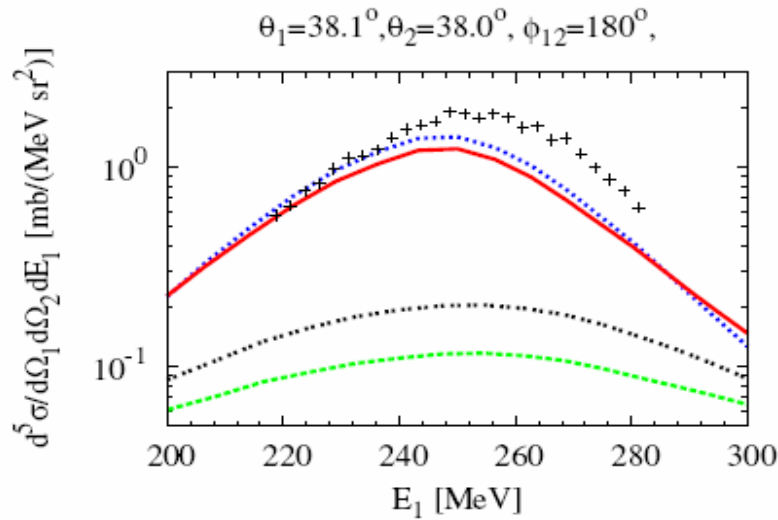
V.Punjabi et al. PRC 38, 2728 (1998) – TRIUMF p+d @ 508 MeV

Outgoing protons are measured in the scattering plane

Exclusive Breakup Scattering (symmetric configuration)

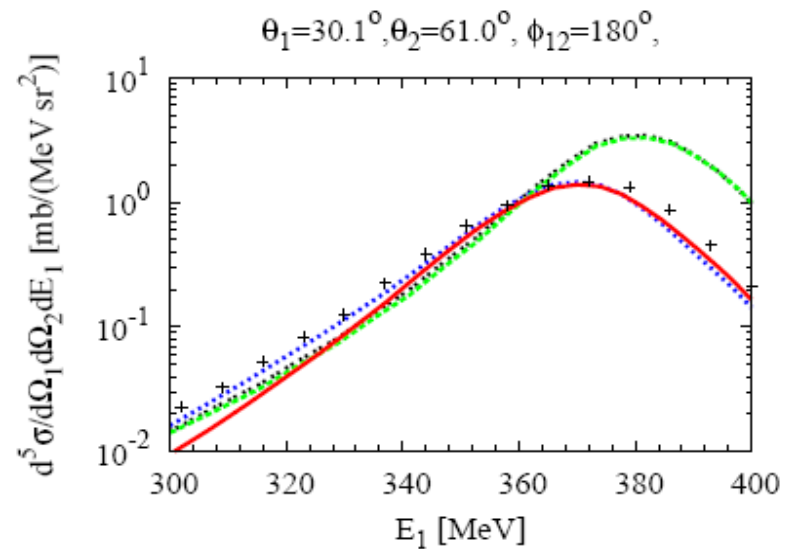
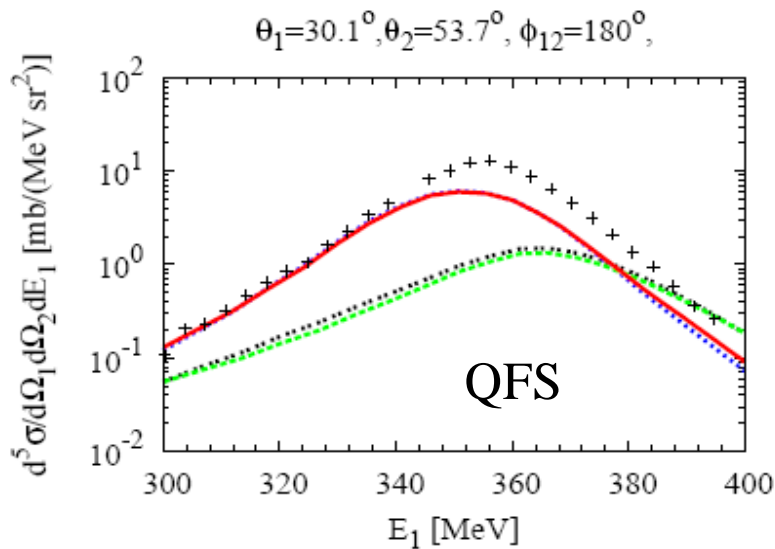
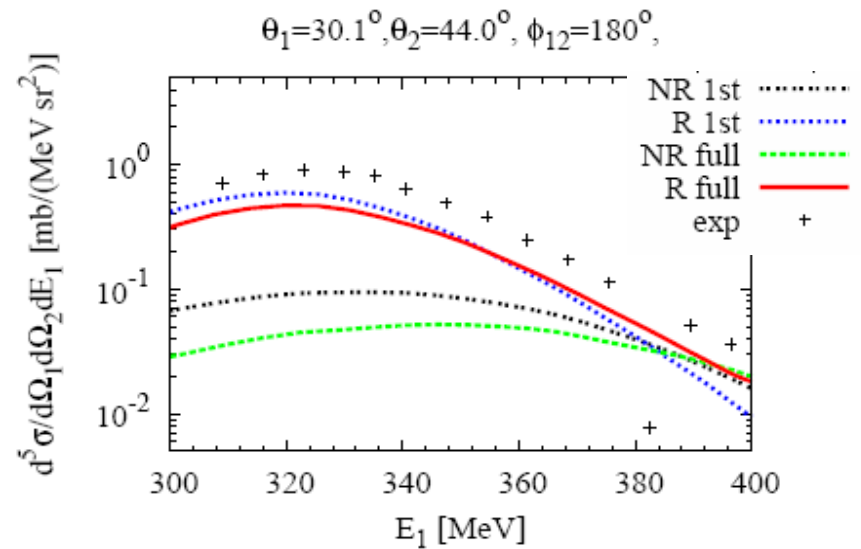
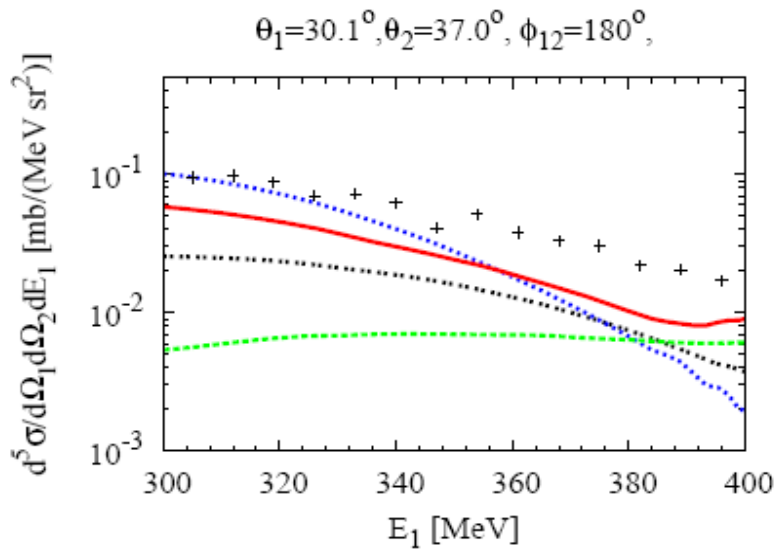
$E_{\text{lab}} = 508 \text{ MeV}$

(V.Punjabi et al. PRC 38, 2728 (1998))



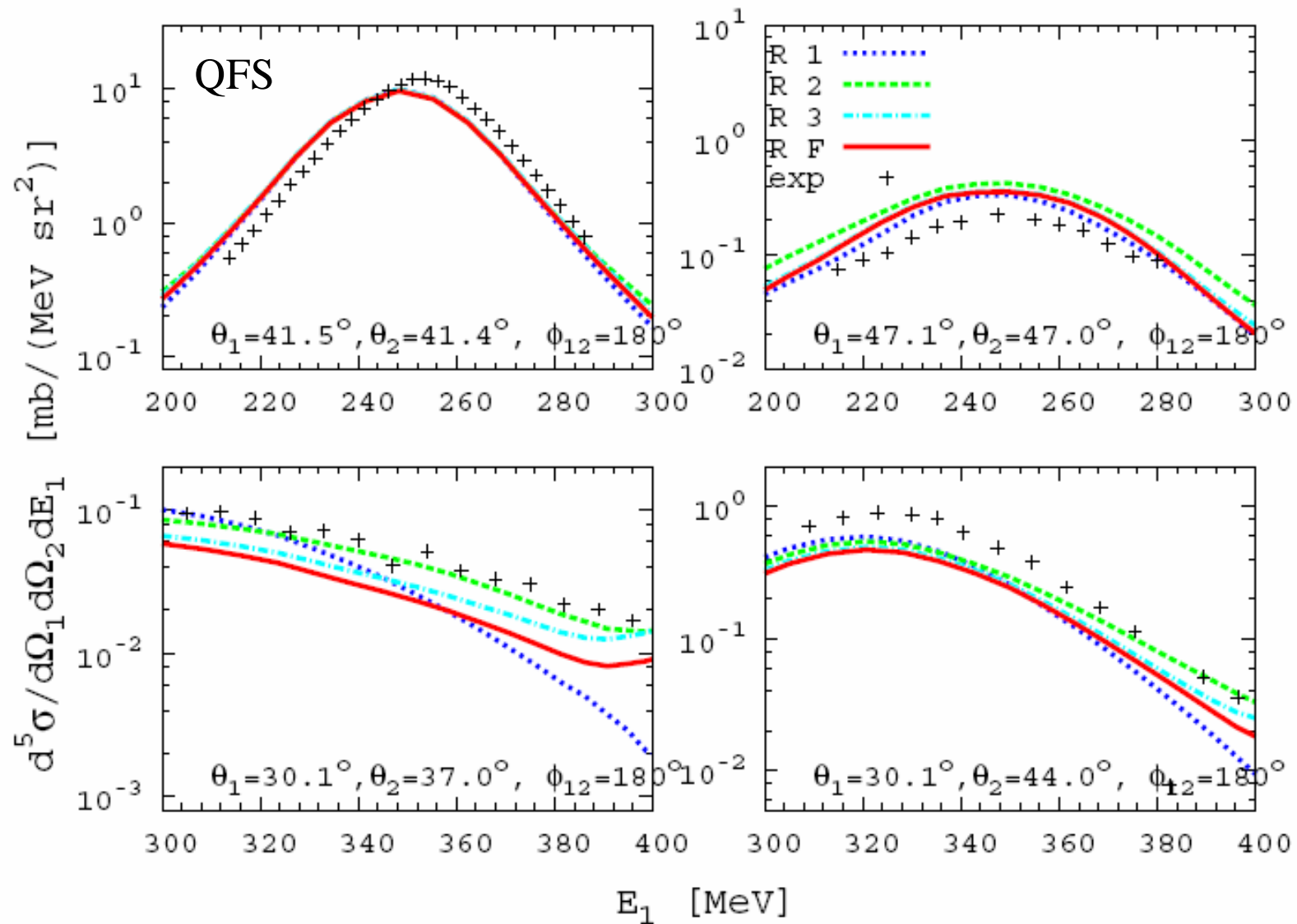
Exclusive Breakup Scattering (asymmetric configuration)

$E_{lab} = 508 \text{ MeV}$

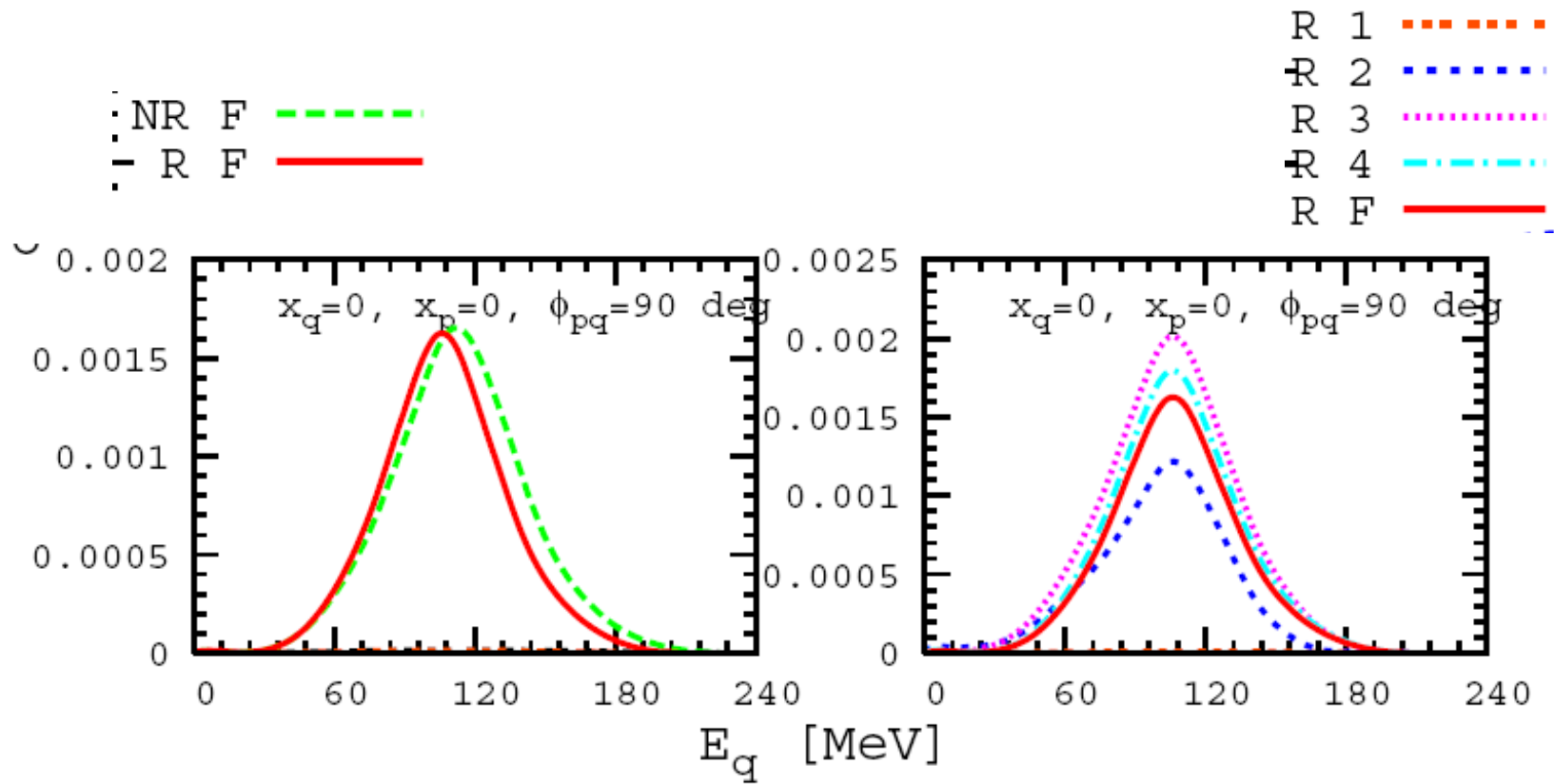


Exclusive Breakup Scattering

$E_{\text{lab}} = 508 \text{ MeV}$



Exclusive Breakup Scattering Space-Star



$$E_{\text{lab}} = 508 \text{ MeV}$$

Poincaré Invariant Faddeev Calculations

- Kinematics
 - Phase space factors
 - Lorentz Transformation from Lab to c.m. frame
 - Lorentz Transformation of Jacobi Coordinates
 - Always reduces effects of phase-space factors
 - Kinematics determines peak positions in break-up observables
- Dynamics
 - Exact calculation of the two-body interaction embedded in the three-particle Hilbert space
 - The dynamic effects act in general opposite kinematic effects

Poincaré Invariant Faddeev Calculations

- **Carried out up to 2 GeV for elastic and breakup scattering**
 - Solved Faddeev equation in vector variables = NO partial waves
- **Relativistic effects are important at 500 MeV and higher**
 - Relativistic total elastic cross section increases up to 10% compared to the non-relativistic
 - Relativistic kinematics determines QFS peak positions in inclusive and exclusive breakup
 - Breakup: Relativistic effects very large dependent on configuration
- **Above 800 MeV projectile energy:**
 - multiple scattering series converges after ~2 iterations
- **Future**
 - Systematic studies of selected cross sections & high energy limits
 - Long term: include Spin