Measuring GWs with PTA experiments $_{\rm OOOOO}$

A new approach for future forecasts $_{\rm OOO}$

Conclusions and outlook

Measuring SGWBs with PTAs

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Rencontres de cosmologie des lacs alpins @ UniGe

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The dawn of GW astronomy

Gravitational Waves (GWs) are:

- Spacetime perturbations
- Almost free streaming
- The ultimate cosmological probe

There are two classes of signals:

- Deterministic signals
 - Typically from binaries
 - Time coherency
 - Localized in the sky

• Stochastic GW Backgrounds

- Superposition of many signals
- Early Universe processes
- No time coherency
- Diffuse signals





* Figures from https://www.ligo.org/detections/images/ligoGW150914signals-lg.jpg and https://www.ligo.org/science/GW-Overview/images/stochastic.jpg

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Present and future GW detectors



The peak of the sensitivity roughly scales with the inverse of the arm length!

* Figure adapted from GWPlotter

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First hints of SGWB from PTA experiments in 2020 ...



Pulsars are very precise clocks! GWs might induce changes in the observed period Error on the measurement performed with a single pulsar is huge ↓ Monitor many for error reduction

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* Figures from https://www.lpc2e.cnrs.fr/en/projets/pta-2 NANOGrav Collaboration, Z. Arzoumanian et al., Astrophys.J.Lett. 905 (2020) 2, L34, ArXiv: 2009.04496.



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... significance now increasing ...

Better significance in the latest data release in late June !



Not only significance for a common process but also for HD correlations!

* Figures from NANOGrav collaboration, G. Agazie et al., Astrophys.J.Lett. 951 (2023) 1, L8, ArXiv: 2306.16213. EPTA and InPTA Collaborations, J. Antoniadis et al., Astron.Astrophys. 678 (2023) A50, Astron.Astrophys. 678 (2023) A50, ArXiv: 2306.16214.

PPTA collaboration, Daniel J. Reardon et al., Astrophys.J.Lett. 951 (2023) 1, L6, ArXiv: 2306.16215.



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... combining datasets might clarify.





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Conclusions and outlook

Some general ingredients

- Data $ilde{d}$ (in frequency space) \longrightarrow $ilde{d} = ilde{s} + ilde{n}$
- For individual sources $\langle \tilde{s} \rangle \neq 0$
- For SGWBs $\langle \tilde{s} \rangle = 0$

• For noise $\langle \tilde{n} \rangle = 0$

For an isotropic SGWB $\longrightarrow \langle h_{\lambda}(\vec{k}) h_{\lambda'}^{*}(\vec{k'}) \rangle \propto \delta_{\lambda\lambda'} P_{h}^{\lambda}(k) \delta(\vec{k} - \vec{k'})$

Assuming $\left<\tilde{s}\tilde{n}\right>=0$ and Gaussian signal and noise

$$\left\langle \tilde{d}^{2} \right\rangle = \left\langle \tilde{s}^{2} \right\rangle + \left\langle \tilde{n}^{2} \right\rangle = \sum_{\lambda} \mathcal{R}_{\lambda} P_{h}^{\lambda} + N \equiv \mathcal{R} \left[P_{h} + S_{n} \right]$$

where we have introduced

- The (quadratic) response function of the instrument ${\cal R}$
- The (intensity of the) signal power spectrum P_h (in 1/Hz)
- The noise power spectrum N (in 1/Hz)
- The (square of the) Strain sensitivity S_n (in 1/Hz)

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In order to compare with cosmological predictions it's customary to introduce

$$\begin{split} \Omega_{\rm GW} &\equiv \frac{1}{3H_0^2 M_p^2} \, \frac{\partial \rho_{\rm GW}}{\partial \ln f} = \frac{4\pi^2}{3H_0^2} f^3 P_h \qquad \text{and} \qquad \Omega_n(f) = \frac{4\pi^2}{3H_0^2} f^3 S_n(f) \;, \\ \text{where } H_0 &\simeq h_0 \times \; 3.24 \times 10^{-18} \, \text{Hz} \text{ is the Hubble parameter today.} \end{split}$$

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Few details on the measurements



Each pulsar is monitored by one (or more) telescopes

- Data are collected every few days (sets the Nyquist, day is $\sim 10^{-5} \text{Hz})$
- Several frequencies are monitored
- Combine many pulses per observation
- Repeat for **very** long time (\gtrsim yrs) to go to very low frequencies ($f_{\rm yr} \sim 3.17 \times 10^{-8} {\rm Hz}$)

Data are compared with some to timing model

The data used in the GW analysis are residuals after timing model subtraction

* Figure from https://nanograv.github.io/11yr_profile_variability/

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Signal part

The time shift induced by a GW is

$$\Delta T_i(t) = \frac{\hat{p}_i^a \hat{p}_i^b}{2} \int_0^{L_i} \mathrm{d}s \, h_{ab}(t(s), \vec{x}(s)) ,$$

where $t(s) = t - L_i + s$ and $\vec{x}(s) = \vec{x}_0 + (L_i - s)\hat{p}_i$.

Expand h_{ab} in plane waves $(\tilde{h}_A(\vec{k})$ Fourier coefficients, e^A_{ab} polarization tensors) $\Delta T_i(t) = L_i \int d\vec{k} e^{-2\pi i \vec{k} \cdot \vec{x}_0} \sum_A \left[e^{2\pi i k t} \mathcal{M}(\vec{k}, \hat{p}_i) \mathcal{G}^A(\hat{k}, \hat{p}_i) \tilde{h}_A(\vec{k}) + h.c.(-\vec{k}) \right]$ where we have integrated in *s* and introduced $\mathcal{G}^A(\hat{k}, \hat{p}_i) \equiv \frac{\hat{p}_i^a \hat{p}_i^b}{2} e^A_{ab}(\hat{k}), \qquad \mathcal{M}(\vec{k}, \hat{p}_i) \equiv -i \frac{1 - e^{-2i\pi k L_i (1 + \hat{k} \cdot \hat{p}_i)}}{2\pi k L_i (1 + \hat{k} \cdot \hat{p}_i)}.$

For SGWB what we need is

$$\langle \Delta T_i(t) \Delta T_j(t) \rangle \propto L_i L_j \int \mathrm{d}k \ P_h(k) \int \mathrm{d}\hat{k} \ \sum_A \mathcal{M}(\vec{k}, \hat{p}_i) \mathcal{M}(\vec{k}, \hat{p}_j) \ \mathcal{G}^A(\hat{k}, \hat{p}_i) \mathcal{G}_A(\hat{k}, \hat{p}_j) \ .$$

Finally, we decompose the angularly-integrated quantity in two parts:

- A frequency-independent part, depending only on $\hat{p}_i \cdot \hat{p}_j$ (HD!)
- A frequency-dependent part, depending on the GW's frequency vs. L_i , L_j 10/17

Introduction

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Noise part

Many noise sources can affect our data:

(SC = spatially correlated, CH = Chromatic, aCH = achromatic)

Noise type	Freq. shape	Space correlations
Irregularities in the period	aCH	no
Orbital irregularities	aCH	no
Pulse jitter	might be CH,	no
Changes in the pulse profile	СН	no
ISM effects	СН	no
Solar system ephemeris	aCH	yes
Clock Errors	aCH	yes
	???	???

Again, for SGWB, what we care for is something like:

 $\langle n_i(t)n_j(t')\rangle = \delta_{ij}P_n + \delta_{ij}P_{i,n} + P_{n,ij} + \dots$

Off-diagonal terms $(P_{n,ij})$ might in principle be there but even if they do, should (hopefully) not behave as HD!!

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A likelihood for the time residuals

Schematically we express the time residuals as

$$\delta t = M\epsilon + Fa + n$$

where M is the design matrix, F is the Fourier design matrix and n is WN.

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A likelihood for the time residuals

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Write a Gaussian likelihood for WN as

$$\ln \mathcal{L} = -\frac{1}{2} \ln \left[\det(2\pi C) \right] - \frac{1}{2} (\delta t - M\epsilon - Fa) C^{-1} (\delta t - M\epsilon - Fa)$$
where $C \equiv \langle nn \rangle$ is the WN covariance matrix.

Assume ϵ and a to be Gaussian (with variance X and φ , respectively)

$$\ln \mathcal{L} = -\frac{1}{2} \ln \left[\det(2\pi N) \right] - \frac{1}{2} \delta t N^{-1} \delta t$$

where $N \equiv C + MXM^T + F\varphi F^T$ is the full noise matrix.

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where $N \equiv C + MXM^T + F\varphi F^T$ is the full noise matrix.

Finally, impose some spatial correlations between pulsar pairs (i.e., ij structure for all these matrixes), the time structure (i.e. correlations between measurements at different times) and compare to data!

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Finally, impose some spatial correlations between pulsar pairs (i.e., ij structure for all these matrixes), the time structure (i.e. correlations between measurements at different times) and compare to data!

Works well but it's quite slow!

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A simplified likelihood and Fisher approximation

Can we make this much faster to do some forecasts??

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Conclusions and outlook

A simplified likelihood and Fisher approximation

Can we make this much faster to do some forecasts??

Let's just consider data in frequency domain and write the likelihood as

$$\ln \mathcal{L} = \sum_{f} -\frac{1}{2} \ln \left[\det(2\pi C_{IJ}^{f}) \right] - \frac{1}{2} \tilde{d}_{I}^{f} C_{IJ}^{-1} \tilde{d}_{J}^{f}$$

where \tilde{d}_{I}^{f} are the data for pulsar I and C_{IJ}^{f} is the covariance.

As before, we express C_{IJ} as signal + noise

 $C_{IJ} = P_{n,IJ} + R_{IJ}P_h$

with P_h , $P_{n,IJ}$ signal and noise power spectra and R_{IJ} response.

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 $C_{IJ} = P_{n,IJ} + R_{IJ}P_h$

with P_h , $P_{n,IJ}$ signal and noise power spectra and R_{IJ} response.

It's easy to show that the Fisher information matrix reads

$$F_{\alpha\beta} \equiv T_d \int_{f_{\min}}^{f_{\max}} \, \mathcal{C}_{IJ} \, \mathcal{C}_{JI} \, \frac{\partial \ln P_h}{\partial \theta_\alpha} \frac{\partial \ln P_h}{\partial \theta_\beta} \mathrm{d}f$$

where θ are the parameters and $C_{IK} = \bar{C}_{IJ}^{-1} R_{JK}$ with $\bar{C}_{IJ} \equiv C_{IJ}/P_h$.

In collaboration with S. Babak, M. Falxa, G. Franciolini

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Comparison with the standard approach (preliminary)

Is this method consistent with the standard approach??

Let's consider a PL signal $\longrightarrow \qquad \Omega_{\rm GW} h^2 = 10^{\alpha_{\rm PL}} \left(\frac{f}{f_{\rm yr}}\right)^{n_T}$

and test against current data + generated time residuals for future configurations using state-of-art codes and run the full analysis (run time \sim day vs. \lesssim sec for Fisher)

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Comparison with the standard approach (preliminary)



The results match quite well!

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Future forecasts (preliminary)

How well can we measure SGWBs with future experiments??

The new approach allows to easily answer this kind of questions!

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Future forecasts (preliminary)

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Future forecasts (preliminary)

How well can we measure SGWBs with future experiments??

The new approach allows to easily answer this kind of questions!

Let's say we have two signals : A PL signal (SMBHBs) + some bump (e.g., from SIGWB)

$$\begin{split} \Omega_{\rm GW} h^2 &= 10^{\alpha_{\rm PL}} \left(\frac{f}{f_{\rm yr}}\right)^{n_T} + \\ &+ 10^{\alpha_{\rm LN}} \exp\left\{-\frac{1}{2\rho^2} \ln^2\left(\frac{f}{f_*}\right)\right\} \end{split}$$

and fix the first component to match current observations.

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Future forecasts (preliminary)

How well can we measure SGWBs with future experiments??

The new approach allows to easily answer this kind of questions!



Obviously the louder the signal, the better we measure it!

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Conclusions and future perspectives

Conclusions:

- Present techniques to analyze PTA data are accurate but not super fast
- An approximate description might be much faster (and reasonably good)
- This approach might be quite useful to make forecasts!
- Tests against standard techniques are still crucial for validation

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Conclusions and future perspectives

Conclusions:

- Present techniques to analyze PTA data are accurate but not super fast
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- This approach might be quite useful to make forecasts!
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Future perspectives:

- Extensive tests for validation (different templates??)
- Application to a set of early Universe models (PTs, CSs, SIGWB, ...)
- Better model the noise components to improve accuracy (if needed)
- Extensions (e.g., to forecast the accuracy of the angular reconstruction?)

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The end

Thank you for your attention