

A critical study of the Monte Carlo replica method

Mark N. Costantini

DIS 2024

arXiv:2404.xxxxx, MNC, M. Madigan, L. Mantani, J. Moore

8-12 April 2024, Grenoble, France



**UNIVERSITY OF
CAMBRIDGE**



Funded by
the European Union



European Research Council
Established by the European Commission

PBSP



Outline

- Introduction: estimation of uncertainties on parameters
 - Bayesian credible regions
 - Monte Carlo replica method
- The Monte Carlo replica posterior
 - Mathematical derivation
 - Toy models
- Applications in high energy physics
 - SMEFT Fits
 - PDF Fits
- Summary and outlook



Introduction

Introduction

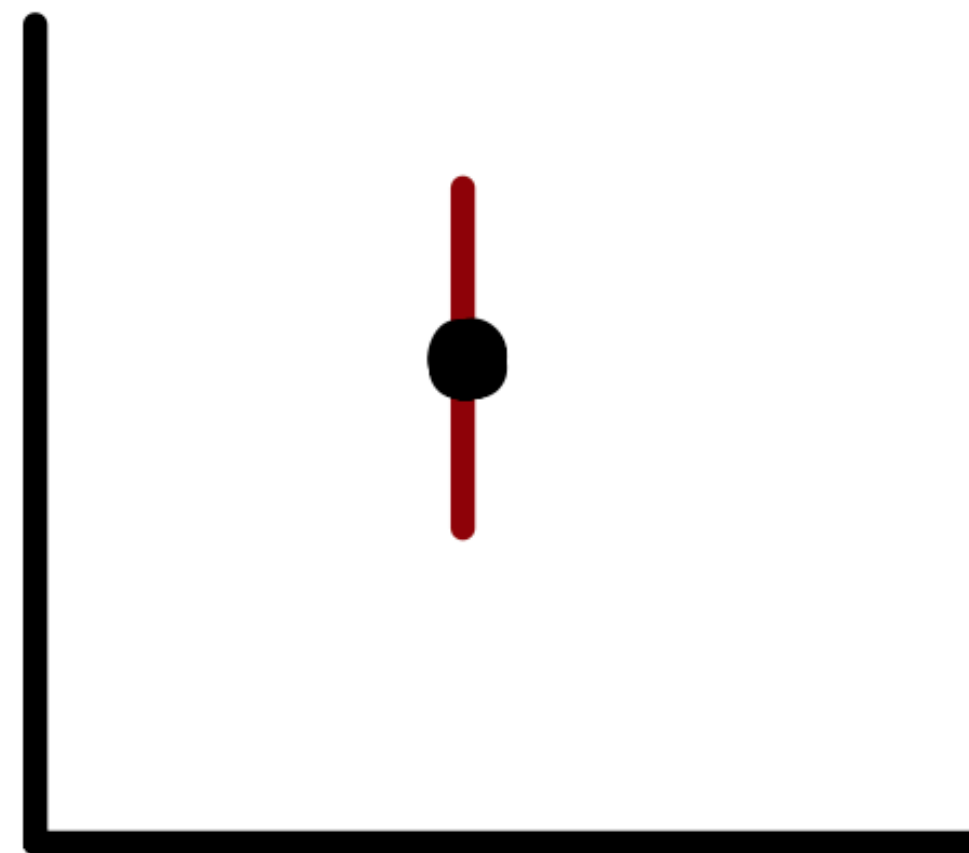
Setup of the problem

X : observed data

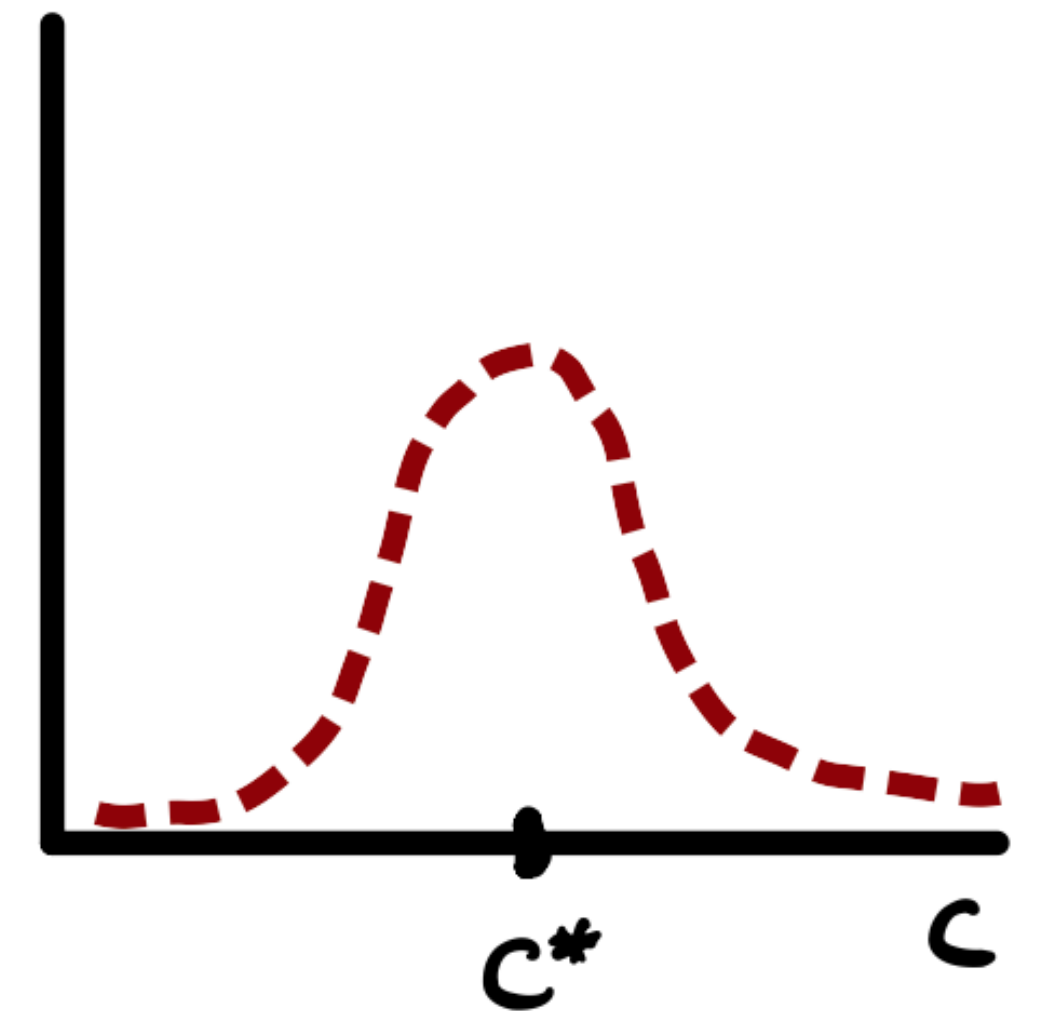
$X \sim \mathbb{P}$: Data generating process

$t[\mathbf{c}]$: Modelling of the data

DATA



MODEL



What is a plausible range of values for the parameter(s) \mathbf{c} ?

Introduction

Bayesian approach: credible regions

c : Random variable

$$\pi(\mathbf{c} | X) \propto \pi(\mathbf{c}) L(X | \mathbf{c})$$



Posterior
distribution

Prior distribution

Likelihood

Credible region:

A $(100 \cdot \gamma) \%$ credible region (A, B) has $\pi(A \leq \mathbf{c} \leq B | X) = \gamma$

Introduction

Monte Carlo replica method approach

use the knowledge of \mathbb{P} to generate N (pseudo) data samples

$$X_1, \dots, X_N \sim \mathbb{P}$$

for each of the samples we compute an estimate of the parameter

$$\{\mathbf{c}_1^*, \dots, \mathbf{c}_N^*\}$$

$$\text{e.g. } \mathbf{c}_i^* = \operatorname{argmin}_{\mathbf{c}} \log(L(X_i | \mathbf{c}))$$

use this collection of samples as an approximation of the posterior

The Monte Carlo Posterior

Monte Carlo replica method

Suppose that experimental data is distributed according to a multivariate normal

$$\mathbf{d} \sim \mathcal{N}(\mathbf{t}(\mathbf{c}), \Sigma), \quad \Sigma \in \mathbb{R}^{N_{\text{dat}} \times N_{\text{dat}}}, \quad \mathbf{t} : \mathbb{R}^{N_{\text{param}}} \rightarrow \mathbb{R}^{N_{\text{dat}}}$$

Bayesian posterior

$$P_B(\mathbf{c} | \mathbf{d}_0) \propto \pi(\mathbf{c}) \exp\left(-\frac{1}{2} \chi^2(\mathbf{t}(\mathbf{c}), \mathbf{d}_0)\right)$$

Monte Carlo replica method:

- Pseudodata distribution $\mathbf{d}_p \sim \mathcal{N}(\mathbf{d}_0, \Sigma)$
- “Best fit parameter”
 $\mathbf{c}_p(\mathbf{d}_p) = \operatorname{argmin}_{\mathbf{c}} (\mathbf{d}_p - \mathbf{t}(\mathbf{c}))^T \Sigma^{-1} (\mathbf{d}_p - \mathbf{t}(\mathbf{c}))$

How is $\mathbf{c}_p(\mathbf{d}_p)$ distributed?

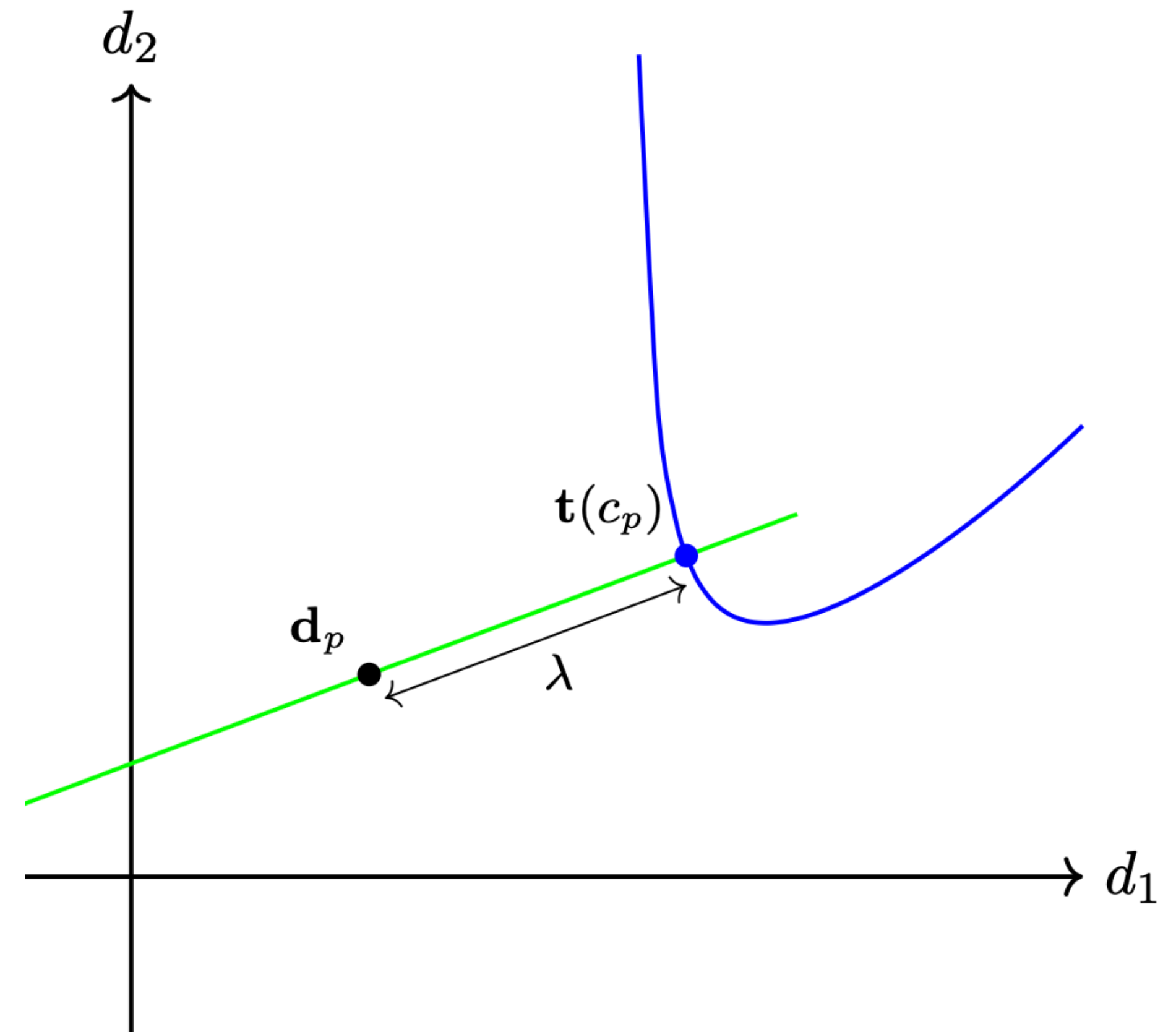
Monte Carlo Posterior

$\mathbf{c}_p(\mathbf{d}_p)$ is a random function of \mathbf{d}_p

$$P_{\text{MC}}(\mathbf{c}) \propto \int d^{N_{\text{dat}}} \mathbf{d}_p \delta(\mathbf{c} - \mathbf{c}_p(\mathbf{d}_p)) \exp\left(-\frac{1}{2}(\mathbf{d}_p - \mathbf{d}_0)^T \Sigma^{-1}(\mathbf{d}_p - \mathbf{d}_0)\right)$$

A general form for $P_{\text{MC}}(\mathbf{c})$ can be found by performing a coordinate transformation

$$\mathbf{d}_p \rightarrow (\mathbf{c}_p, \lambda)$$



Monte Carlo Posterior

Linear theory

See also L. D. Debbio, T. Giani, M. Wilson [2111.05787]

$$t(\mathbf{c}) = t_0 + t_{\text{lin}} \mathbf{c}$$

The Monte Carlo posterior

$$P_{\text{MC}}(\mathbf{c}) \propto \int d^{N_{\text{dat}}} \mathbf{d}_p \delta(\mathbf{c} - \mathbf{c}_p(\mathbf{d}_p)) \exp\left(-\frac{1}{2}(\mathbf{d}_p - \mathbf{d}_0)^T \Sigma^{-1}(\mathbf{d}_p - \mathbf{d}_0)\right)$$

reduces to

$$P_{\text{MC}}(\mathbf{c}) \propto \exp\left(-\frac{1}{2} \chi_{\mathbf{d}_0}^2(\mathbf{c})\right)$$

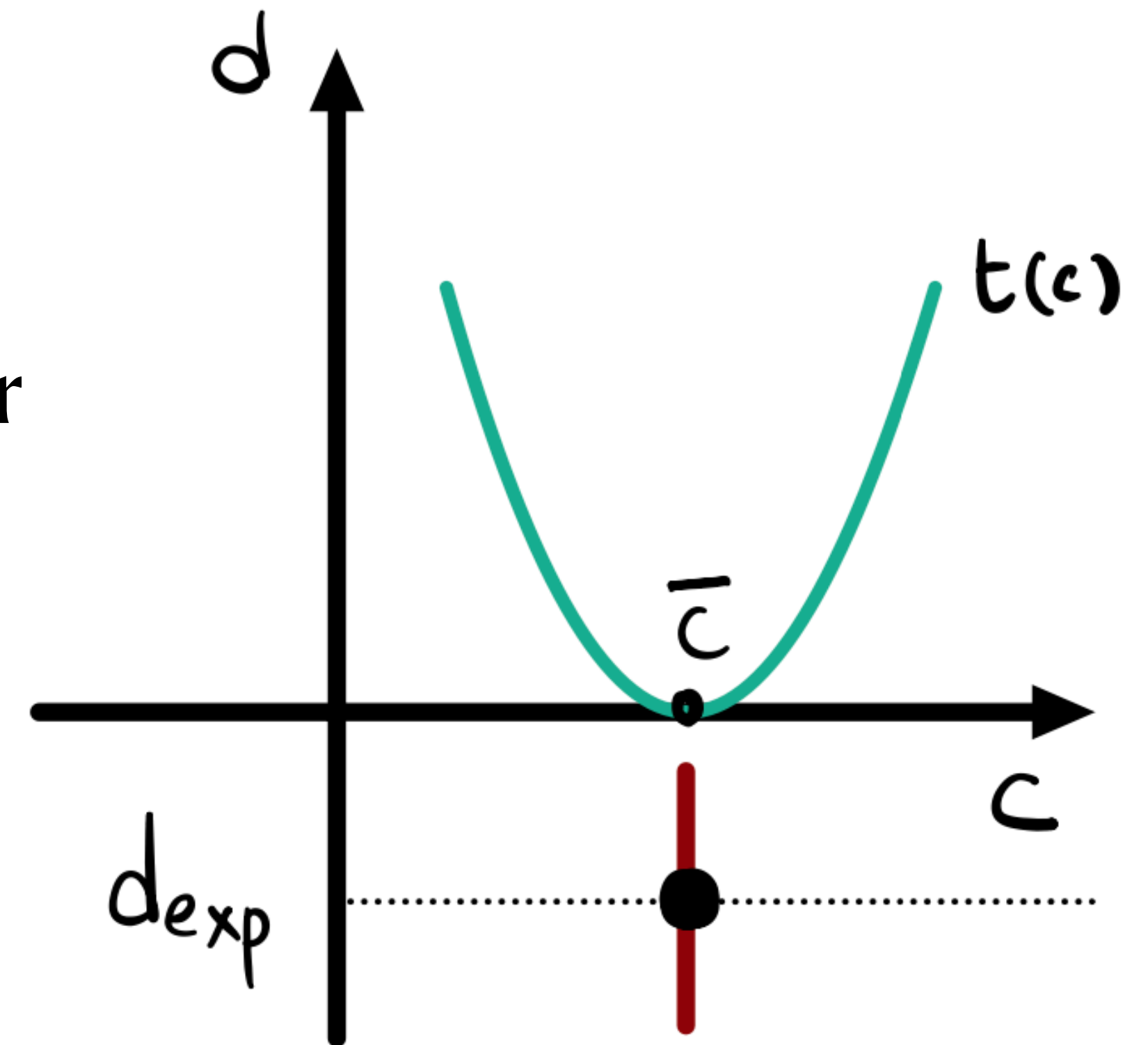
For a linear theory, the Bayesian and Monte Carlo approaches coincide (wide flat prior)

Monte Carlo Posterior

Quadratic Model

Let's consider one datapoint, one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c + t_{\text{quad}}c^2, t_{\text{quad}} > 0$$



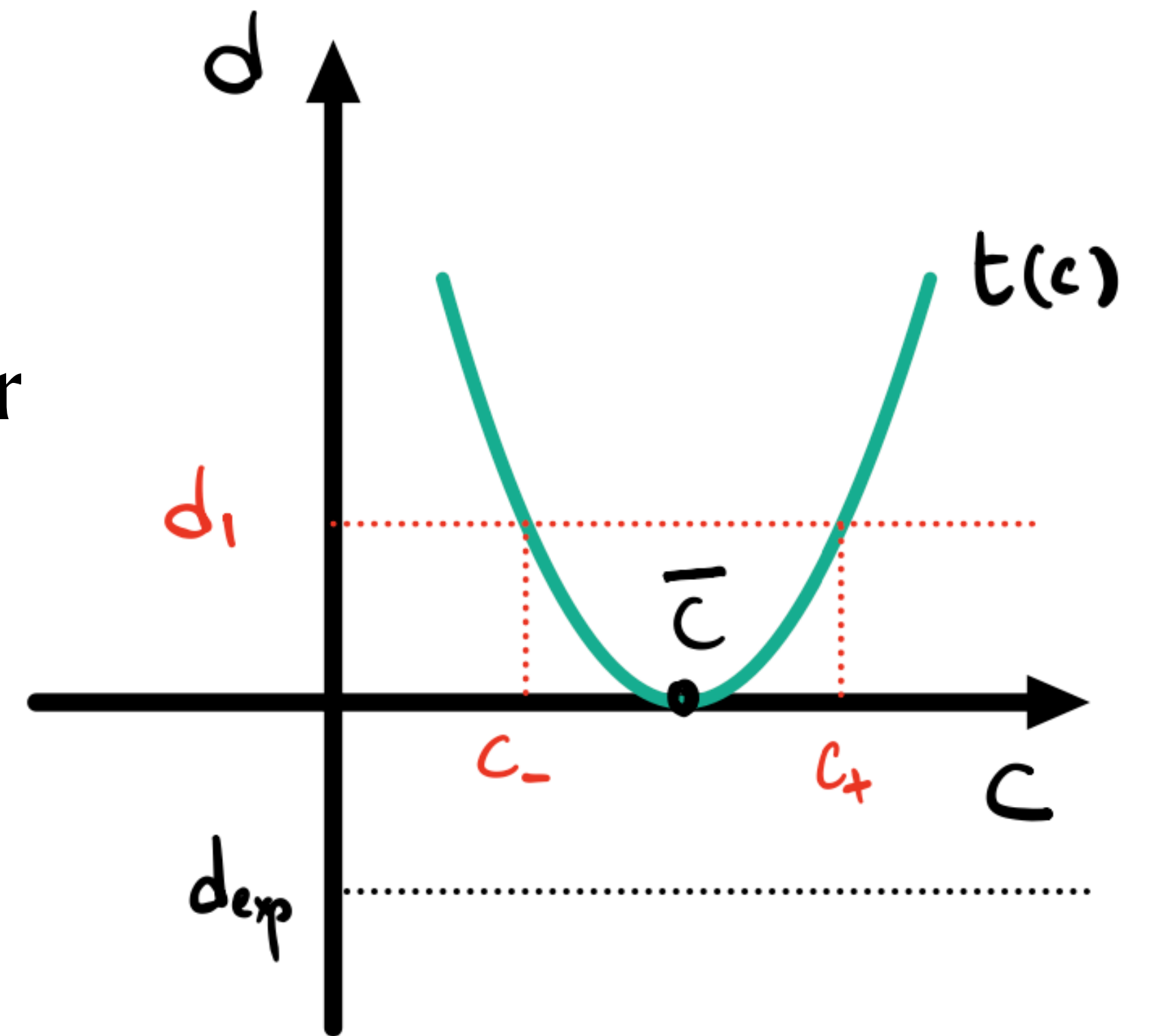
Monte Carlo Posterior

Quadratic Model

Let's consider one datapoint, one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c + t_{\text{quad}}c^2, \quad t_{\text{quad}} > 0$$

$$\chi^2 = \frac{(t(c) - d_{\text{exp}})^2}{\sigma_{\text{exp}}^2}, \quad \Delta\chi^2 = \chi^2 - \chi_{\text{min}}^2 = 1 \quad \rightarrow [c_-, c_+]$$



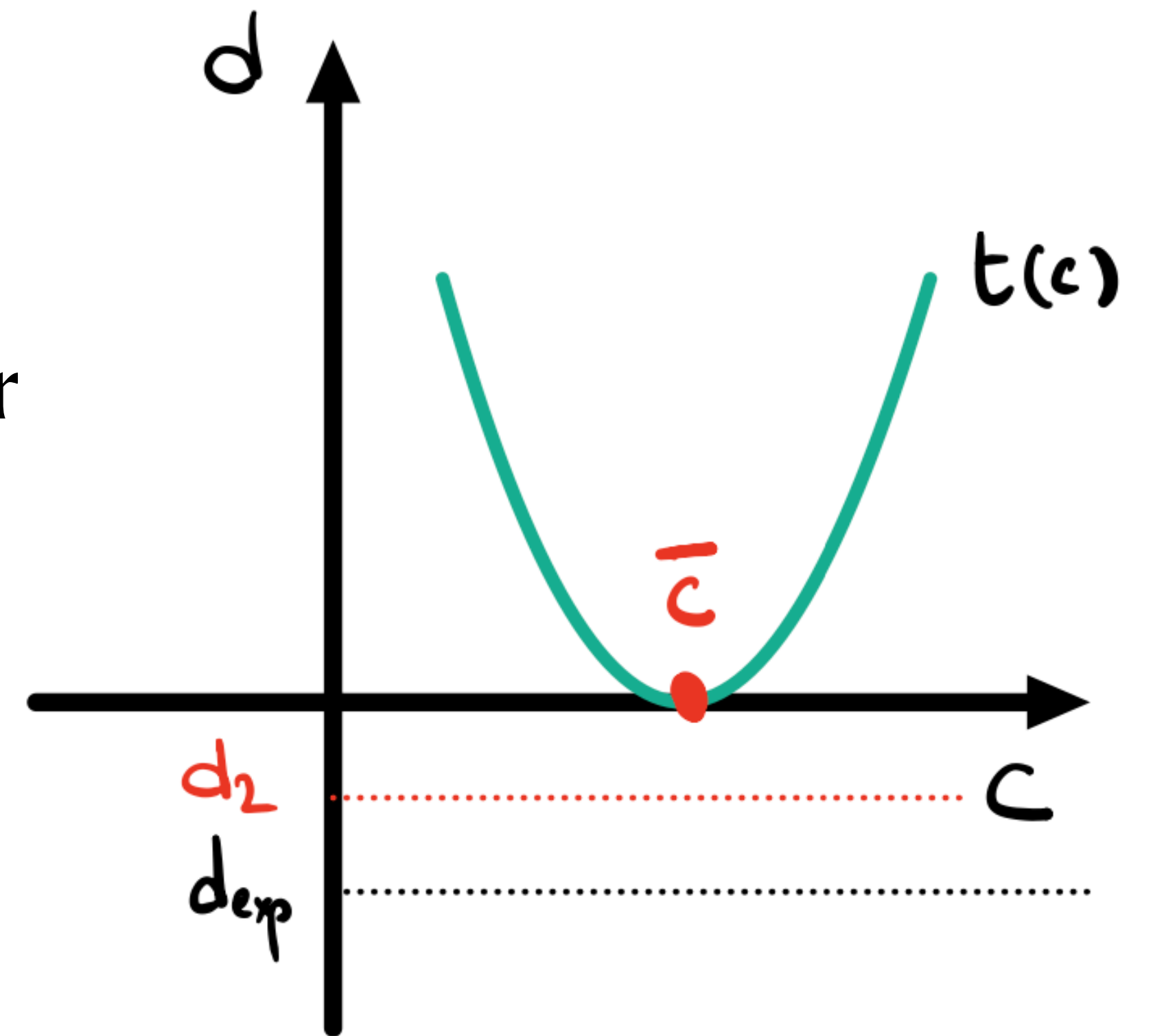
Monte Carlo Posterior

Quadratic Model

Let's consider one datapoint, one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c + t_{\text{quad}}c^2, t_{\text{quad}} > 0$$

$$c = -\frac{t_{\text{lin}}}{2t_{\text{quad}}}$$

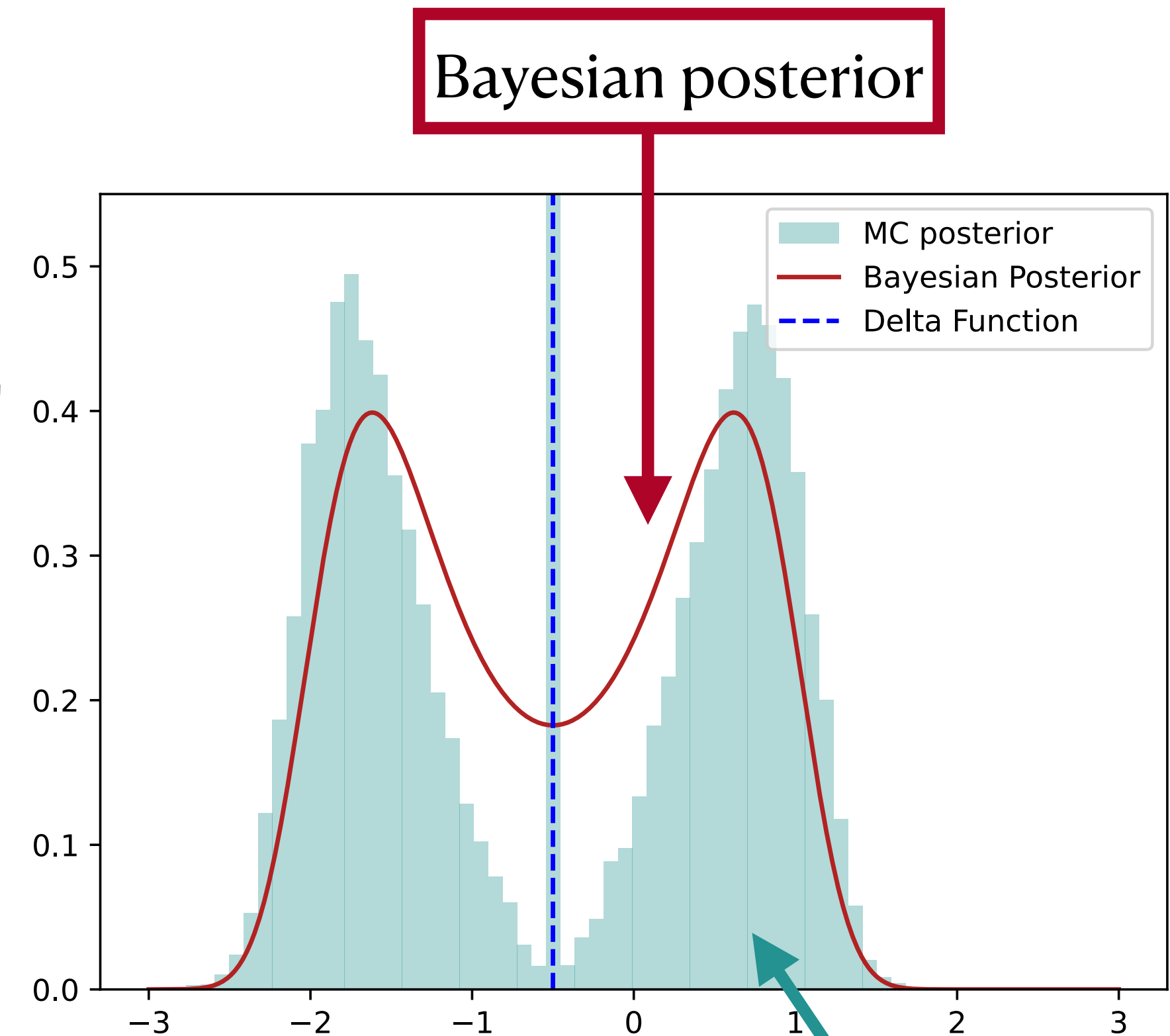


Monte Carlo Posterior

Quadratic Model

Let's consider one datapoint, one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c + t_{\text{quad}}c^2, \quad t_{\text{quad}} > 0$$



$$P_{\text{MC}}(c) \propto \delta\left(c + \frac{t_{\text{lin}}}{2t_{\text{quad}}}\right) \int_{-\infty}^{t_{\text{min}}} dd_p \exp\left(-\frac{1}{2} \frac{(d_0 - d_p)^2}{\sigma^2}\right) + 2 |t_{\text{lin}} + 2ct_{\text{quad}}| \exp\left(-\frac{1}{2} \frac{(d_0 - t(c))^2}{\sigma^2}\right)$$

MC posterior

Independent on d_p : $\frac{\partial t(c)}{\partial c}$ has not full rank

2 roots

“Determinant” factor

.....

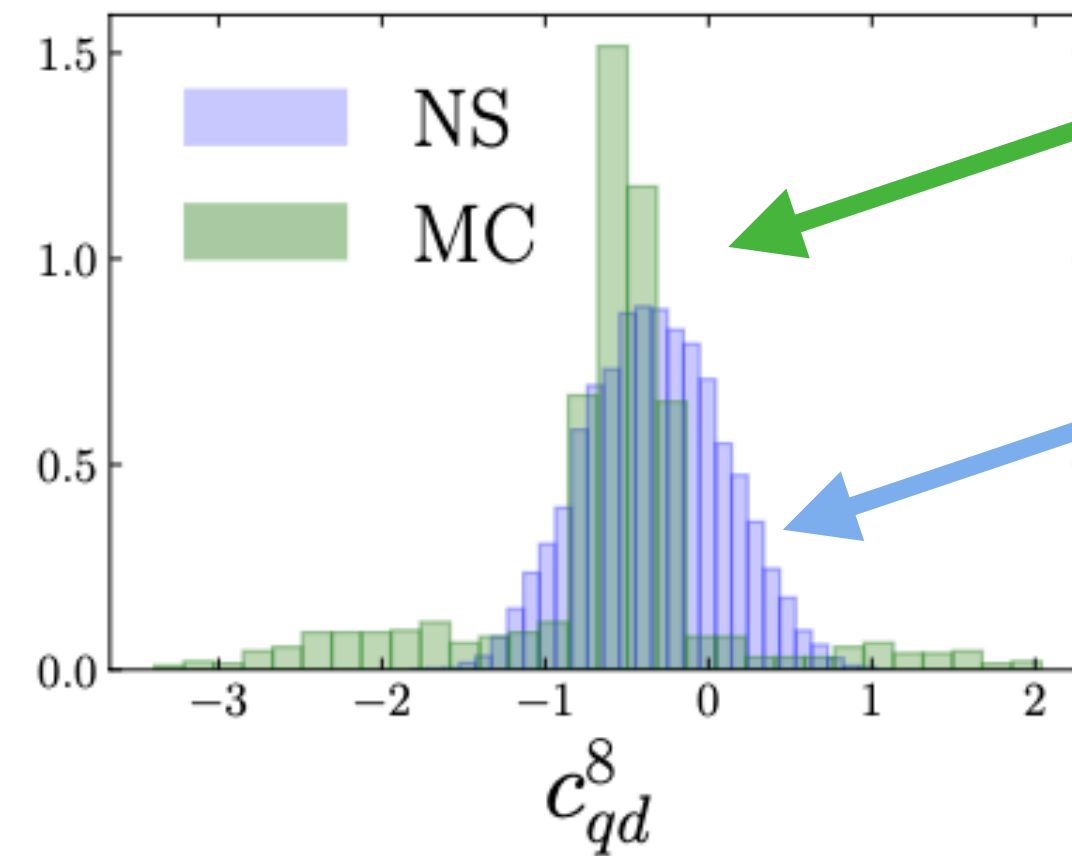
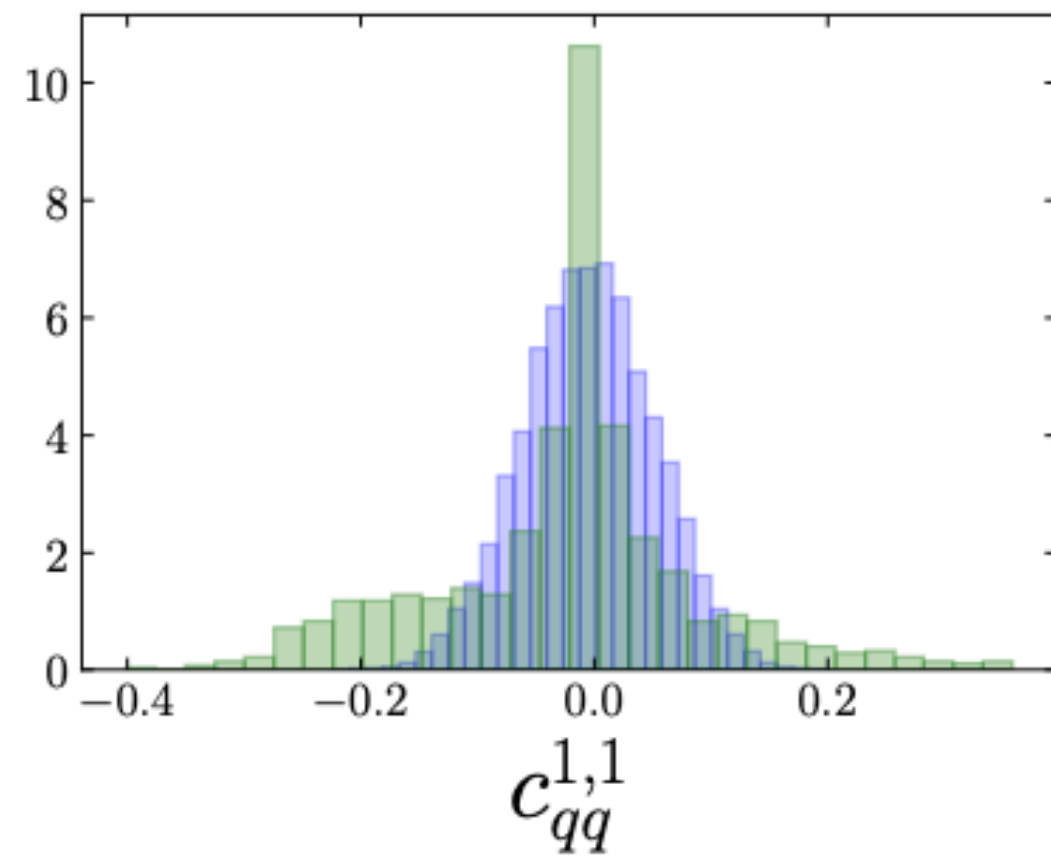
Applications in HEP

.....

Applications in HEP

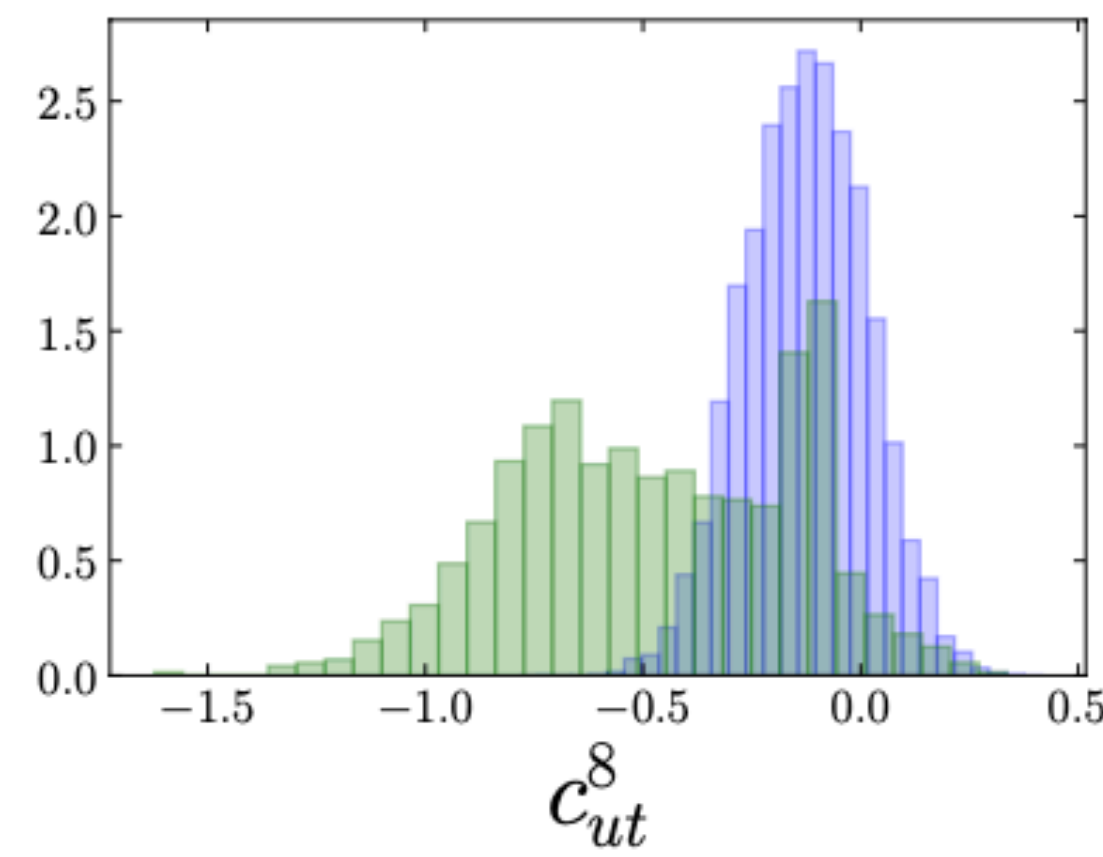
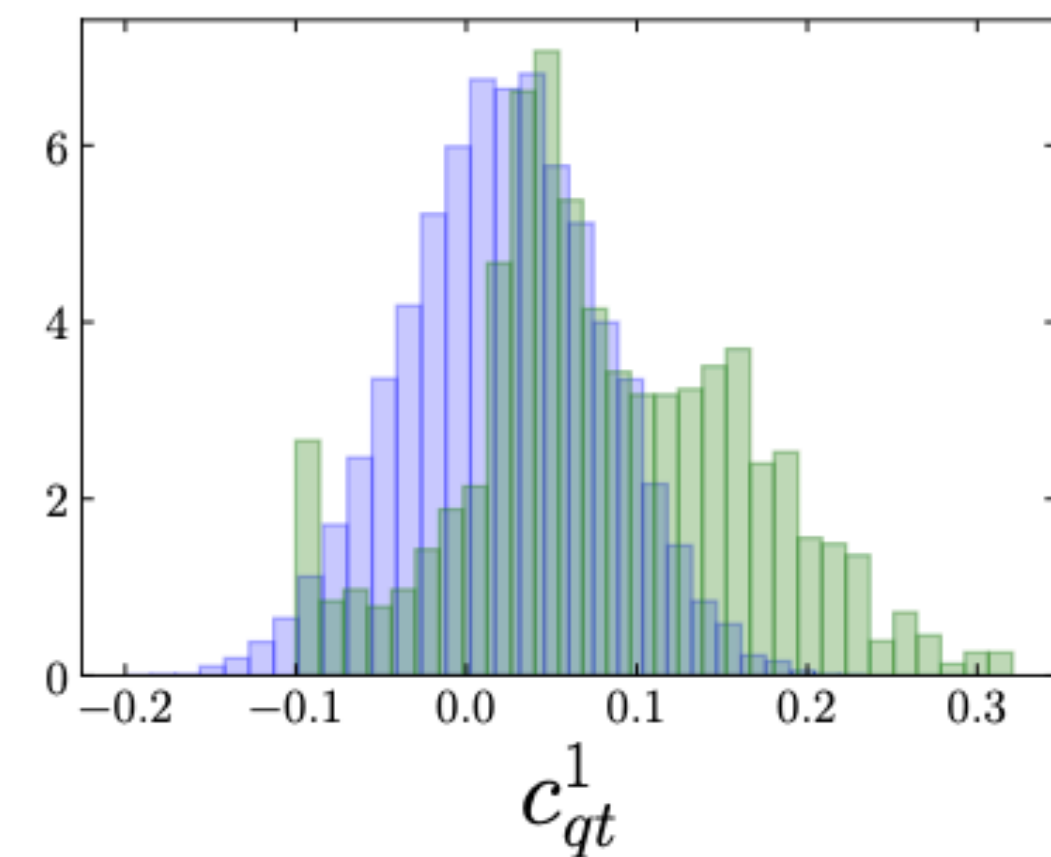
SMEFT fit in TOP sector

SMEFiT [2302.06660]



Monte Carlo

Nested Sampling



4 fermions operators are dominated by quadratic Wilson coefficients

$$\mathcal{O} = \mathcal{O}_{SM} + \frac{C_i}{\Lambda^2} \mathcal{O}_i^{INT} + \frac{C_i C_j}{\Lambda^4} \mathcal{O}_{ij}^{SQ}$$

Applications in HEP

PDF fits

three flavours in the evolution basis: Σ , g , V

for each flavour we choose a grid

$$(x_1^f, \dots, x_N^f)$$

reduced grid is treated as an interpolation grid

$$f(x, Q_0^2) = \begin{cases} f(x_1^f, Q_0^2) & \text{if } x \leq x_1^f; \\ \left(\frac{x_{i+1}^f - x}{x_{i+1}^f - x_i^f} \right) f(x_i^f, Q_0^2) + \left(\frac{x - x_i^f}{x_{i+1}^f - x_i^f} \right) f(x_{i+1}^f, Q_0^2) & \text{if } x \in [x_i, x_{i+1}], \text{ for } i = 1, \dots, N_{\text{grid}}(f); \\ f(x_{N_{\text{grid}}(f)}^f, Q_0^2) & \text{if } x > x_{N_{\text{grid}}(f)}^f. \end{cases}$$

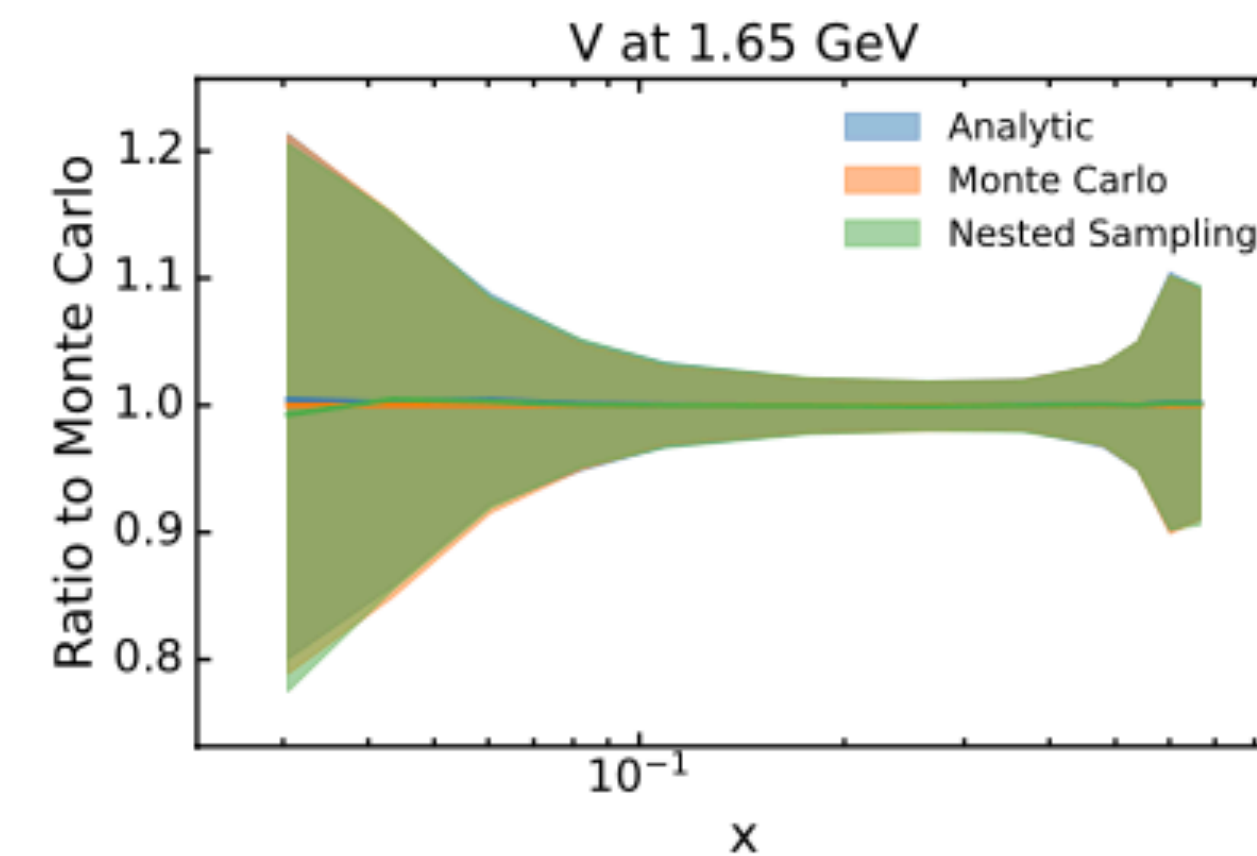
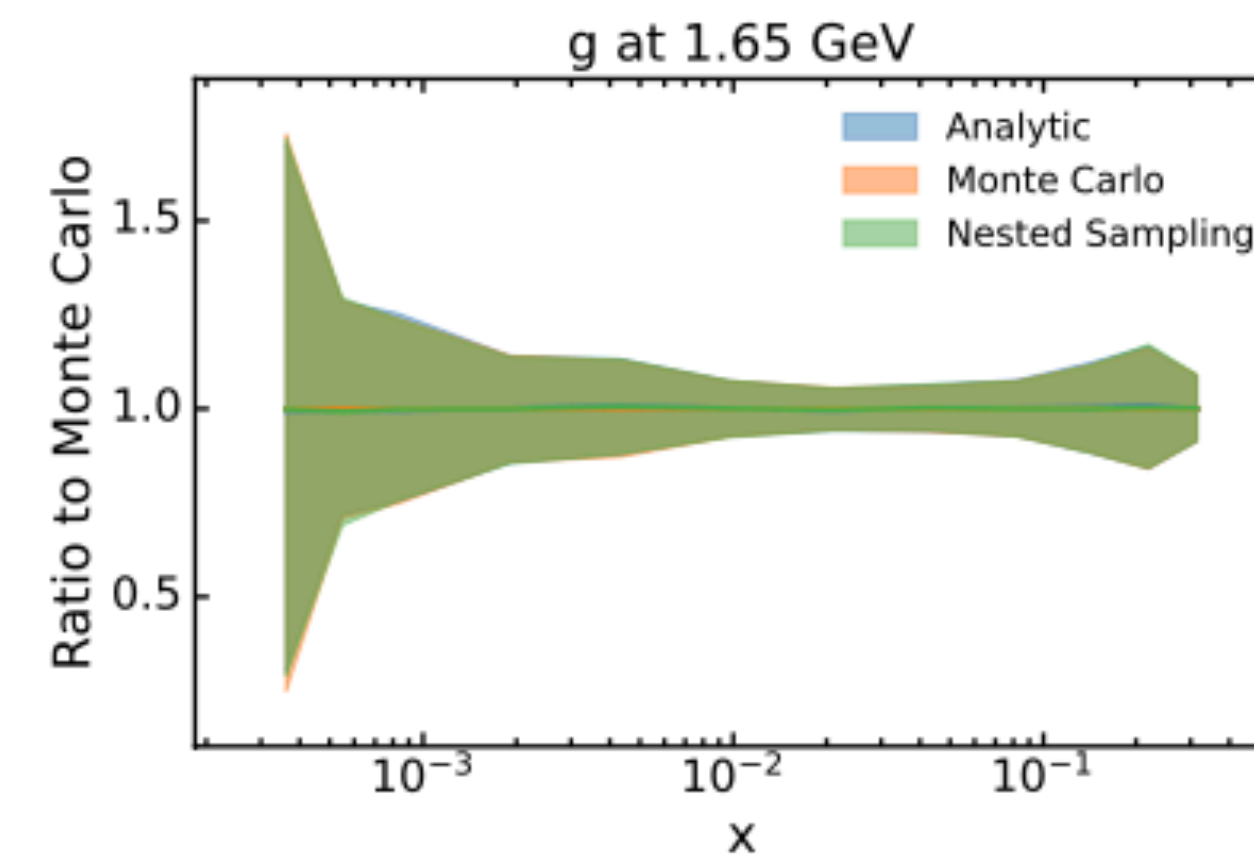
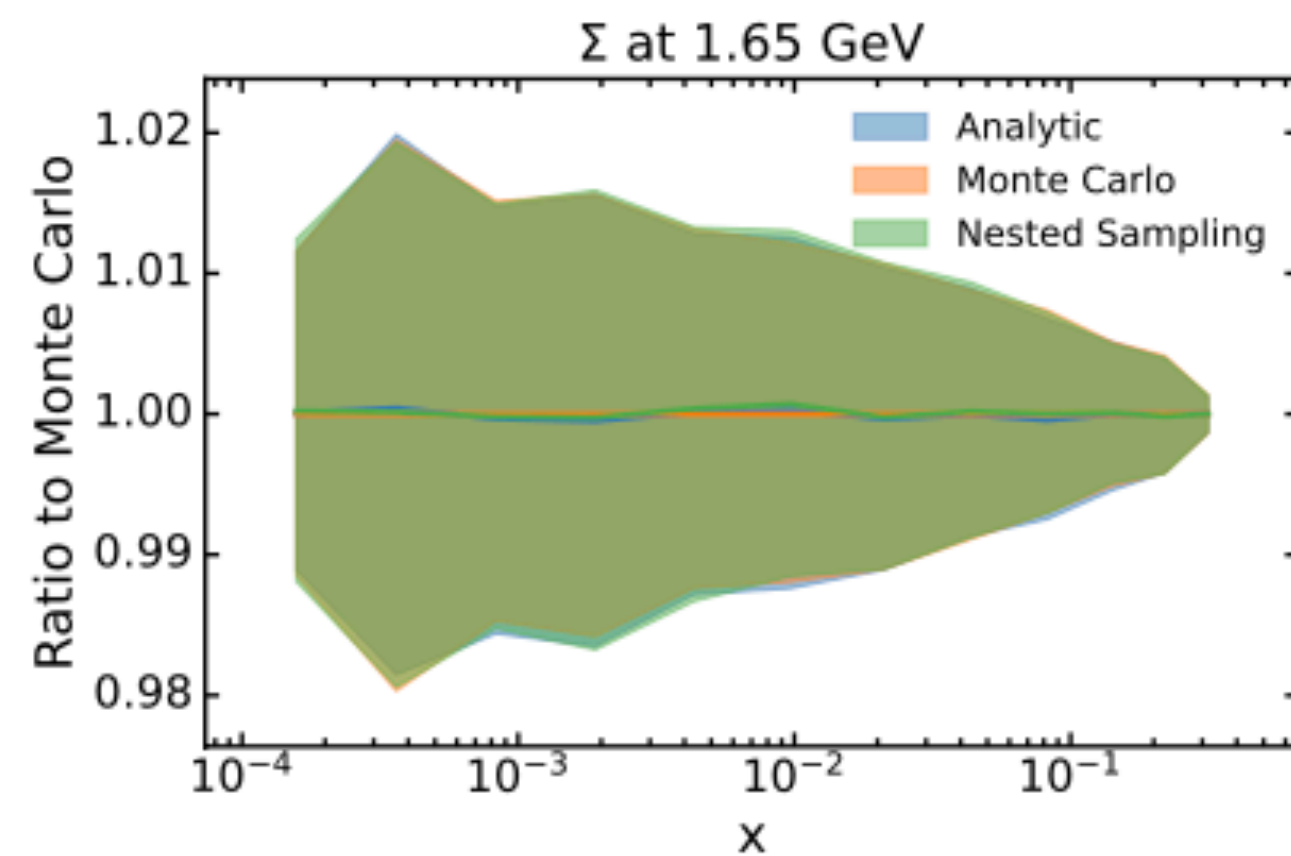
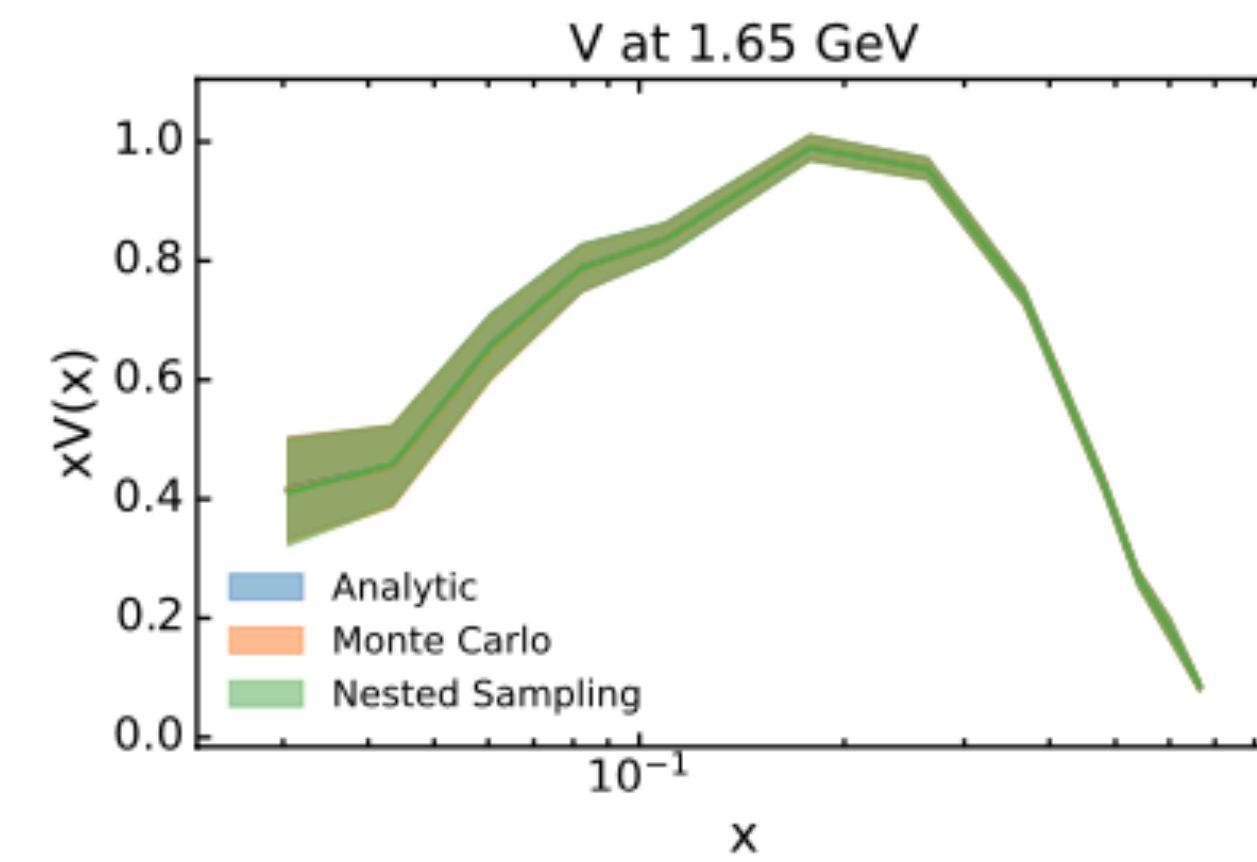
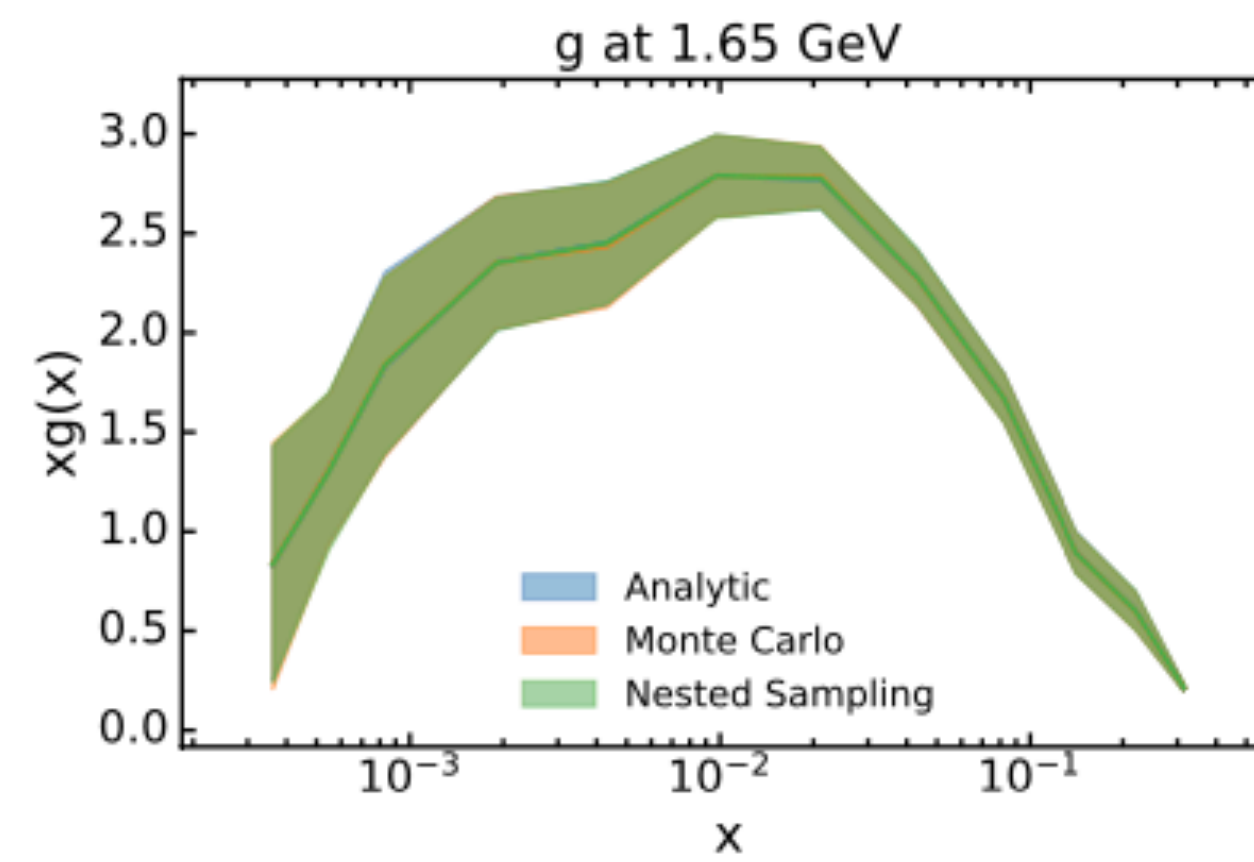
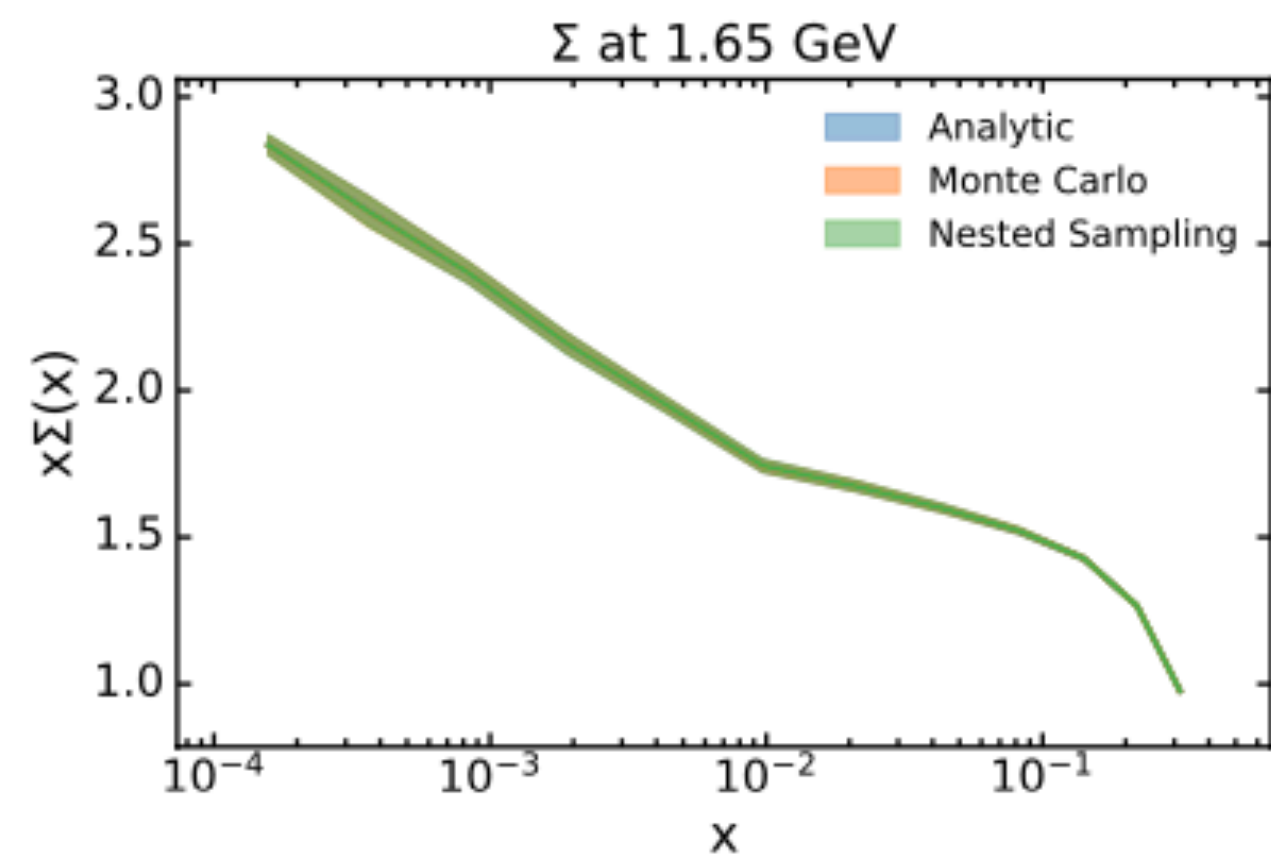
Level 1 Closure test:
data = theory + noise
(noise sampled from
covariance matrix)

Linear Interpolation!



Applications in HEP

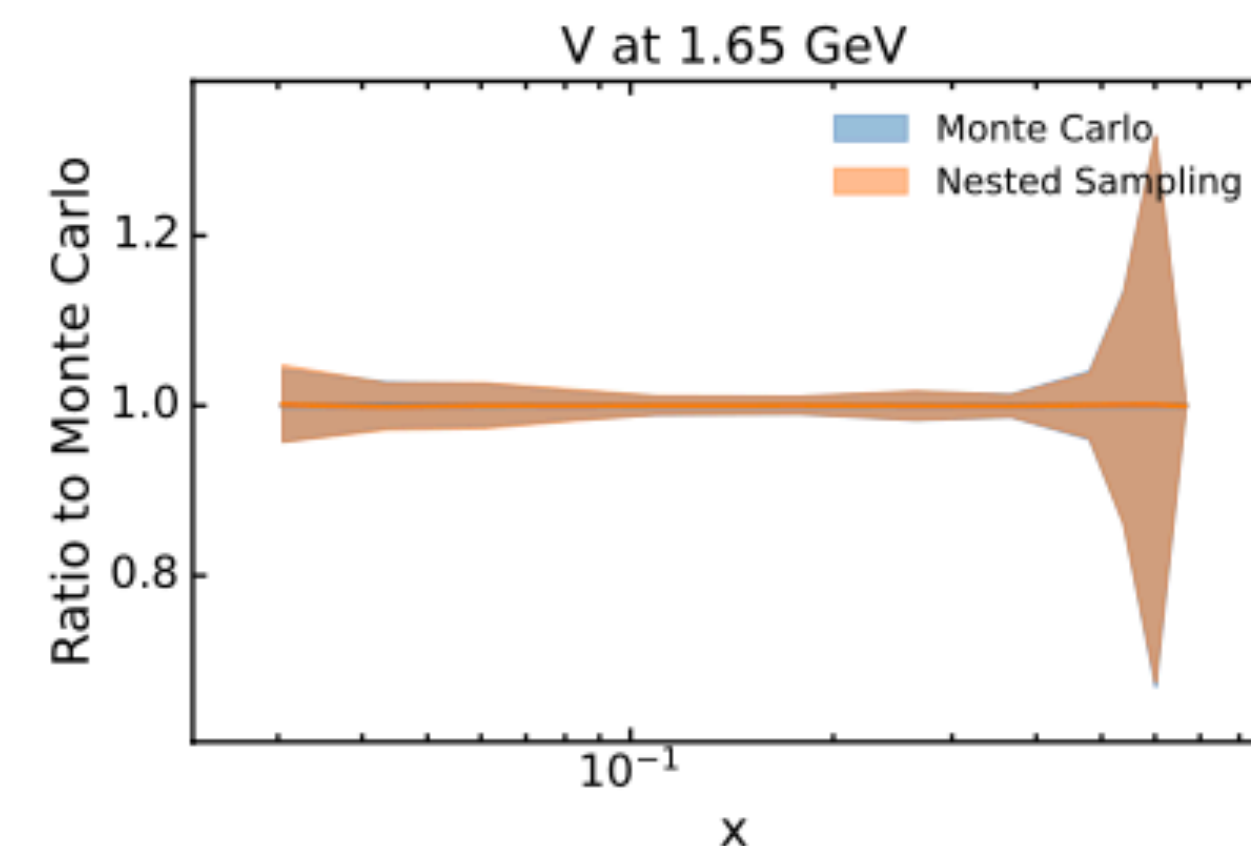
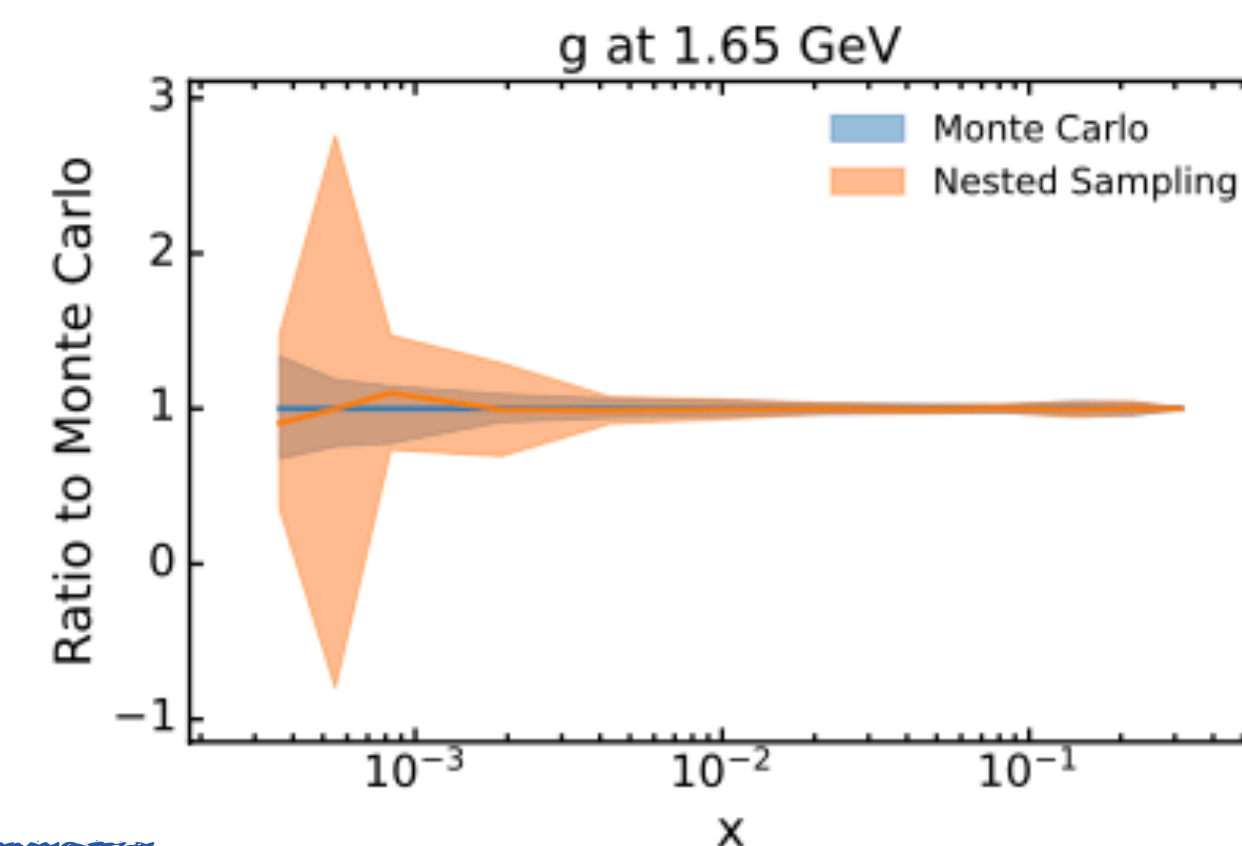
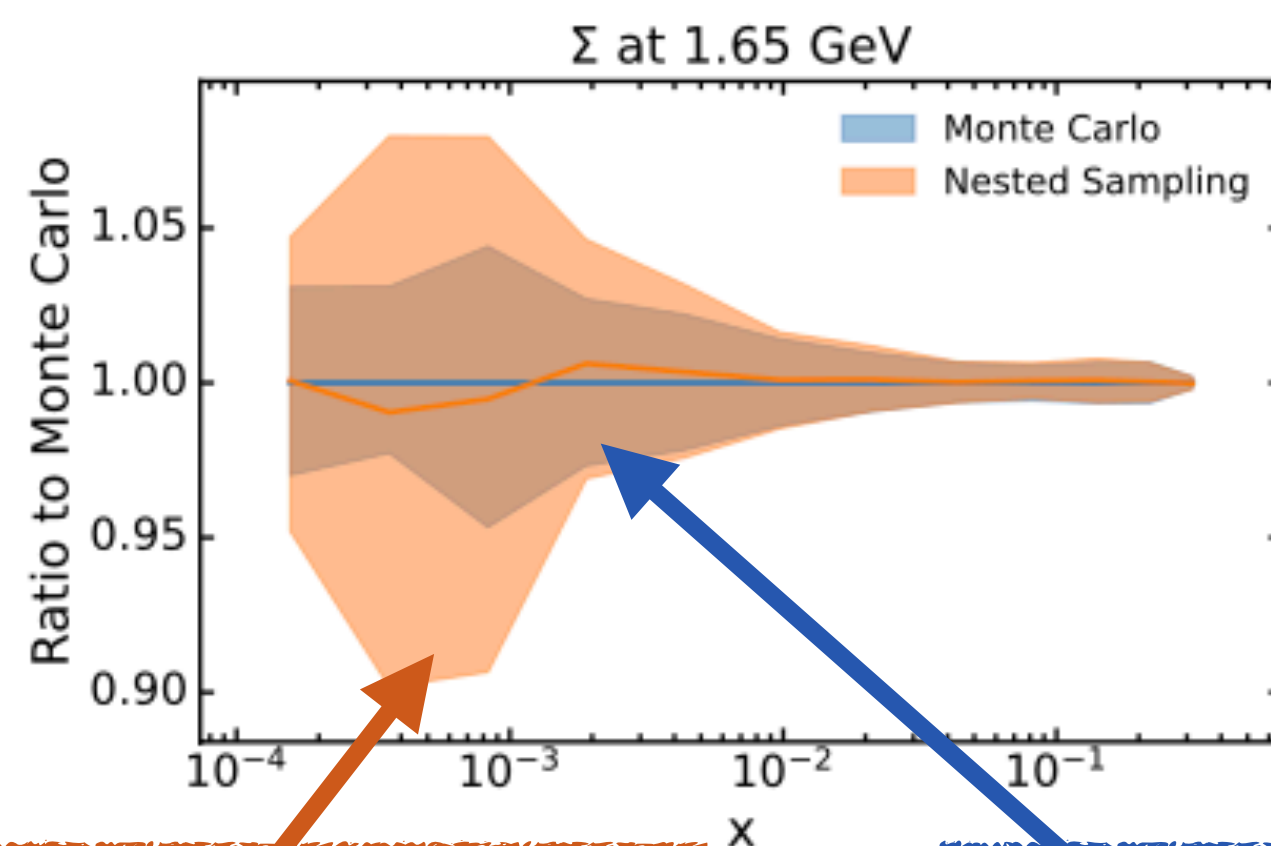
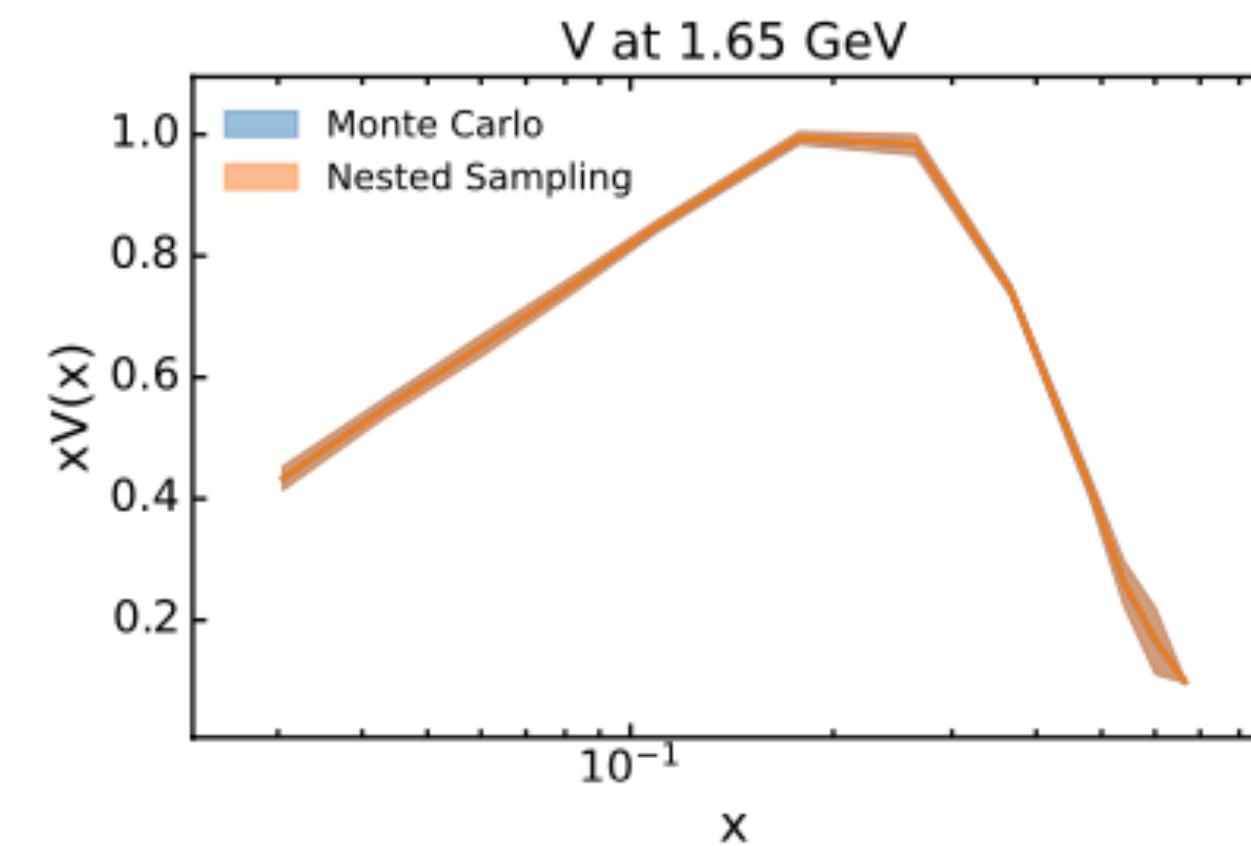
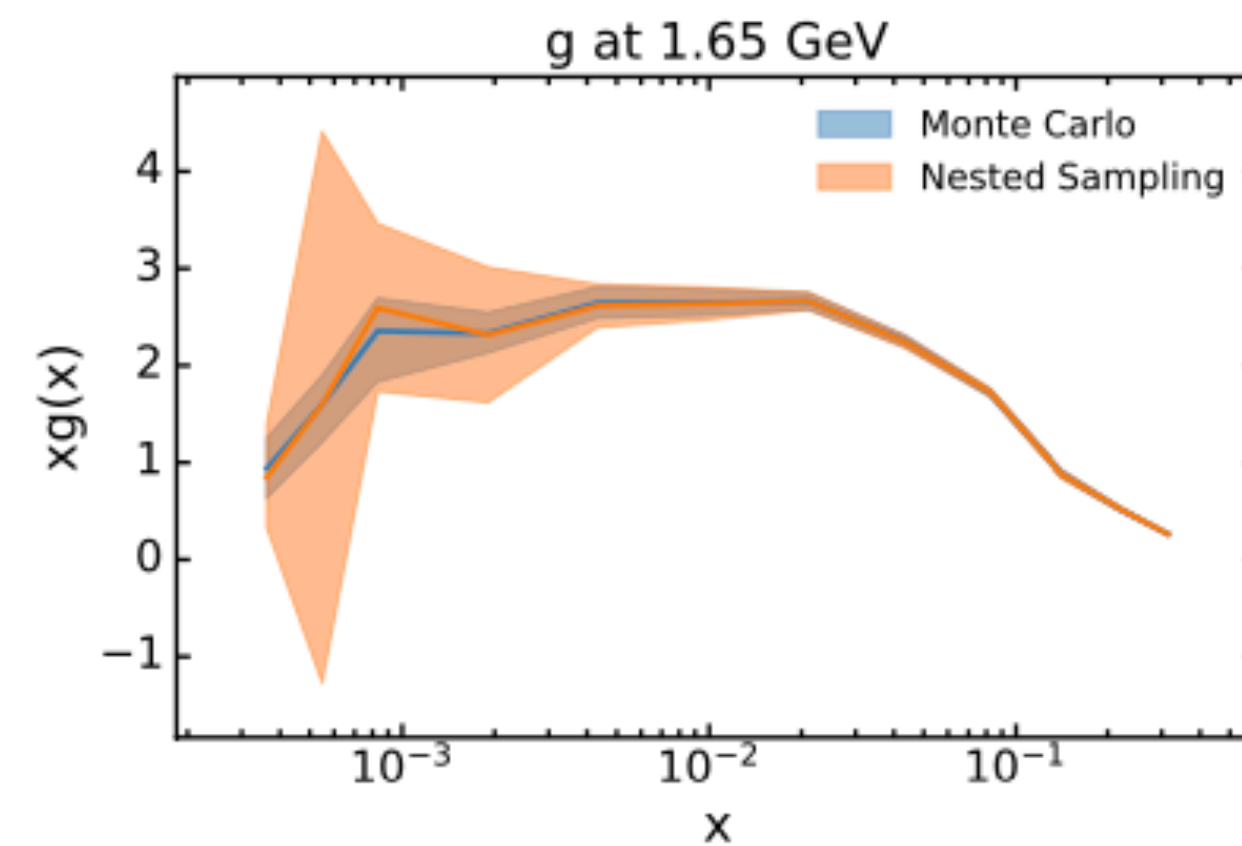
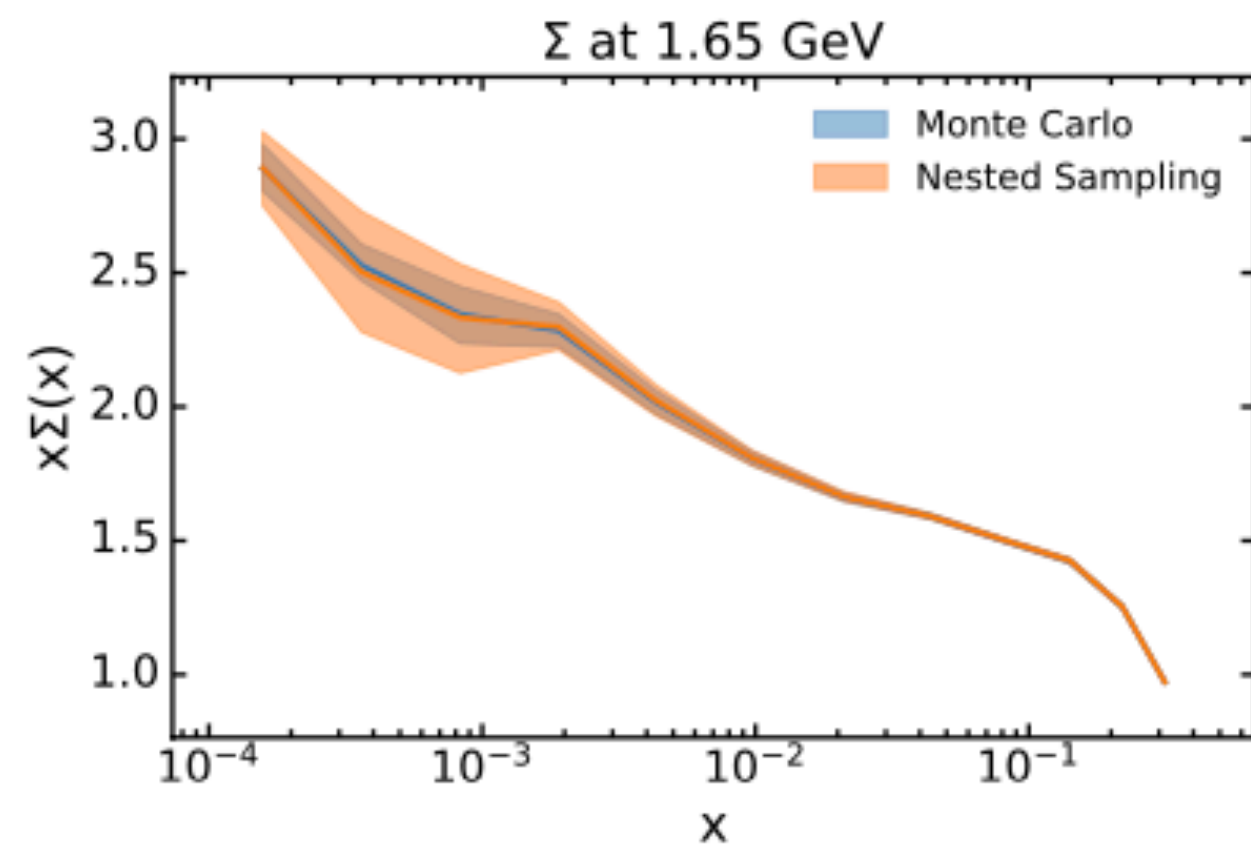
PDF fits: DIS benchmark



~ 3000
datapoints

Applications in HEP

PDF fits: Hadronic-only fit



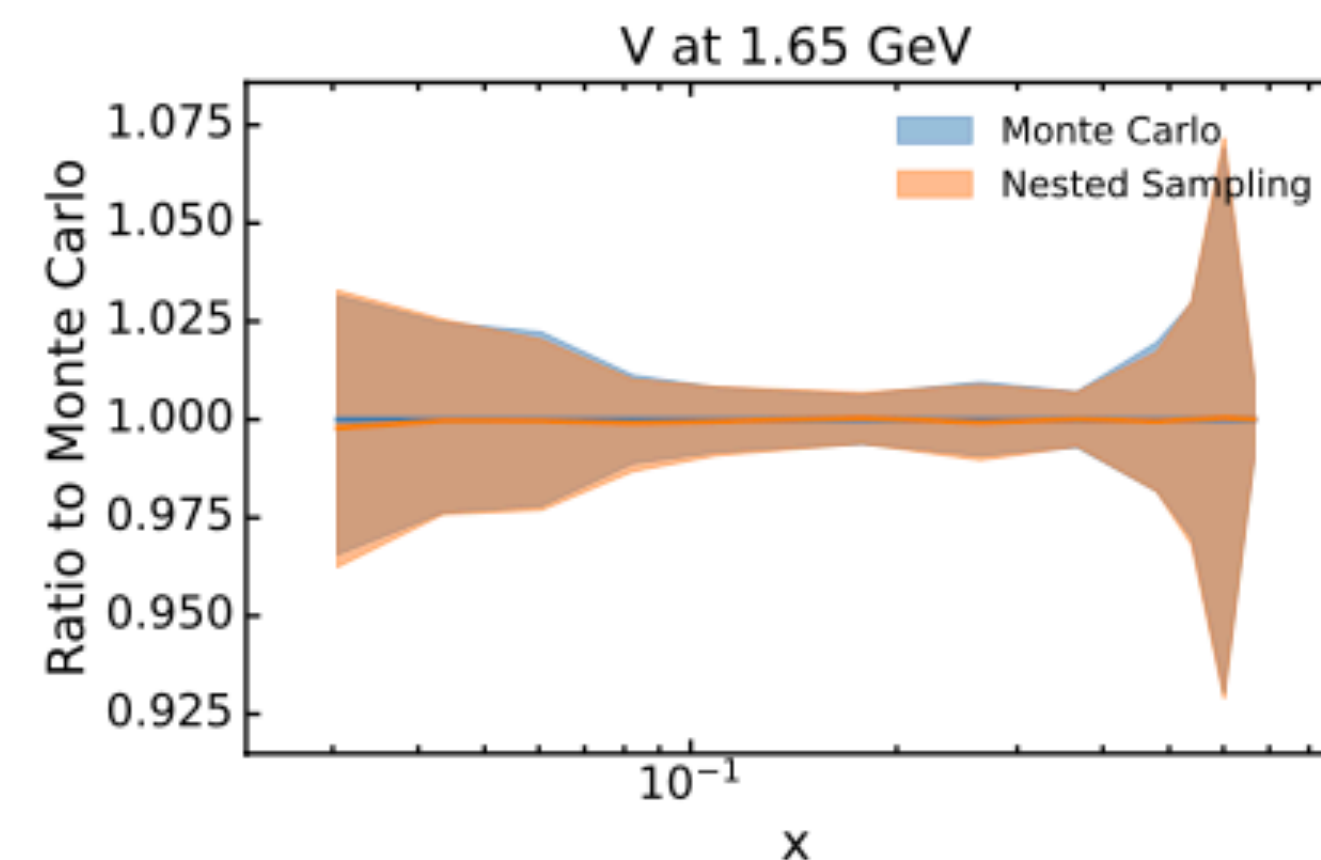
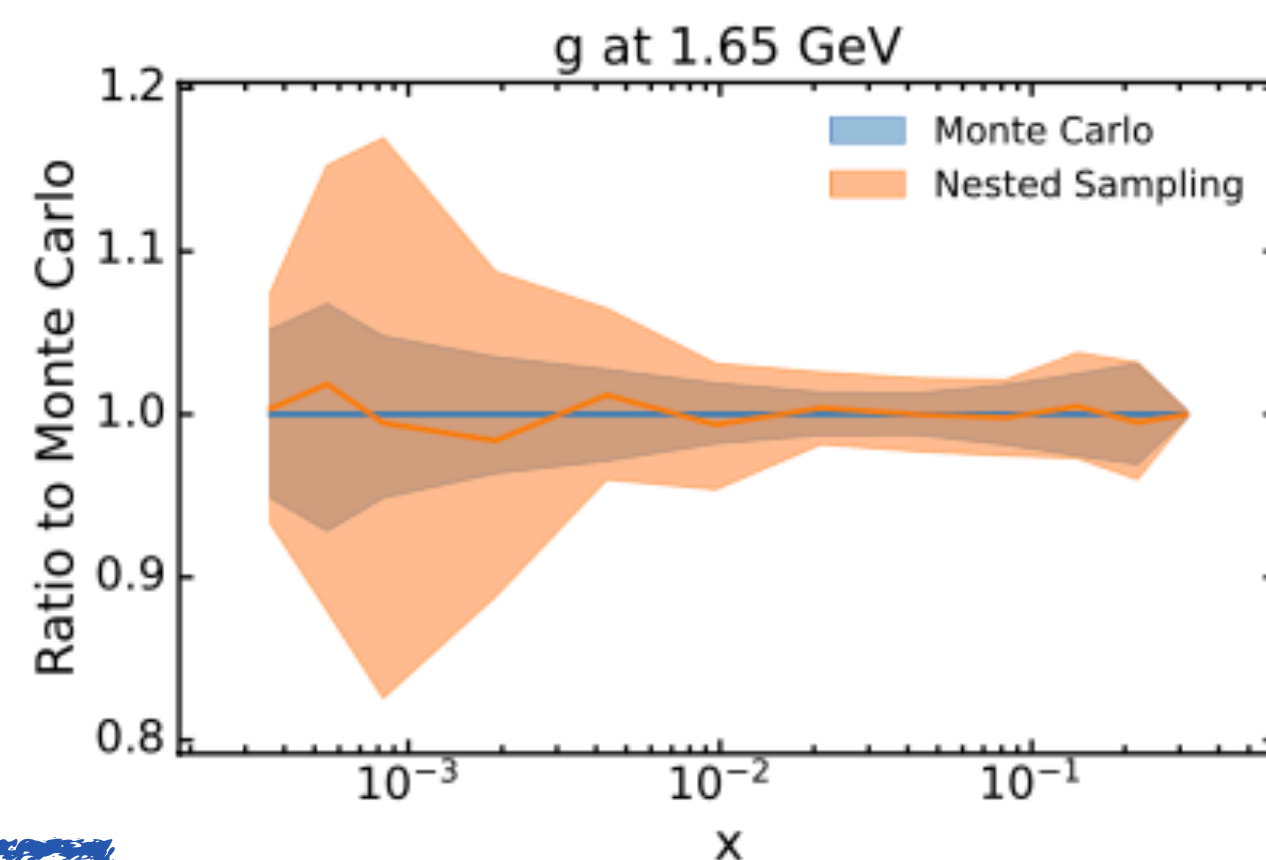
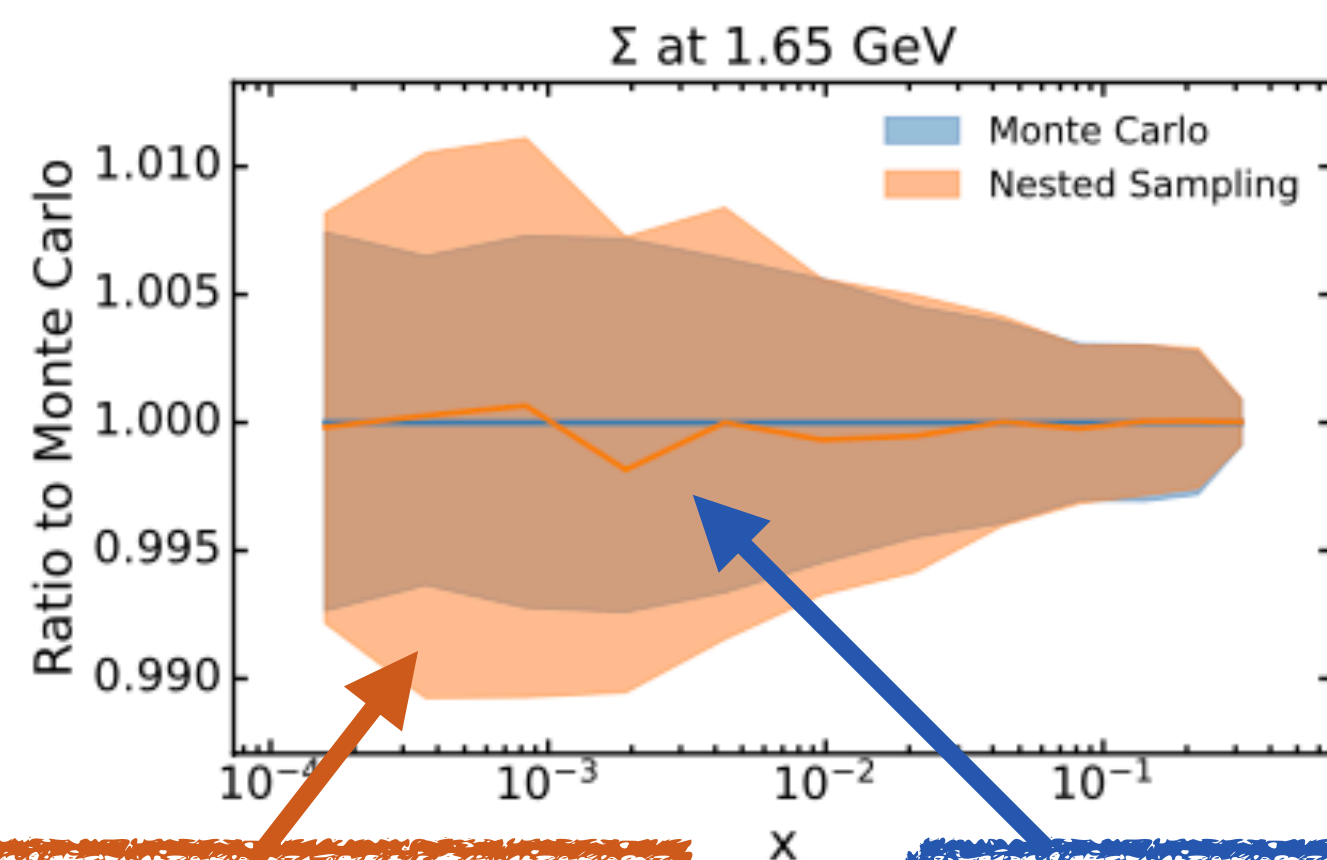
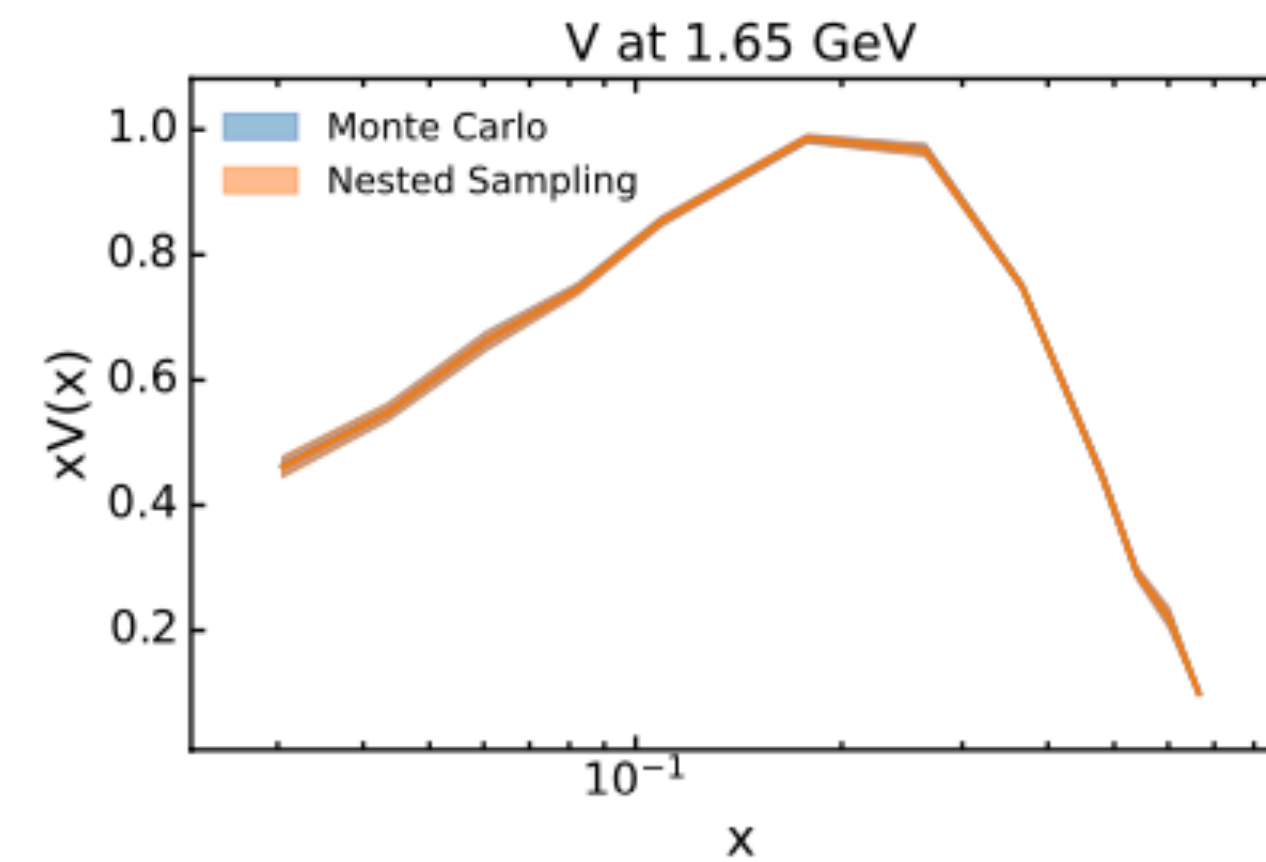
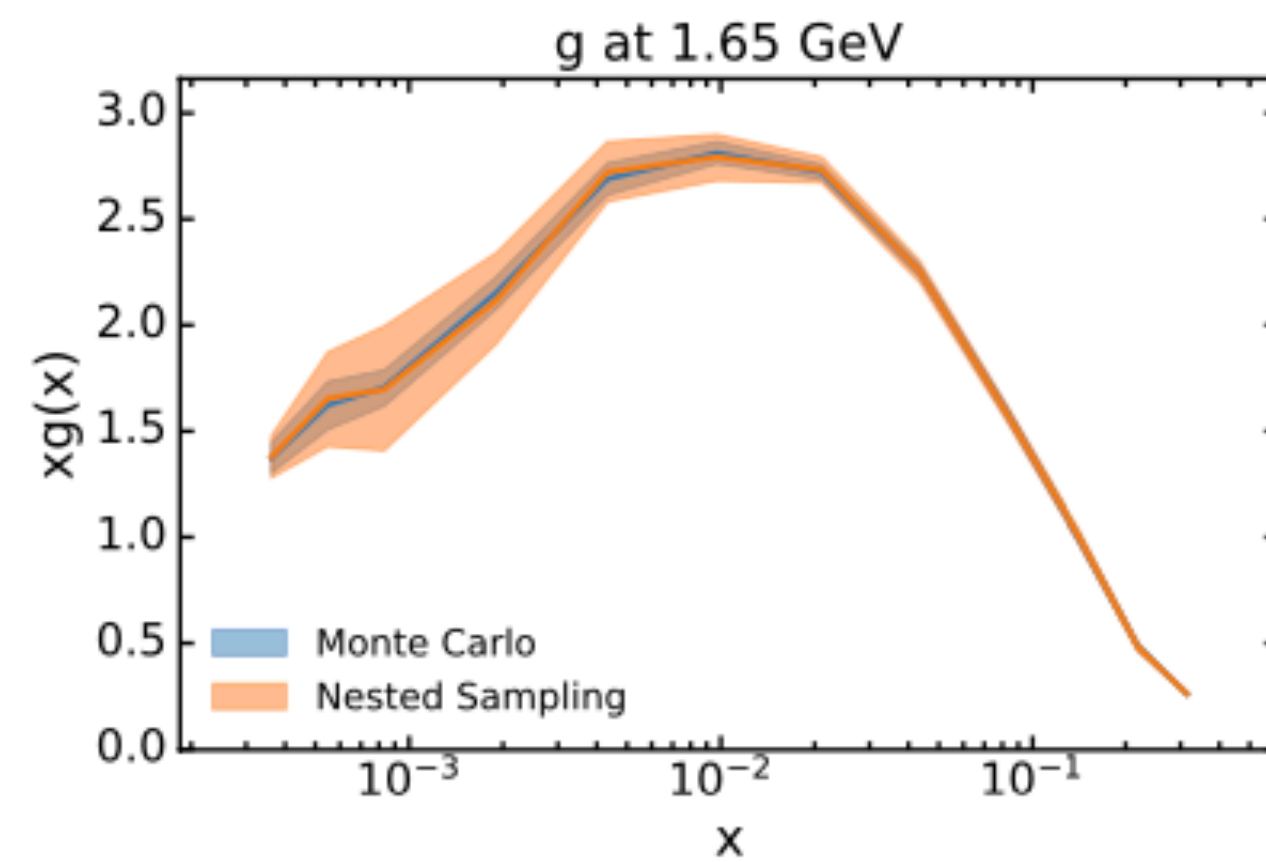
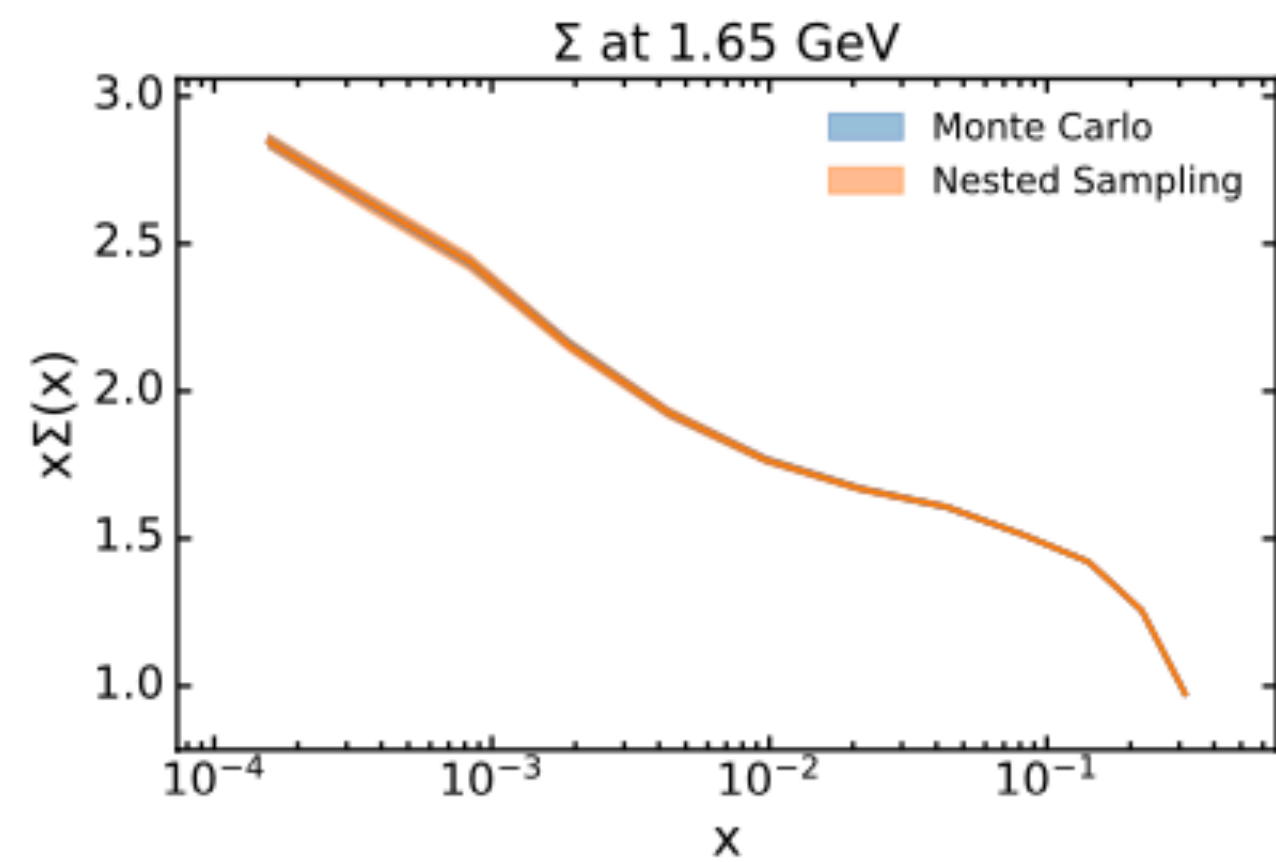
~ 1000
datapoints

Nested Sampling

Monte Carlo

Applications in HEP

PDF fits: Global fit



~ 4000
datapoints

Nested Sampling

Monte Carlo

The word "Summary" is centered between two horizontal dotted lines. The lines are composed of small, evenly spaced teal dots.

Summary

Summary / Outlook

➔ **First rigorous mathematical formulation of the Monte Carlo replica method**

➔ **Compare Monte Carlo replica approach against Bayesian approach**

- Agreement for Linear models
- Examples for non linear models

➔ **Applications to phenomenologically relevant scenarios: SMEFT**

- SMEFT Fit of the top sector
- Bayesian and Monte Carlo replica method do not agree for quadratic fits

Summary / Outlook

→ Applications to phenomenologically relevant scenarios: PDF fits

- Truly linear parameterisation of PDF
- DIS benchmark: Bayesian and Monte Carlo agree
- For purely hadronic and global fits disagreement is observed

→ Outlook

- Understanding potential limitations of uncertainty quantification methods is really important for the coming years and this sort of study is the starting point
- Repeat exercise with other fitting methodologies (such as Hessian with a tolerance)



Backup



Parametrical Bootstrap

Given data $X_1, \dots, X_N \sim \mathbb{P}$

And a statistic $\theta_N = \theta_N(X_1, \dots, X_N)$ that depends on it

make parametrical assumption on distribution $\mathbb{P} = \mathbb{P}_\theta$ and find parameter(s) θ using (e.g.) MLE

use \mathbb{P}_θ to generate bootstrap sample $\{X_1^{*,1}, \dots, X_N^{*,1}\}$ and compute the bootstrapped statistic $\theta_N^{*,1} = \theta_N^{*,1}(X_1^{*,1}, \dots, X_N^{*,1})$

repeat procedure B times so as to get B bootstrapped estimators $\{\theta_N^{*,1}, \dots, \theta_N^{*,B}\}$ and compute mean, variance, and quantiles on these.

Monte Carlo Posterior

$\mathbf{c}_p(\mathbf{d}_p)$ Is a random function of \mathbf{d}_p

$$P_{MC}(\mathbf{c}) \propto \int d^{N_{\text{dat}}} \mathbf{d}_p \delta(\mathbf{c} - \mathbf{c}_p(\mathbf{d}_p)) \exp\left(-\frac{1}{2}(\mathbf{d}_p - \mathbf{d})^T \Sigma^{-1}(\mathbf{d}_p - \mathbf{d})\right)$$

Jacobian factor

Change of coordinates to absorb delta function: $\mathbf{d}_p \rightarrow (\mathbf{c}_p, \boldsymbol{\lambda})$

$$P_{MC}(\mathbf{c}) \propto \exp\left(-\frac{1}{2}\chi_d^2(\mathbf{c})\right) \int d^{N_{\text{dat}} - N_{\text{param}}} \boldsymbol{\lambda} \left| \det \left(\frac{\partial \mathbf{t}}{\partial \mathbf{c}} + \frac{\partial(\Sigma M \boldsymbol{\lambda})}{\partial \mathbf{c}} \bigg|_{\Sigma M(\mathbf{c})} \right) \right|$$

Same as for Bayesian posterior $\times \exp\left(-\frac{1}{2}\boldsymbol{\lambda}^T M(\mathbf{c})^T \Sigma M(\mathbf{c}) \boldsymbol{\lambda} + \boldsymbol{\lambda}^T M(\mathbf{c})^T (\mathbf{d} - \mathbf{t}(\mathbf{c}))\right)$

M : basis for the kernel of $\left(\frac{\partial \mathbf{t}(\mathbf{c})}{\partial \mathbf{c}}\right)^T (\mathbf{c}_p(\mathbf{d}_p))$

Monte Carlo Posterior

Linear Toy Model

one datapoint , one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c, t_{\text{lin}} \neq 0$$

$$c_p(d_p) = \operatorname{argmin}_c \left(\frac{(t(c) - d_p)^2}{\sigma^2} \right) = \frac{d_p - t_0}{t_{\text{lin}}}$$

Same as for Bayesian posterior



$$P_{\text{MC}}(c) = \int dd_p \delta(c - c_p(d_p)) \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2} \frac{(d_0 - d_p)^2}{\sigma^2}\right) = \frac{t_{\text{lin}}}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2} \frac{(d_0 - t(c))^2}{\sigma^2}\right)$$

MC and Bayesian posterior agree in the linear case (General)

Monte Carlo Posterior

Quadratic Toy Model

one datapoint, one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c + t_{\text{quad}}c^2, \quad t_{\text{quad}} > 0$$

$$c_p(d_p) = \operatorname{argmin}_c \left(\frac{(t(c) - d_p)^2}{\sigma^2} \right) \text{ can be found analytically}$$

$$P_{\text{MC}}(c) \propto \delta \left(c + \frac{t_{\text{lin}}}{2t_{\text{quad}}} \right) \int_{-\infty}^{t_{\text{min}}} dd_p \exp \left(-\frac{1}{2} \frac{(d_0 - d_p)^2}{\sigma^2} \right) + 2 |t_{\text{lin}} + 2ct_{\text{quad}}| \exp \left(-\frac{1}{2} \frac{(d_0 - t(c))^2}{\sigma^2} \right)$$



Independent on d_p : $\frac{\partial t(c)}{\partial c}$ has not full rank

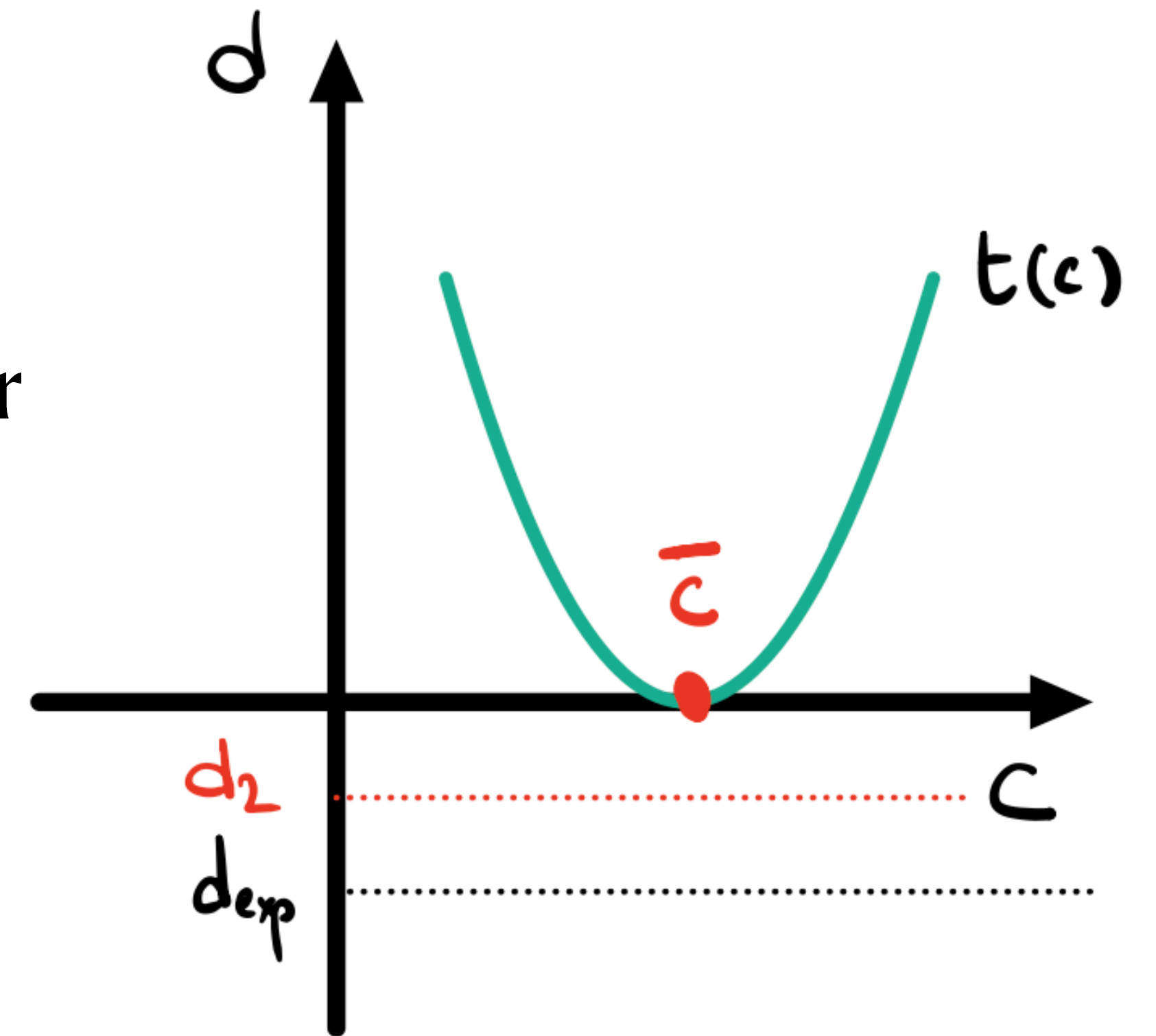
2 roots “Determinant” factor

Monte Carlo Posterior

Quadratic Model

Let's consider one datapoint, one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c + t_{\text{quad}}c^2, \quad t_{\text{quad}} > 0$$



$$P_{\text{MC}}(c) \propto \delta\left(c + \frac{t_{\text{lin}}}{2t_{\text{quad}}}\right) \int_{-\infty}^{t_{\text{min}}} dd_p \exp\left(-\frac{1}{2} \frac{(d_0 - d_p)^2}{\sigma^2}\right) + 2 |t_{\text{lin}} + 2ct_{\text{quad}}| \exp\left(-\frac{1}{2} \frac{(d_0 - t(c))^2}{\sigma^2}\right)$$

Independent on d_p : $\frac{\partial t(c)}{\partial c}$ has not full rank

2 roots

“Determinant” factor

Monte Carlo Posterior

Quadratic Toy Model

one datapoint , one theory parameter

$$t(c) = t_0 + t_{\text{lin}}c + t_{\text{quad}}c^2, t_{\text{quad}} > 0$$

MC and Bayesian posterior do not agree in the quadratic case $P_{\text{MC}}(c) \neq P_B(c | d_0)$

Note: In general it is unclear whether MC method under- or over-estimates the Bayesian uncertainties. Interestingly both scenarios can happen

→ A numerical simulation is needed in order to assess the effect of the “determinant” factor

Nested Sampling

General Idea

- Monte Carlo algorithm for computing an integral over a model parameter space
- Nested Sampling provides both the posterior samples as well as the marginalised likelihood Z

Bayes Rule

$$P(\Theta | D) = \frac{L(D | \Theta)\pi(\Theta)}{Z}$$

Marginalised Likelihood

$$Z = \int L(D | \Theta)\pi(\Theta)d\Theta$$

Nested Sampling

Algorithm

1. **Initialisation**: sample randomly from the prior N live points and compute the Likelihood at each point
2. **Shrinkage**: remove point with the lowest likelihood L_1
3. **Likelihood Restricted Prior Sampling**: sample new point from prior with Likelihood $> L_1$
4. **Iterate**

Iteration i reduces integration volume by a factor $\delta V_i \approx \left(1 - \frac{1}{N}\right)^i \frac{1}{N}$,

The integral Z is simply $Z \approx \sum_i \delta V_i \times L_i$

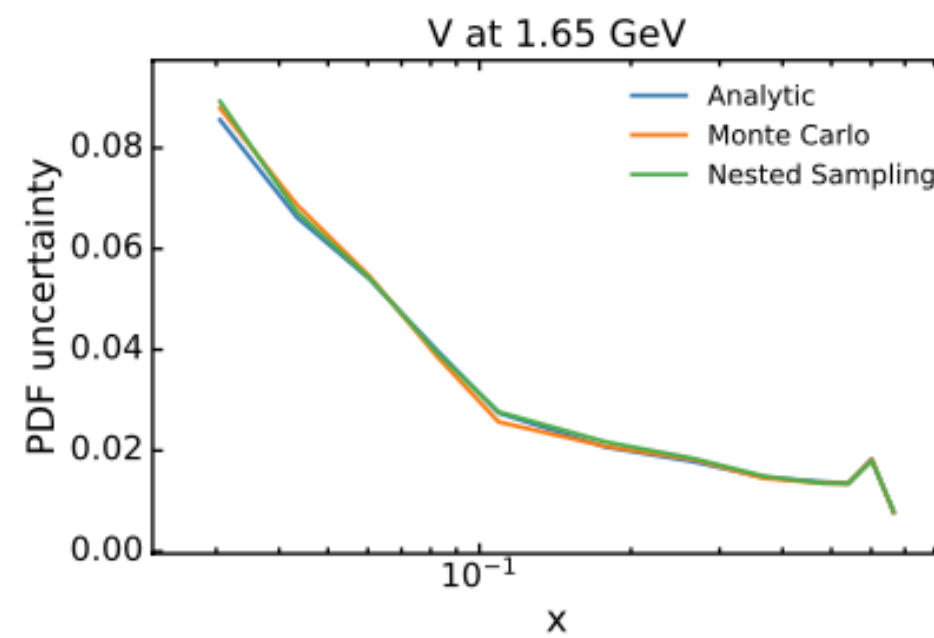
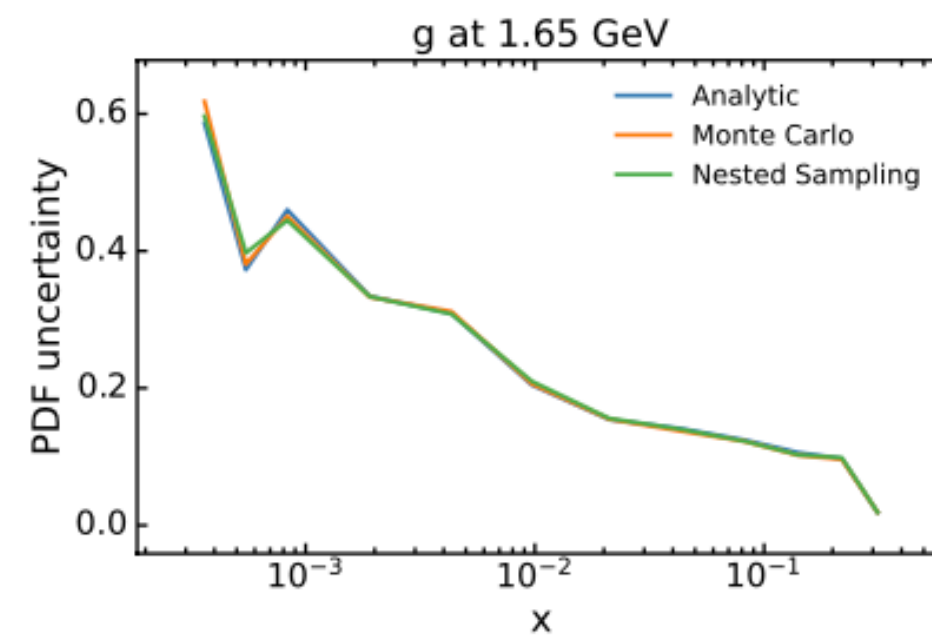
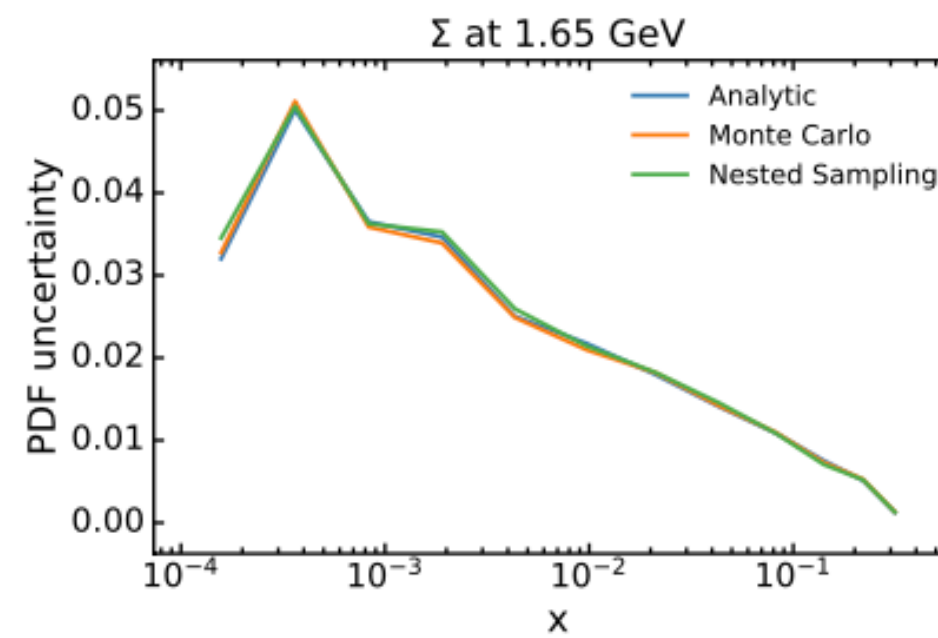
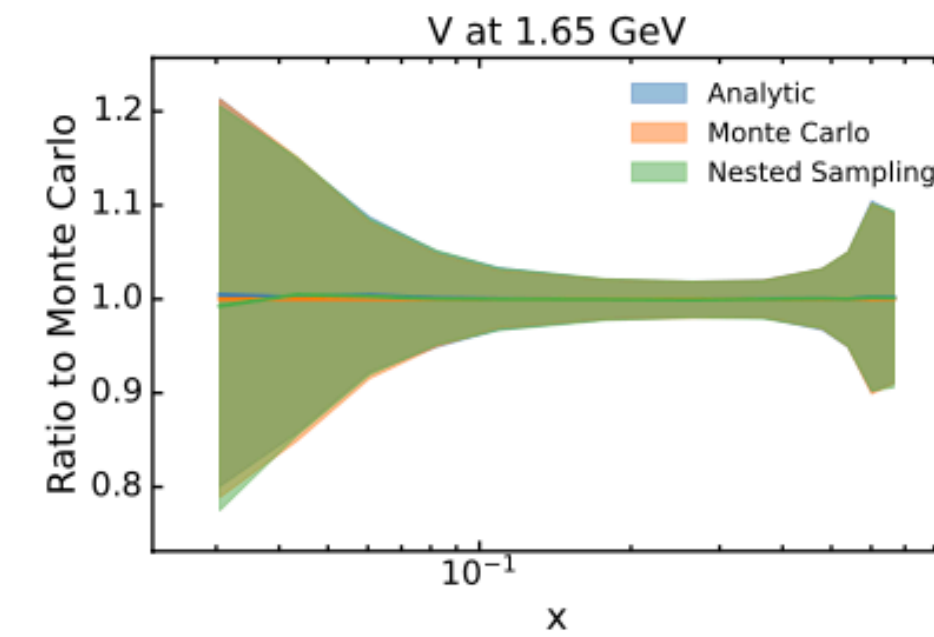
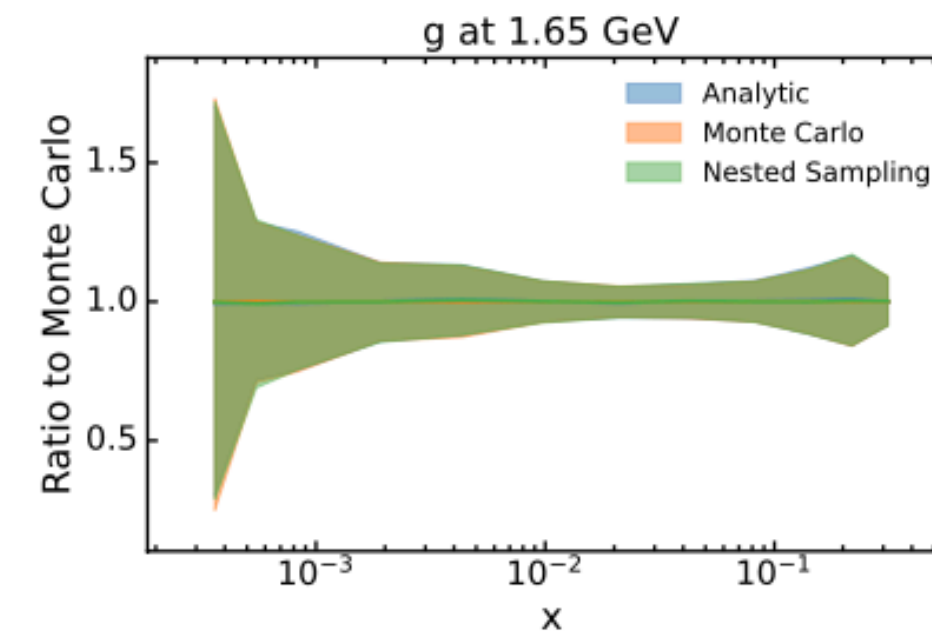
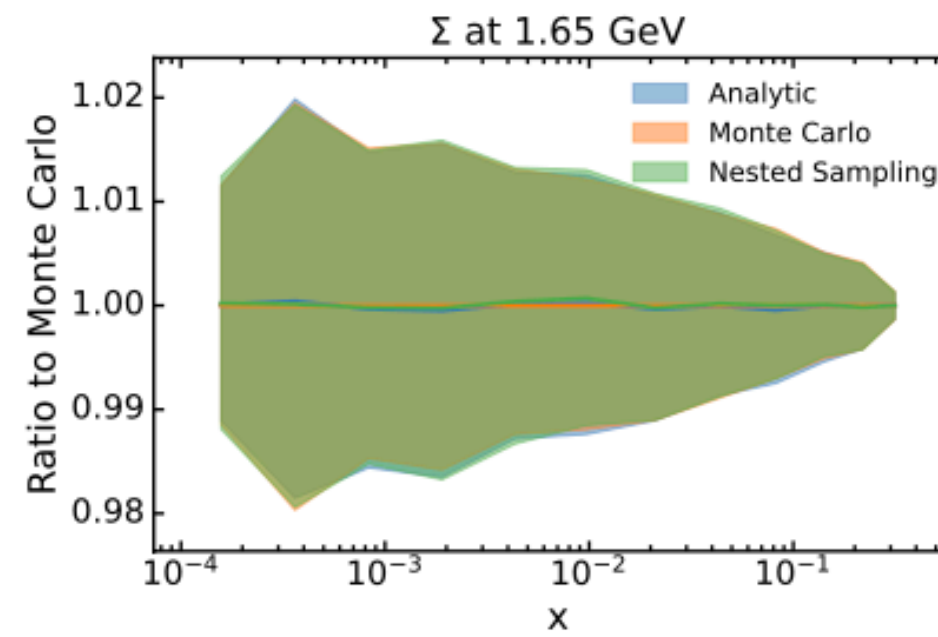
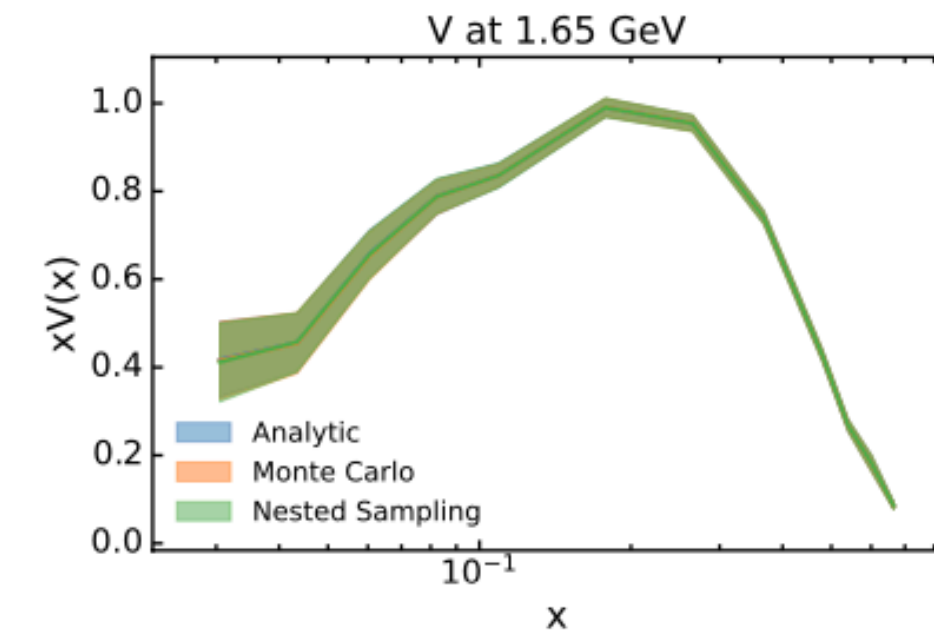
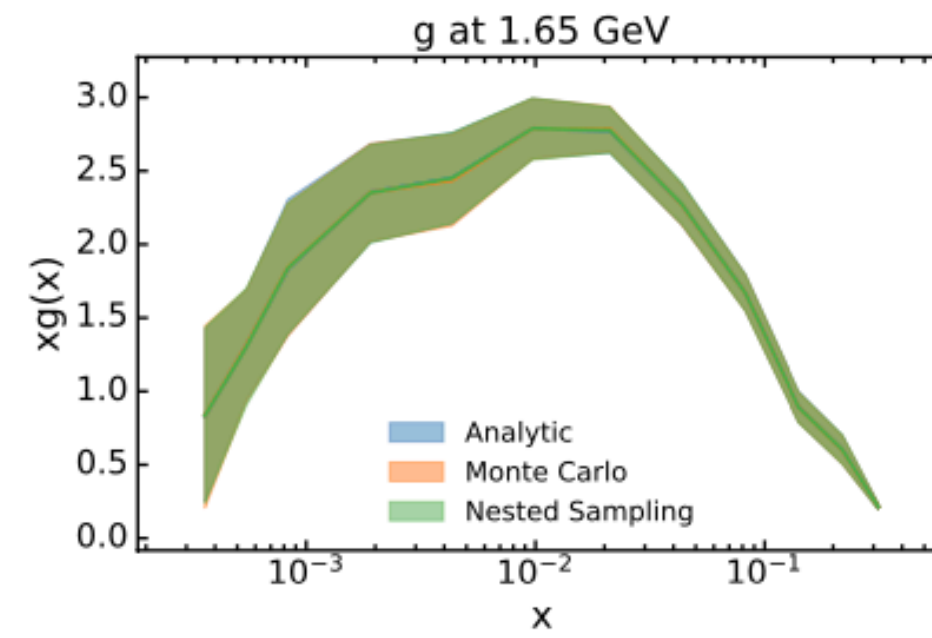
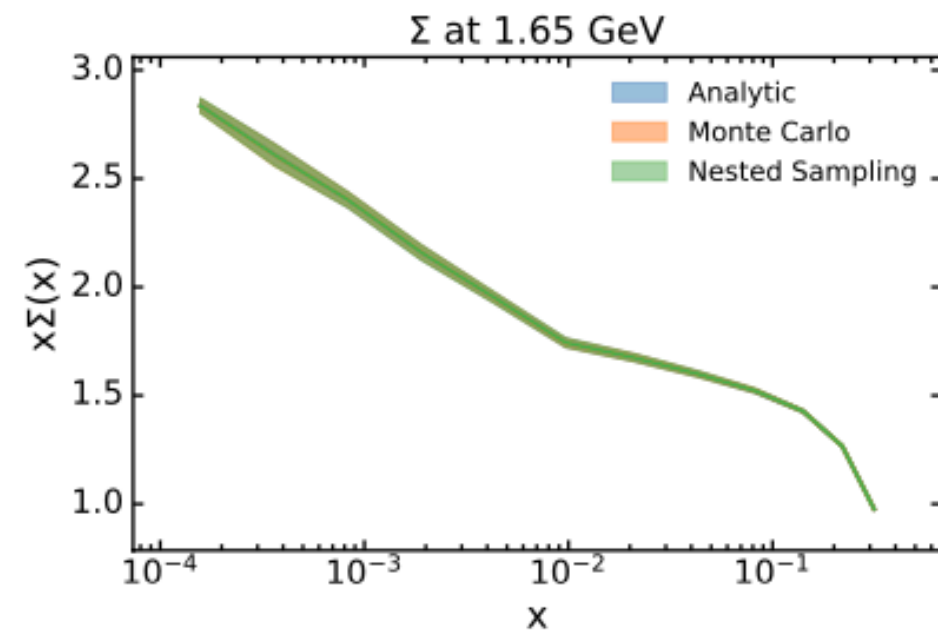
Termination: when $\delta V_i \times L_i$ contributions to Z are negligible

Nested Sampling

Summary

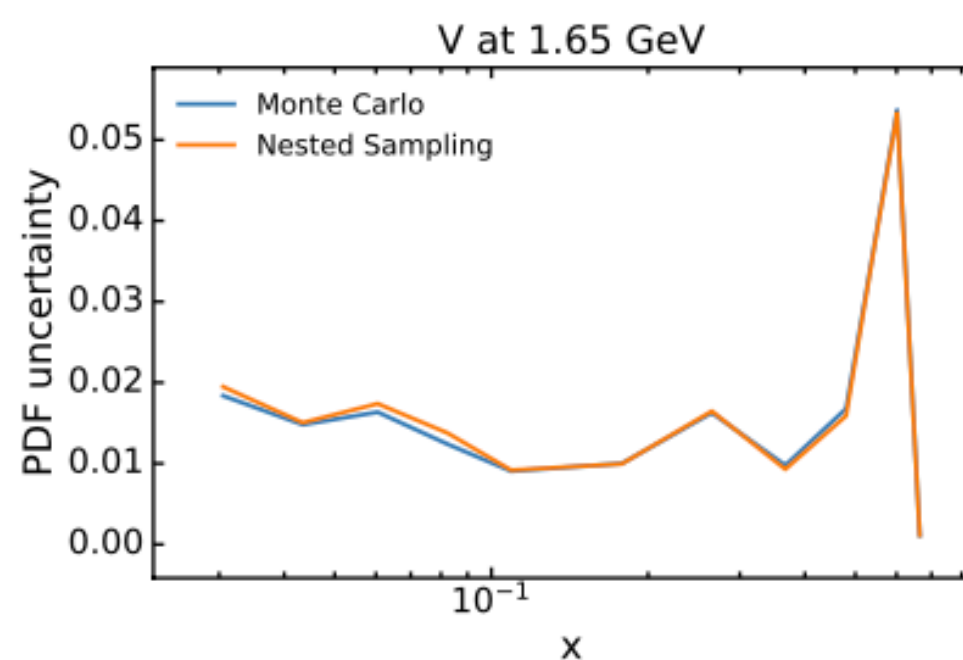
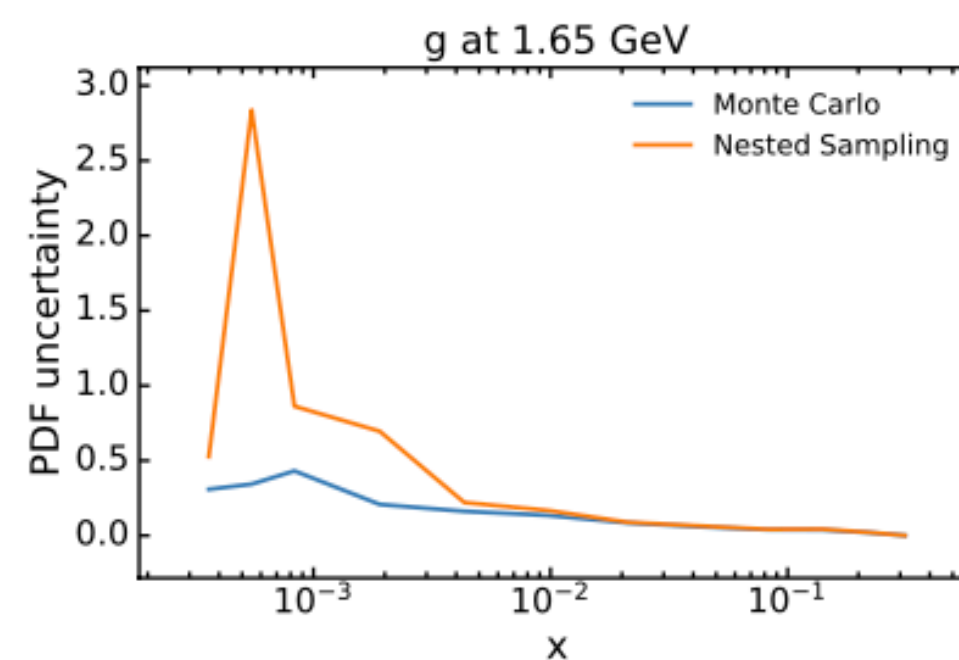
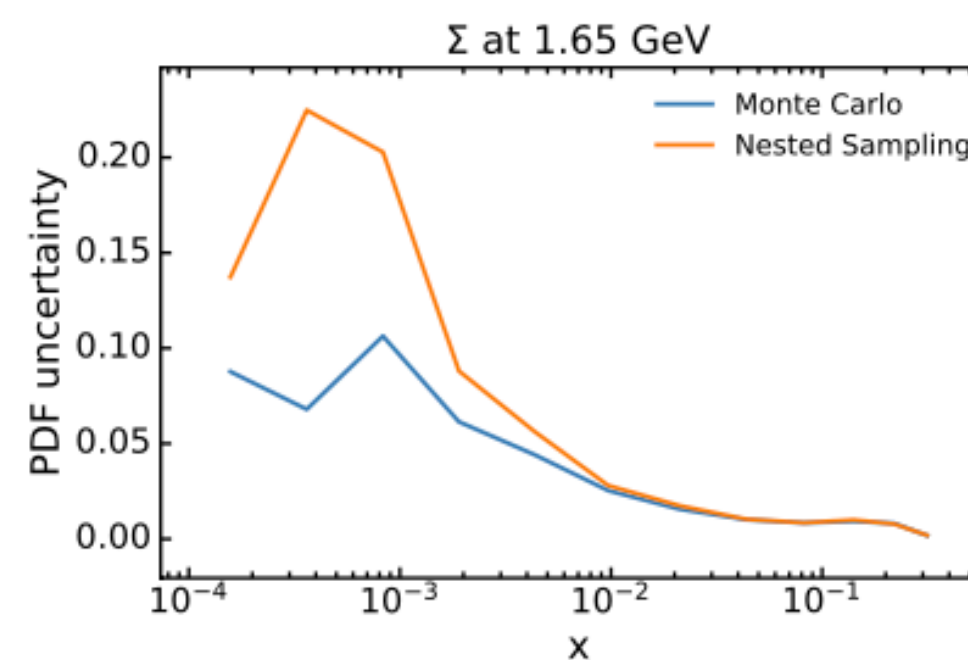
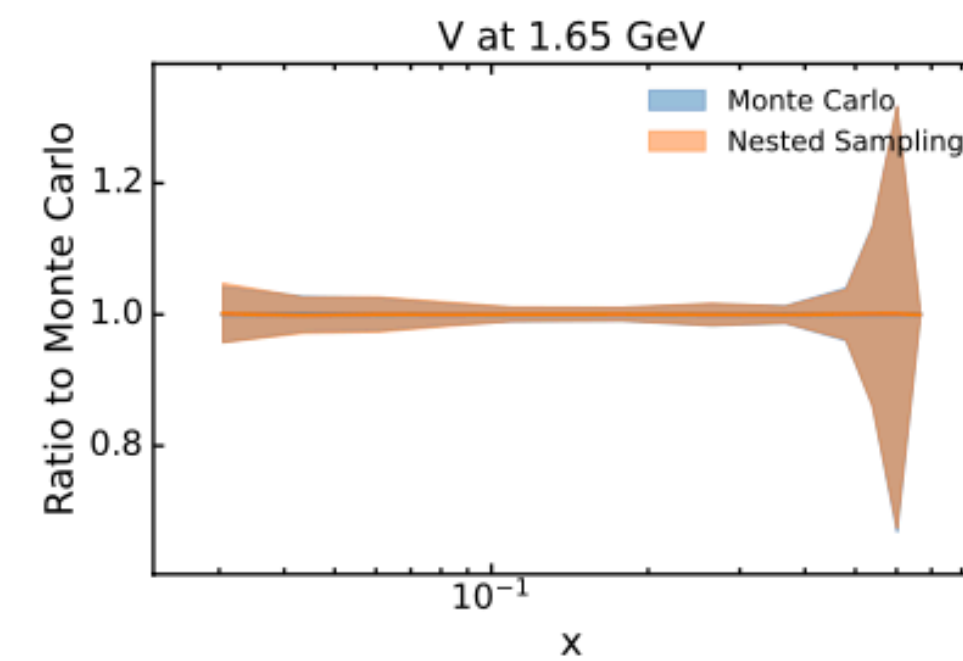
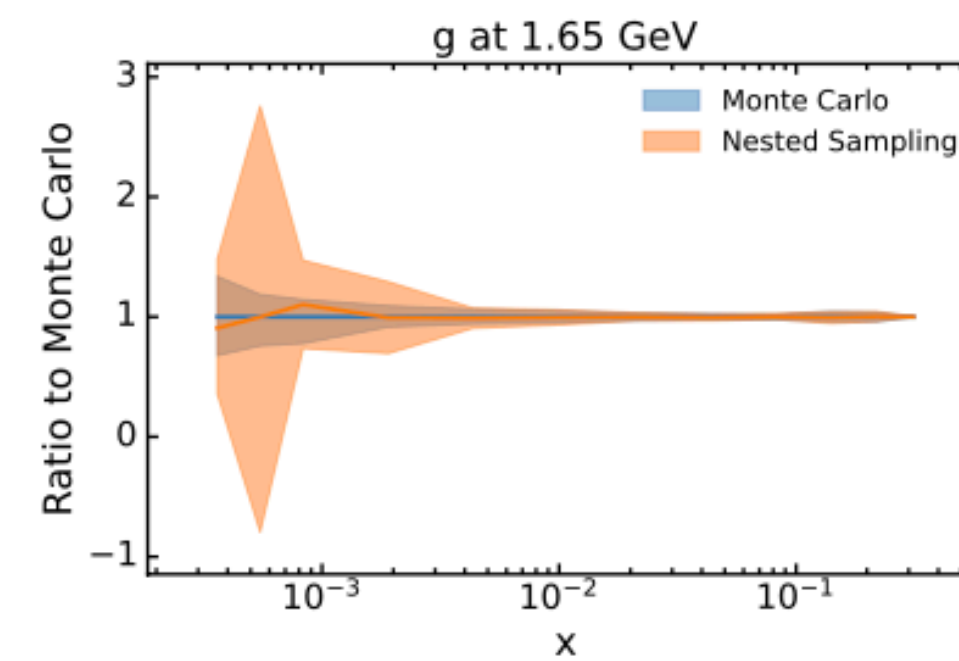
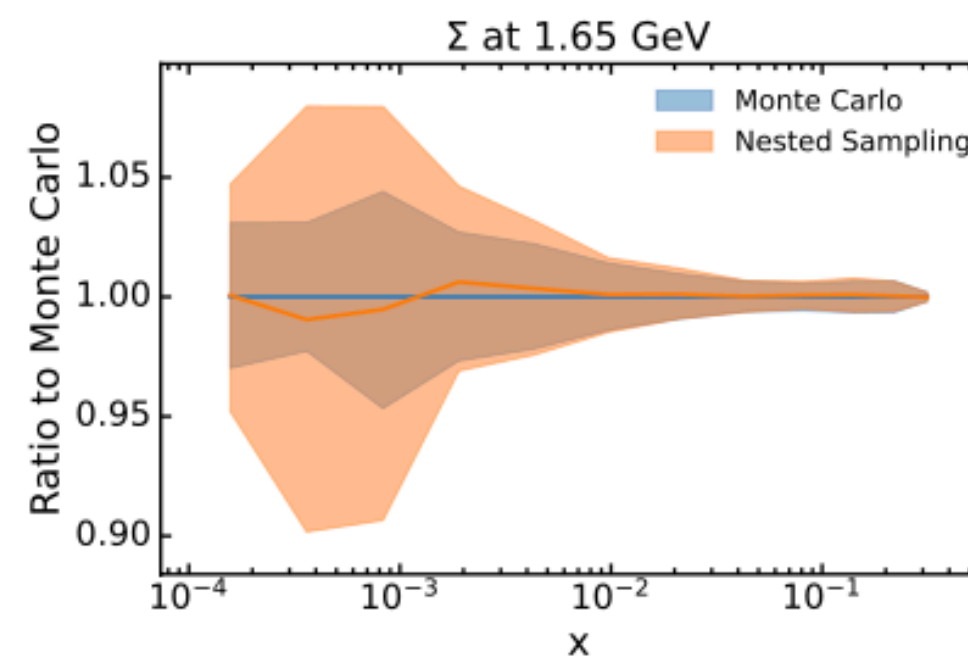
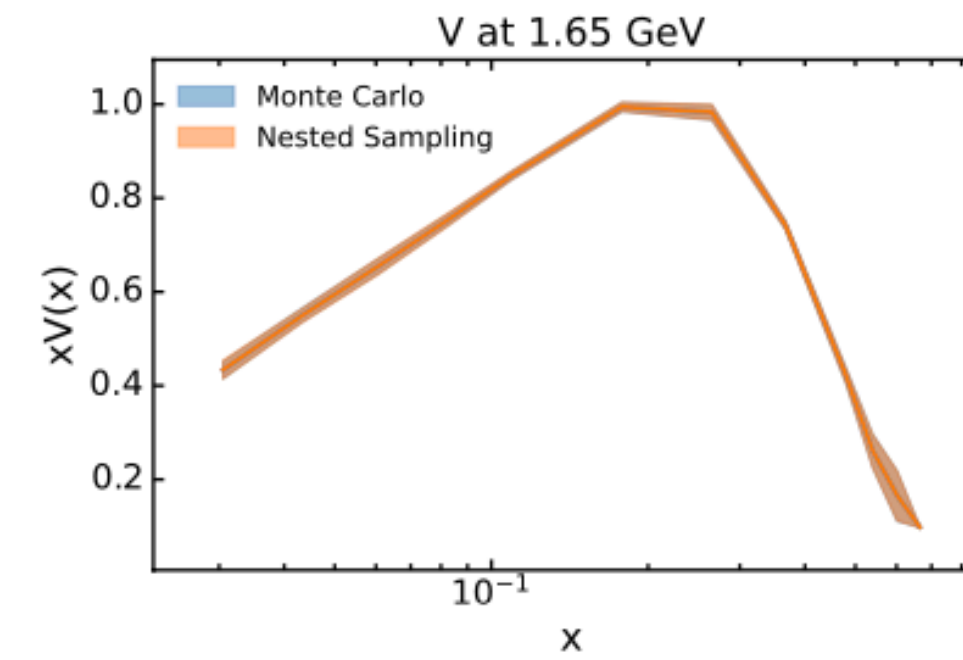
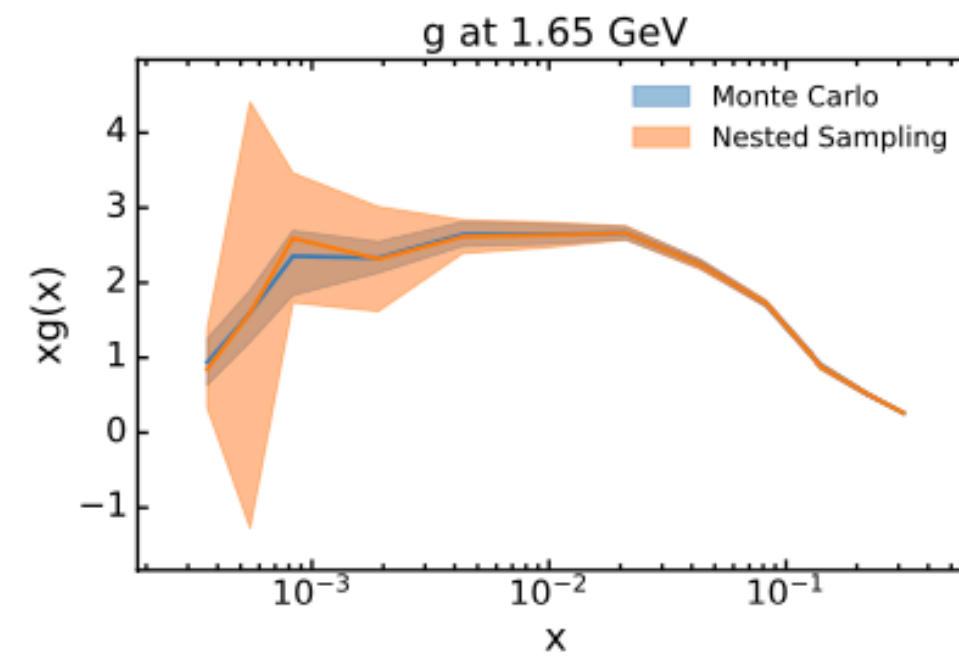
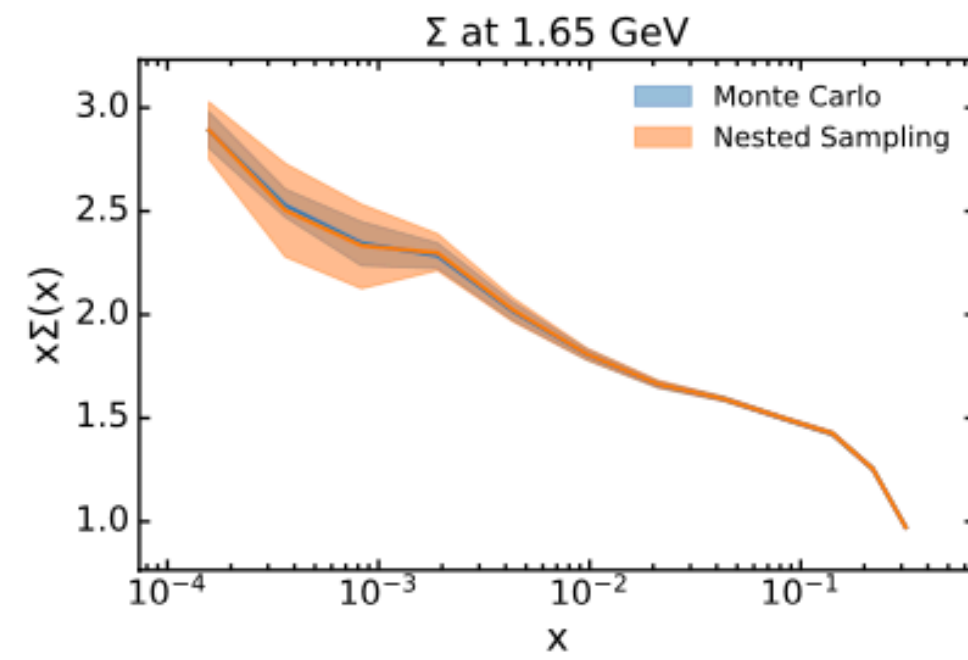
1. It explores the parameter space globally;
2. it handles multi-modal distributions well;
3. it initialises and terminates at a well defined point -> no supervision;
4. it provides both marginal likelihood and posterior samples;

DIS benchmark



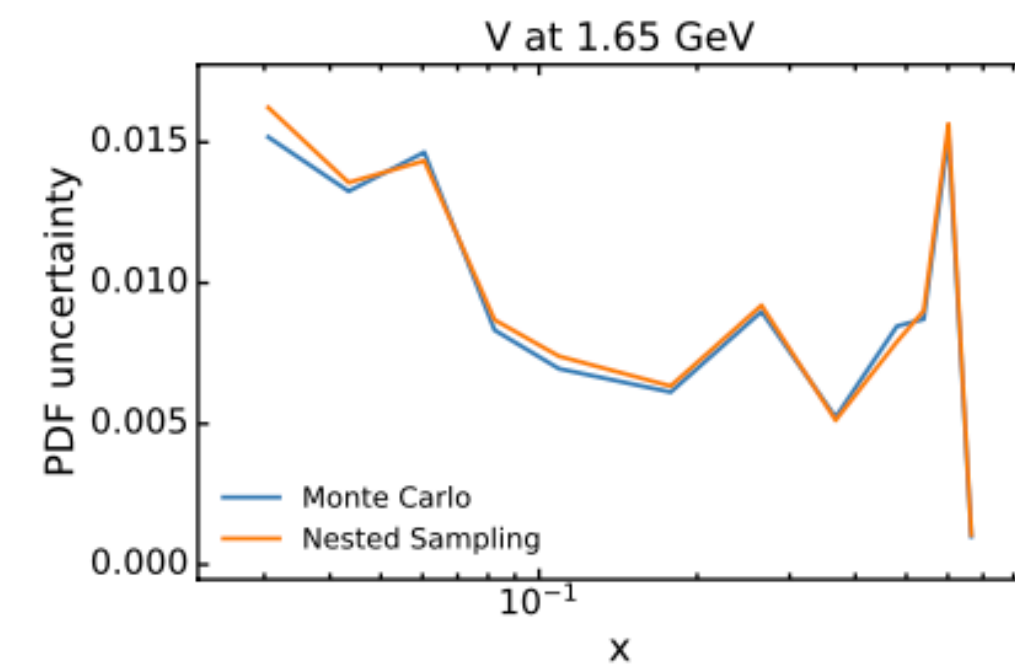
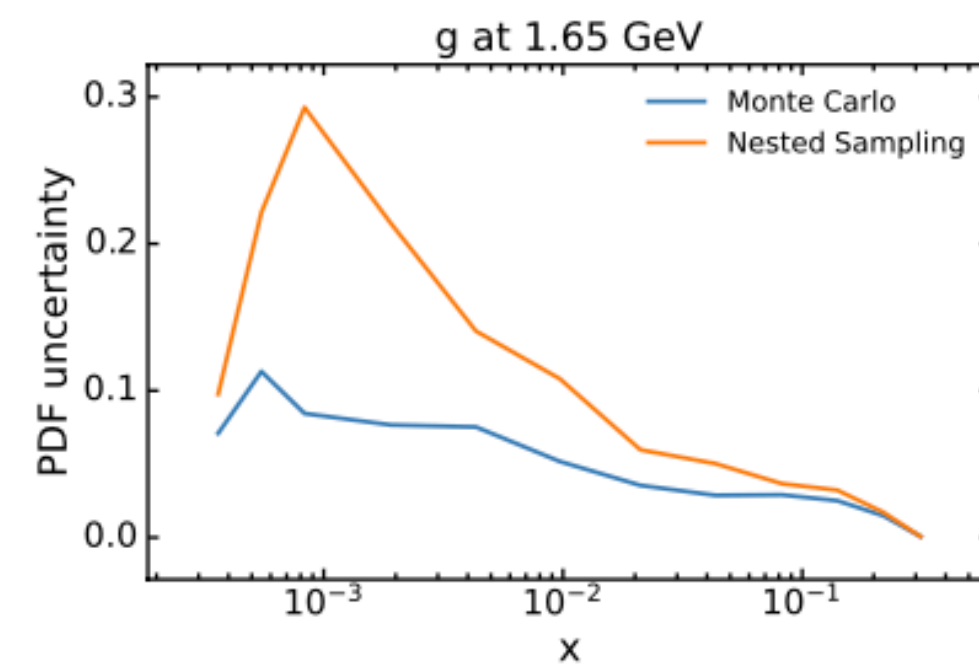
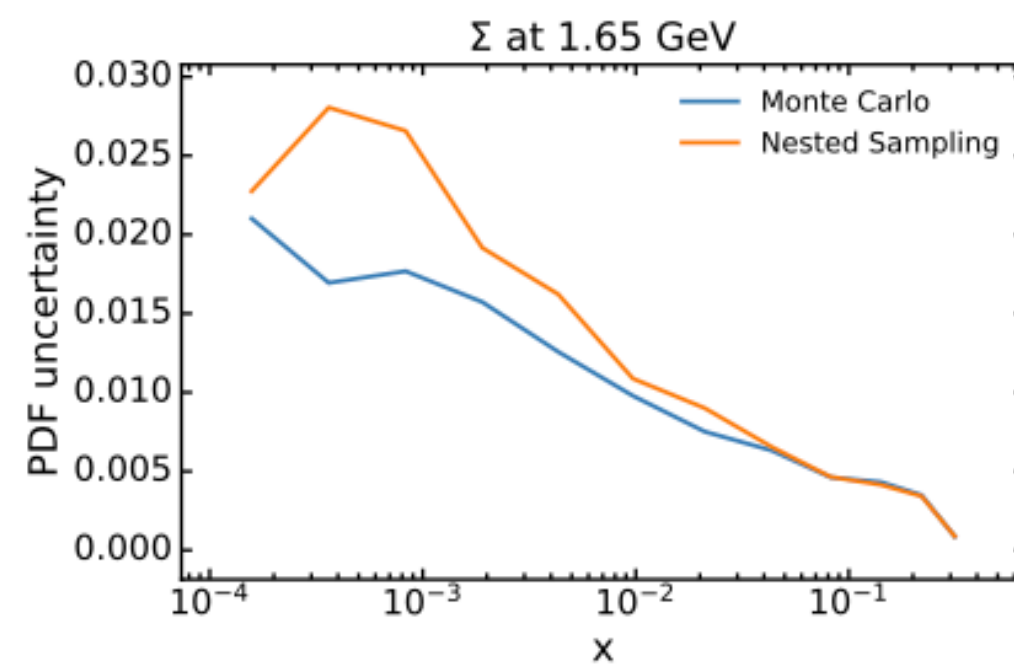
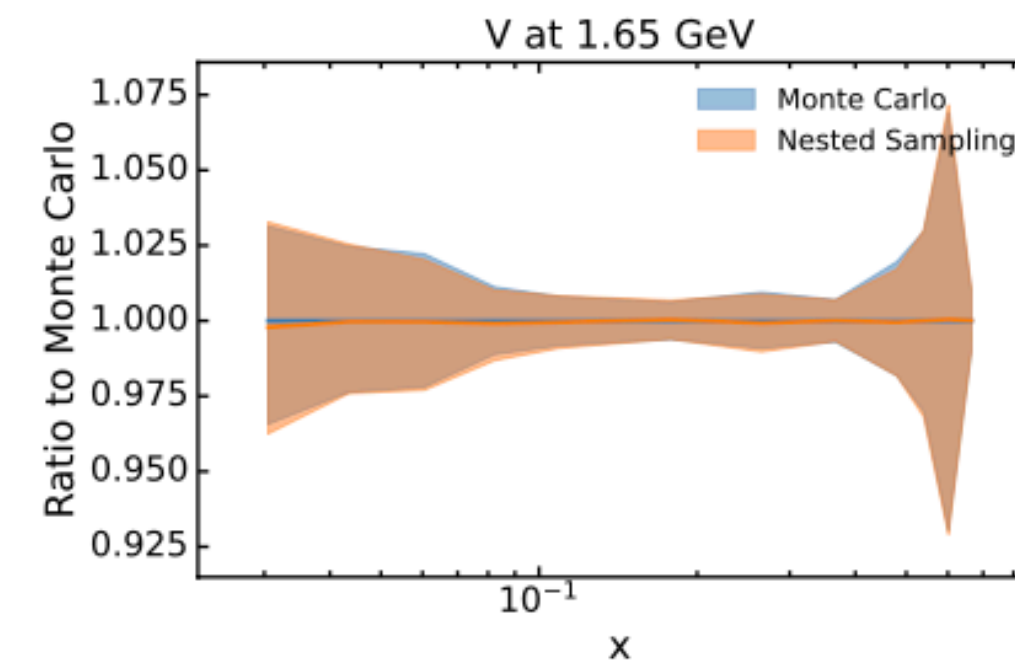
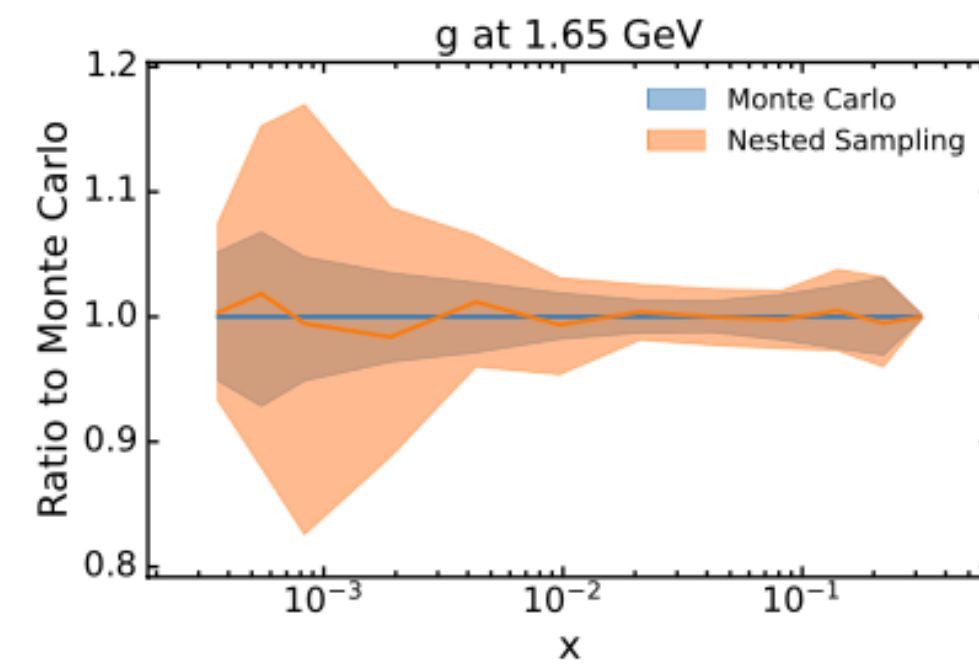
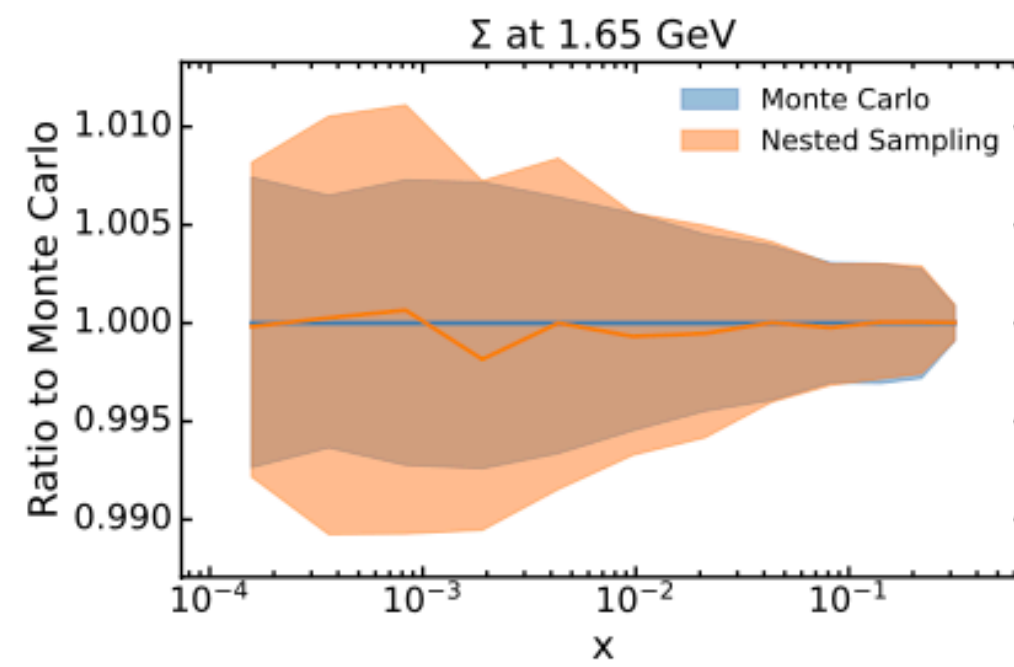
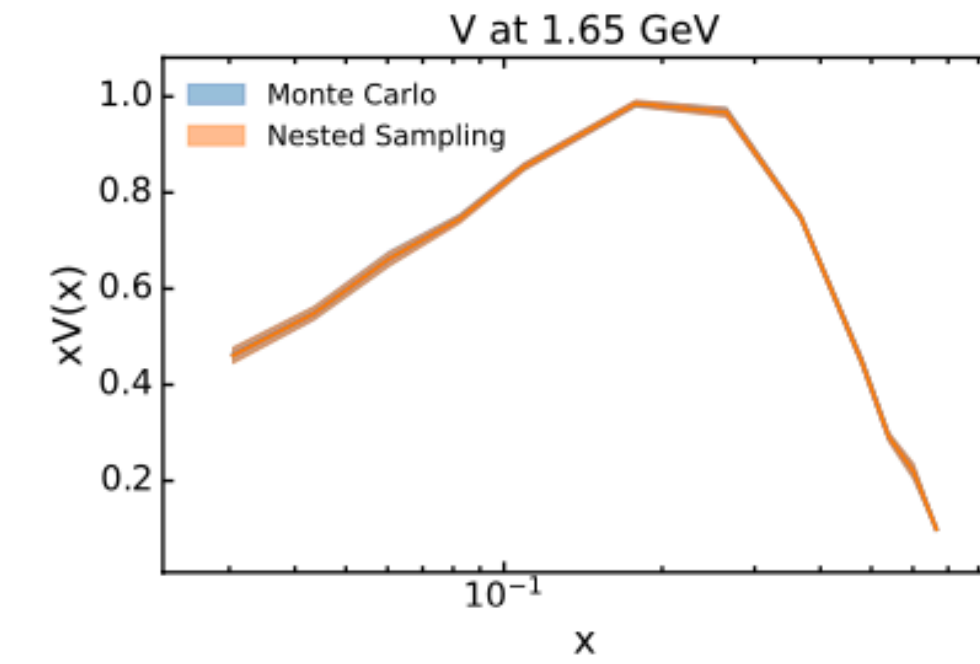
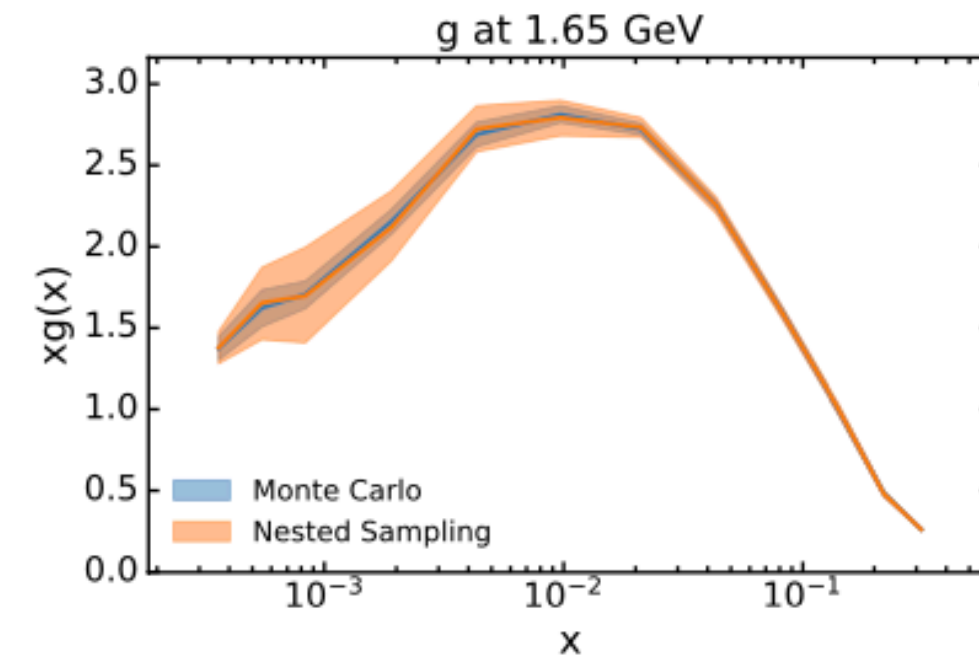
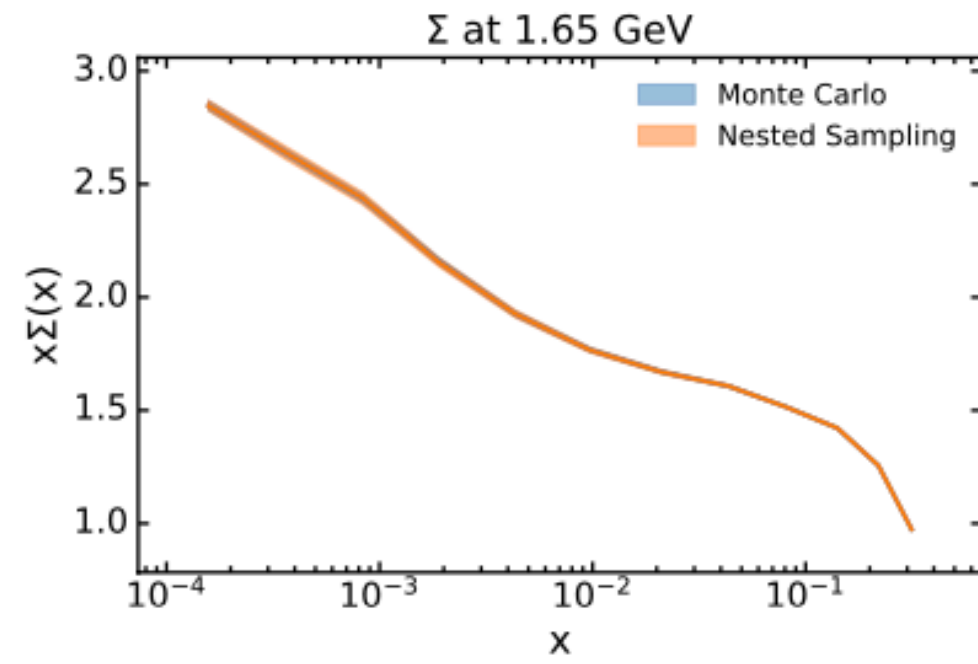
~ 3000
datapoints

Hadronic-only



~ 1000
datapoints

Global fit



~ 4000
datapoints